



Setting the Standard for Automation™

Modeling and Control of Solid-Sorbent CO₂ Capture Systems

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Short Biography of Benjamin Omell

- Post-Doctoral Fellow in the Department of Chemical Engineering at West Virginia University
- Research interest is in the area of steady-state and dynamic modeling and advanced process control for energy-generating and associated processes
- Member of AIChE
- Hobbies- Biking, hiking

OUTLINE

- ❖ Motivation
- ❖ Overview of Carbon Capture Simulation Initiative (CCSI)
- ❖ Dynamic Model Development
- ❖ Dynamic Reduced Model (D-RM) Builder Development
- ❖ Advanced Process Control (APC) Framework Development
- ❖ Results and Discussions
- ❖ Conclusions

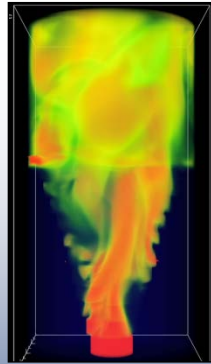
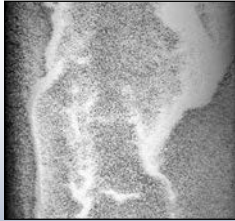
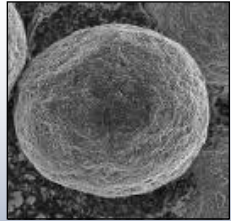
MOTIVATION

- Under the auspices of US DOE's *Carbon Capture Simulation Initiative (CCSI)*, government and university researchers are collaborating to develop computational models and tools for various post-combustion CO₂ capture technologies
- CO₂ capture processes must be designed to operate efficiently in the face of disturbances that are typical of commercial-scale power plants
- Dynamic process models and advanced process control can be used to ensure efficient operation of these CO₂ capture technologies.



CCSI

Carbon Capture Simulation Initiative



Identify promising concepts



Reduce the time for design & troubleshooting



Quantify the technical risk, to enable reaching larger scales, earlier



Stabilize the cost during commercial deployment

National Labs



Academia

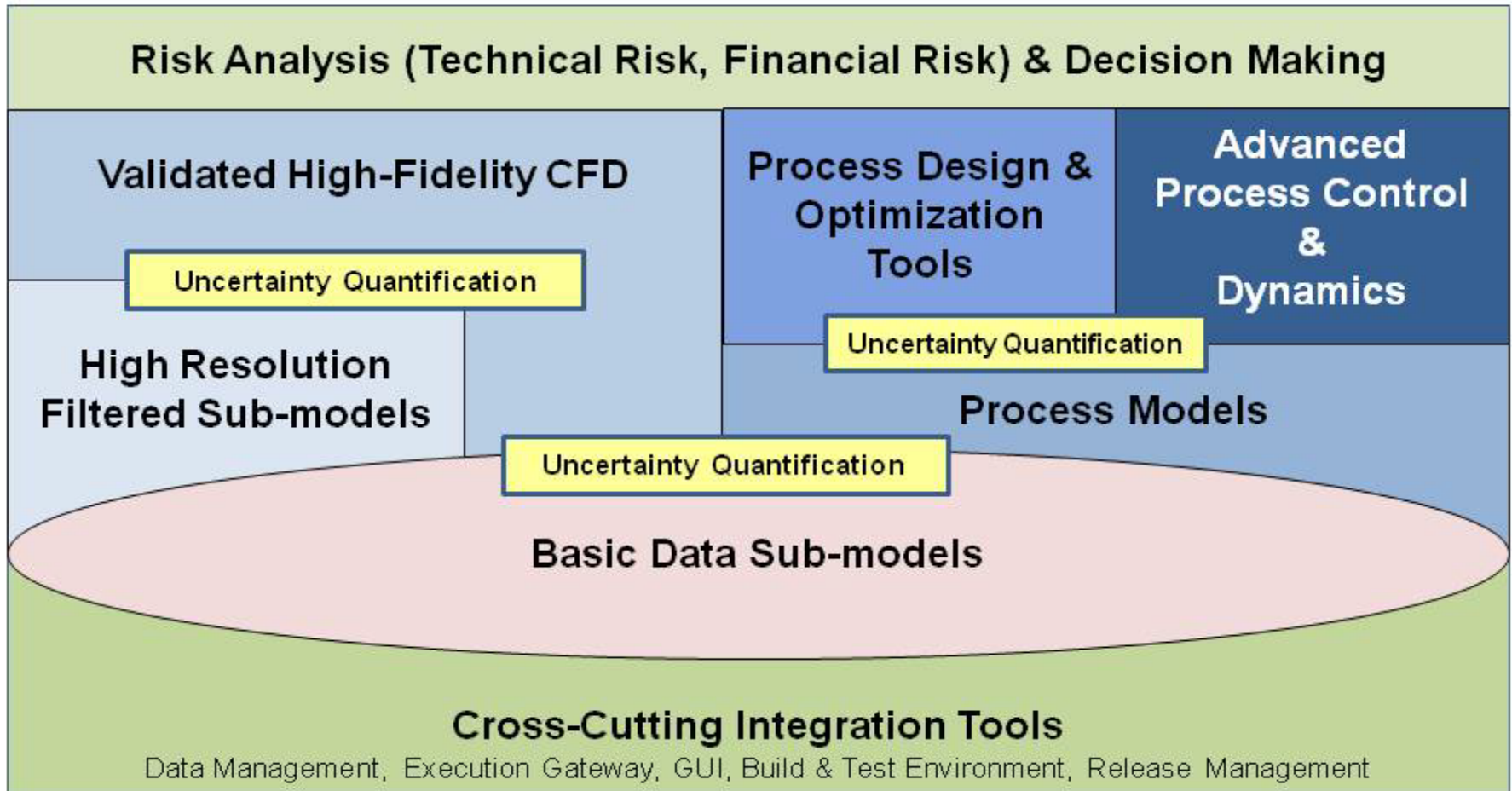


Industry



57th Annual ISA POWID Symposium, 2-4 June 2014, Scottsdale, Arizona

Computational Tools to Accelerate Next-Generation Technology Development

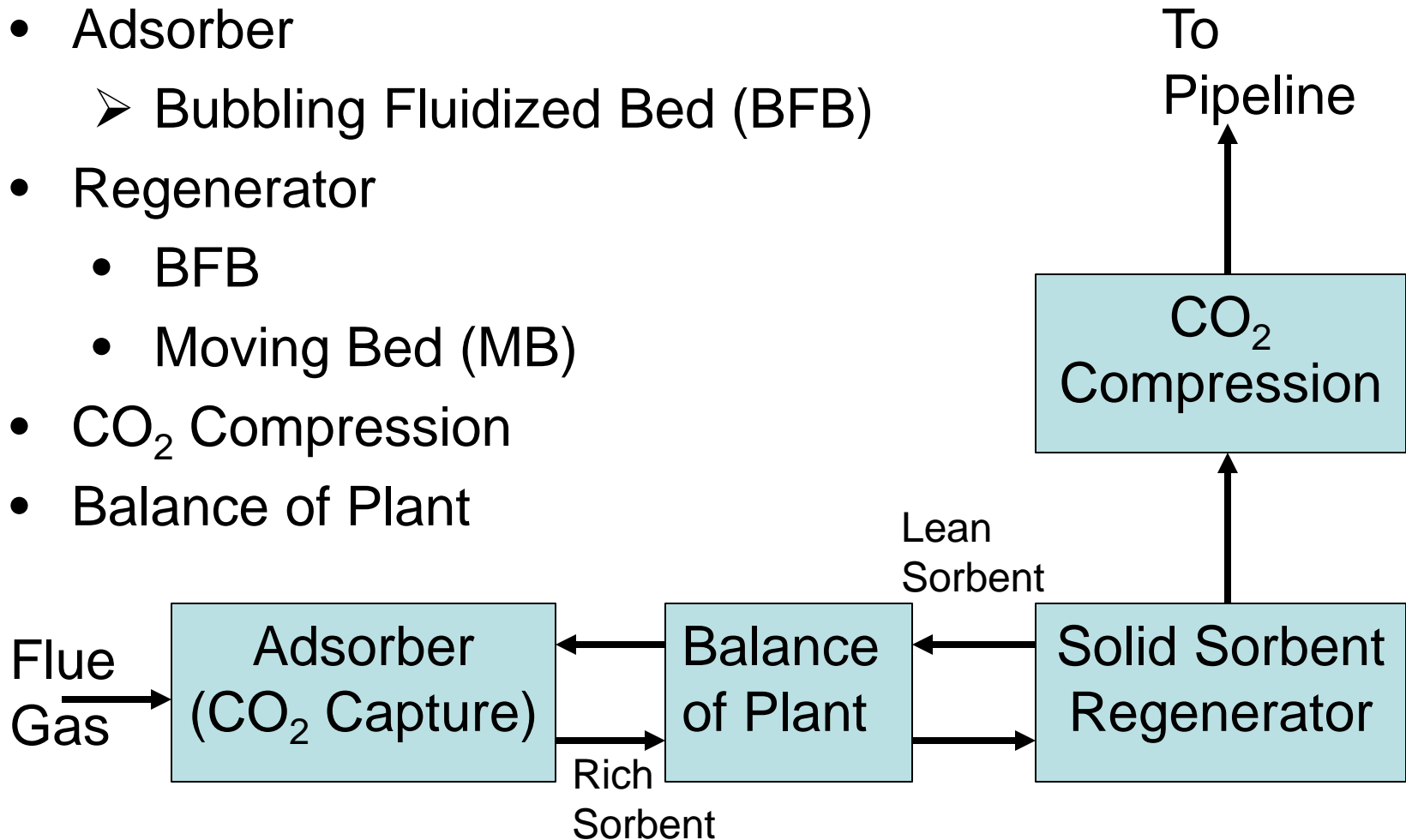


MODEL DEVELOPMENT



Solid Sorbent-based CO₂ Capture and Compression

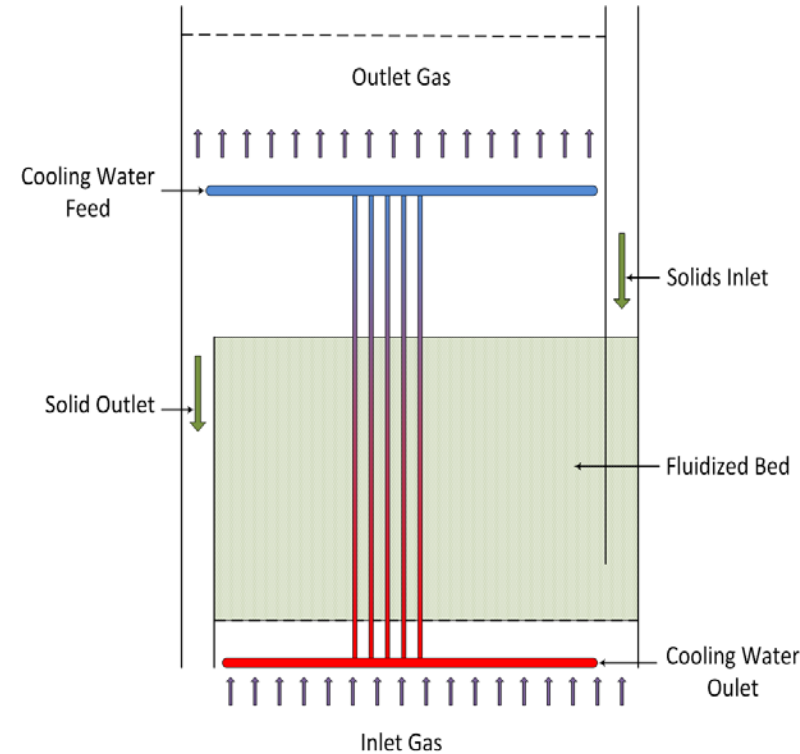
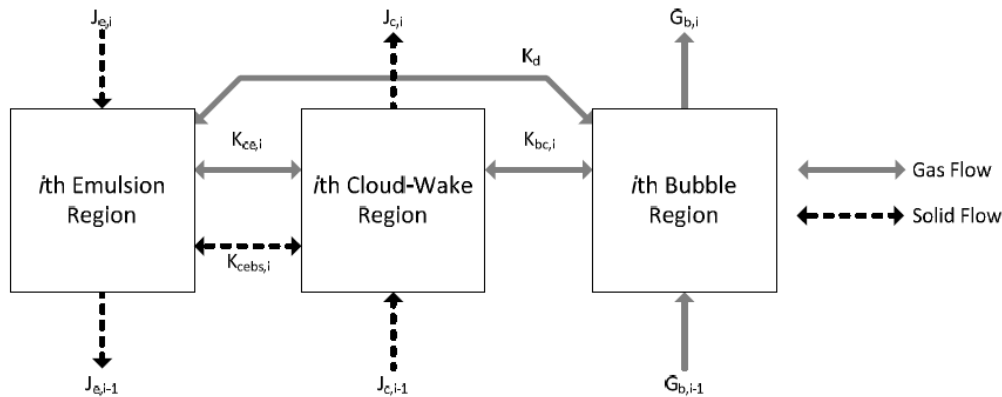
- Adsorber
 - Bubbling Fluidized Bed (BFB)
- Regenerator
 - BFB
 - Moving Bed (MB)
- CO₂ Compression
- Balance of Plant



MODEL DEVELOPMENT

Bubbling Fluidized Bed (BFB)

- 1-D two-phase, pressure-driven, non-isothermal dynamic model
- Model is flexible – adsorber or regenerator, cooler or heater depending on the application

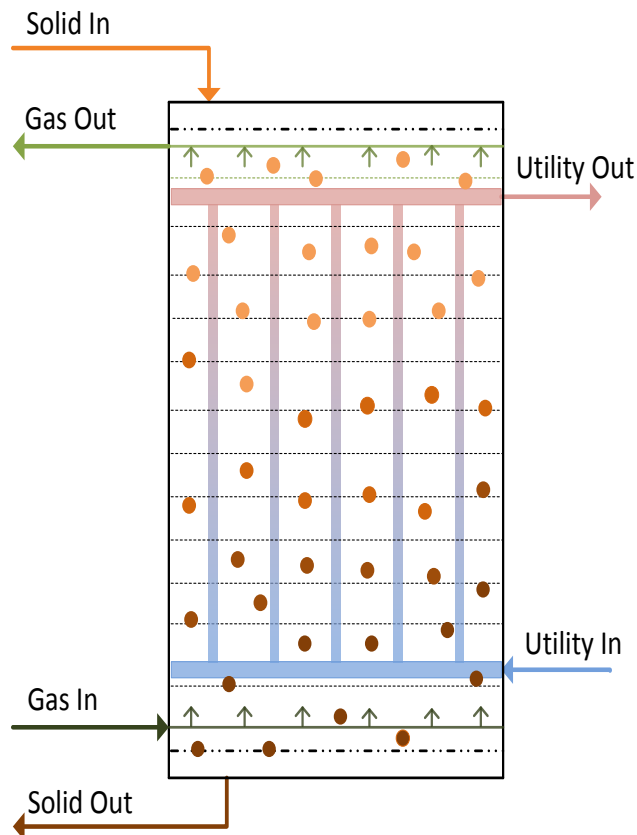


- Transient species conservation and energy balance equations for both gas and solid phases in all three regions
- Rigorous hydrodynamic models

MODEL DEVELOPMENT

Moving Bed Reactor

- 1-D two-phase pressure-driven non-isothermal dynamic model of a moving bed reactor for the regenerator



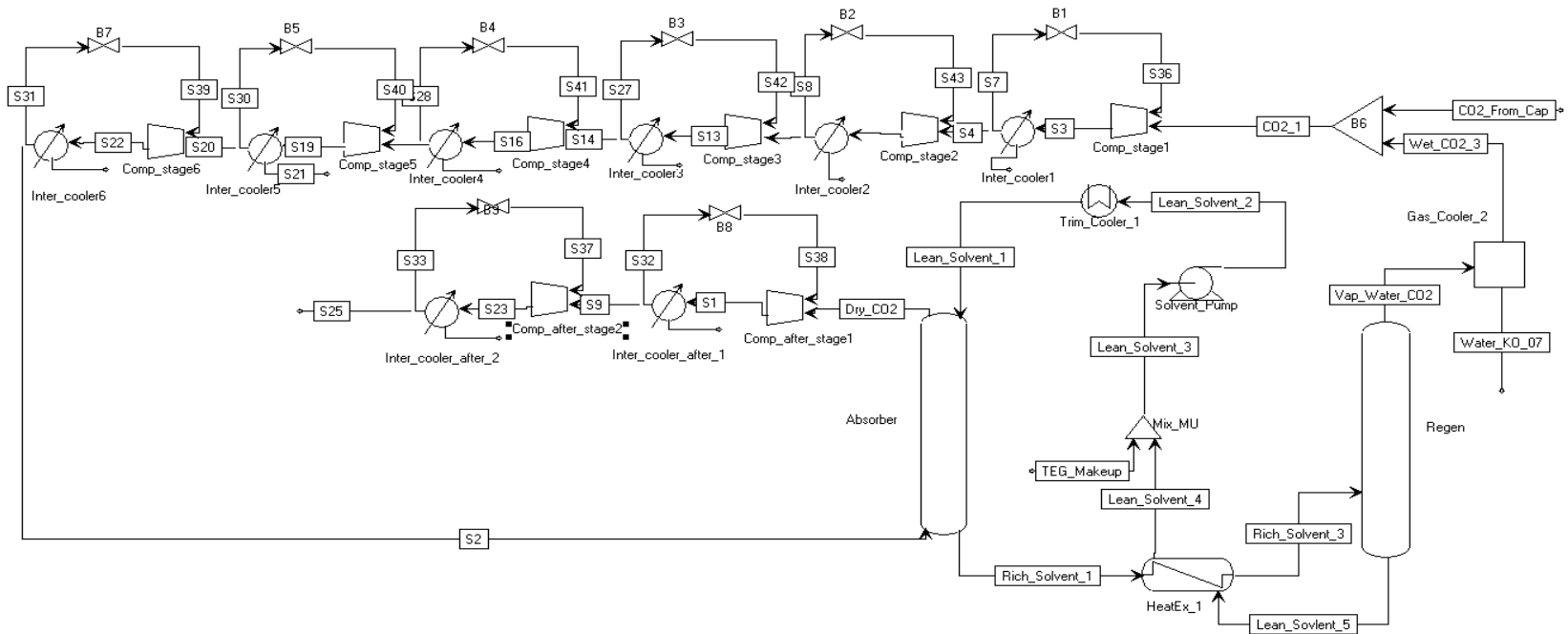
Model Assumptions

- Vertical shell & tube type reactor
 - Gas and solids flows are modeled by plug flow model with axial dispersion.
 - Particles are uniformly dispersed through the reactor with constant voidage
 - Particle attrition ignored
 - Temperature is uniform within the particles
- Gaseous species: CO_2 , N_2 , H_2O
 - Solid phase components: bicarbonate, carbamate, and physisorbed water

MODEL DEVELOPMENT

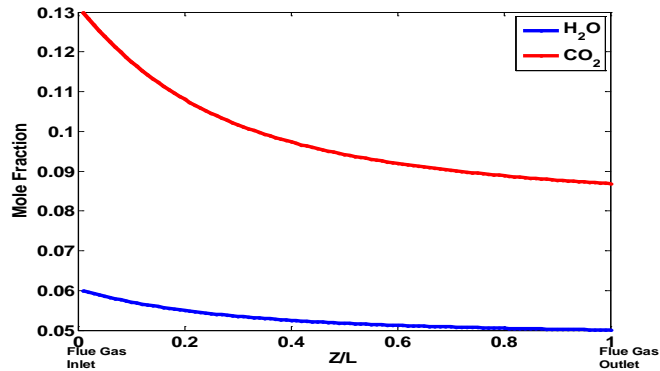
CO₂ Compression System Model

- Dynamic model of a multi-stage integral gear compressor system with inter-stage coolers, knock-out drums, and TEG absorption system has been developed.
- Performance curves obtained from a commercial vendor have been used for calculating off-design performance.

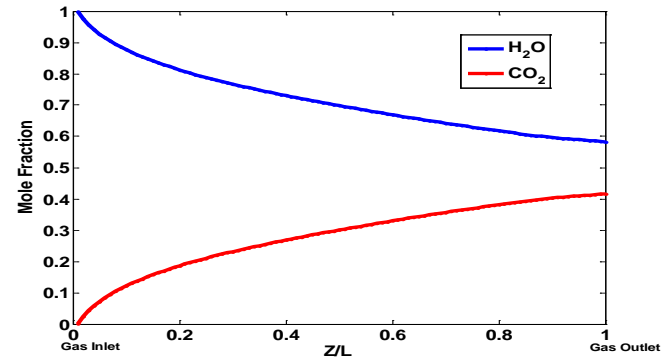


Results

Single-Stage BFB Model Adsorber

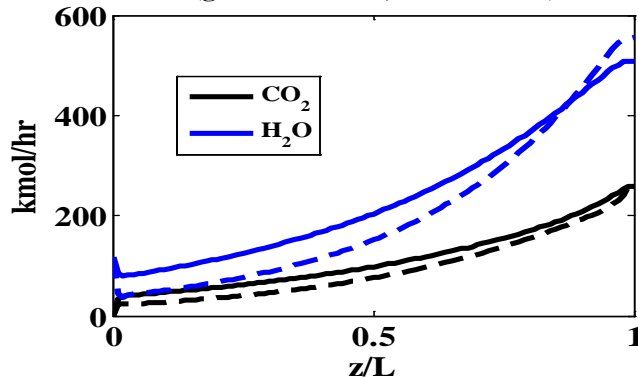


Regenerator

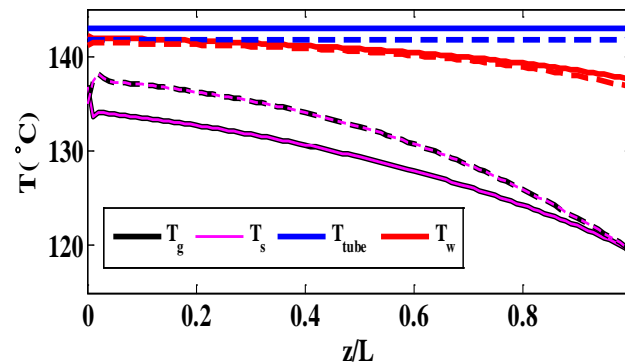


MB Model of Regenerator

Gas Component Flow Profile of MB Regenerator
(gPROMS-Solid, ACM-Dotted)



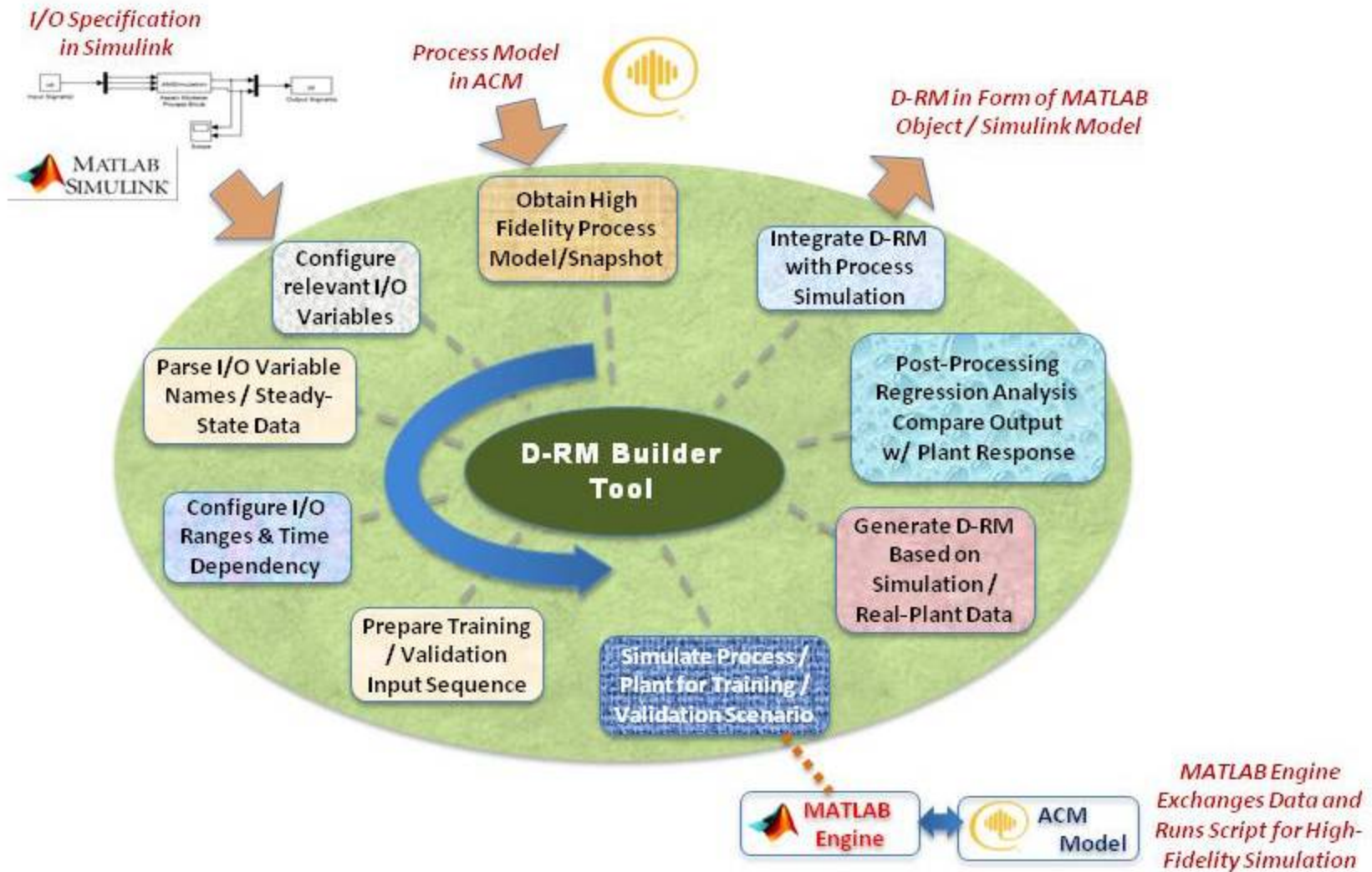
Temperature Profile of MB Regenerator
(gPROMS-Solid, ACM-Dotted)



Why Dynamic Reduced Models?

- **High-fidelity models are computationally expensive**
 - ❖ May contains hundreds of thousands of DAEs
 - ❖ Require small time steps to handle stiffness
- **Dynamic reduced models (D-RMs) could speed up a few orders of magnitude**
- **Two types of D-RMs**
 - ❖ **Reduced order D-RMs**
 - Generated based on equations involved, e.g. POD
 - Generation method is generally model specific
 - On-going CCSI project for BFB reactor
 - ❖ **Data-driven D-RMs**
 - Based on pre-computed results from repeated simulations of a high-fidelity dynamic model over a range of input conditions
- **Can be used for off-line operator training systems (OTS) and on-line implementations of advanced process control (APC) and real-time optimization (RTO)**

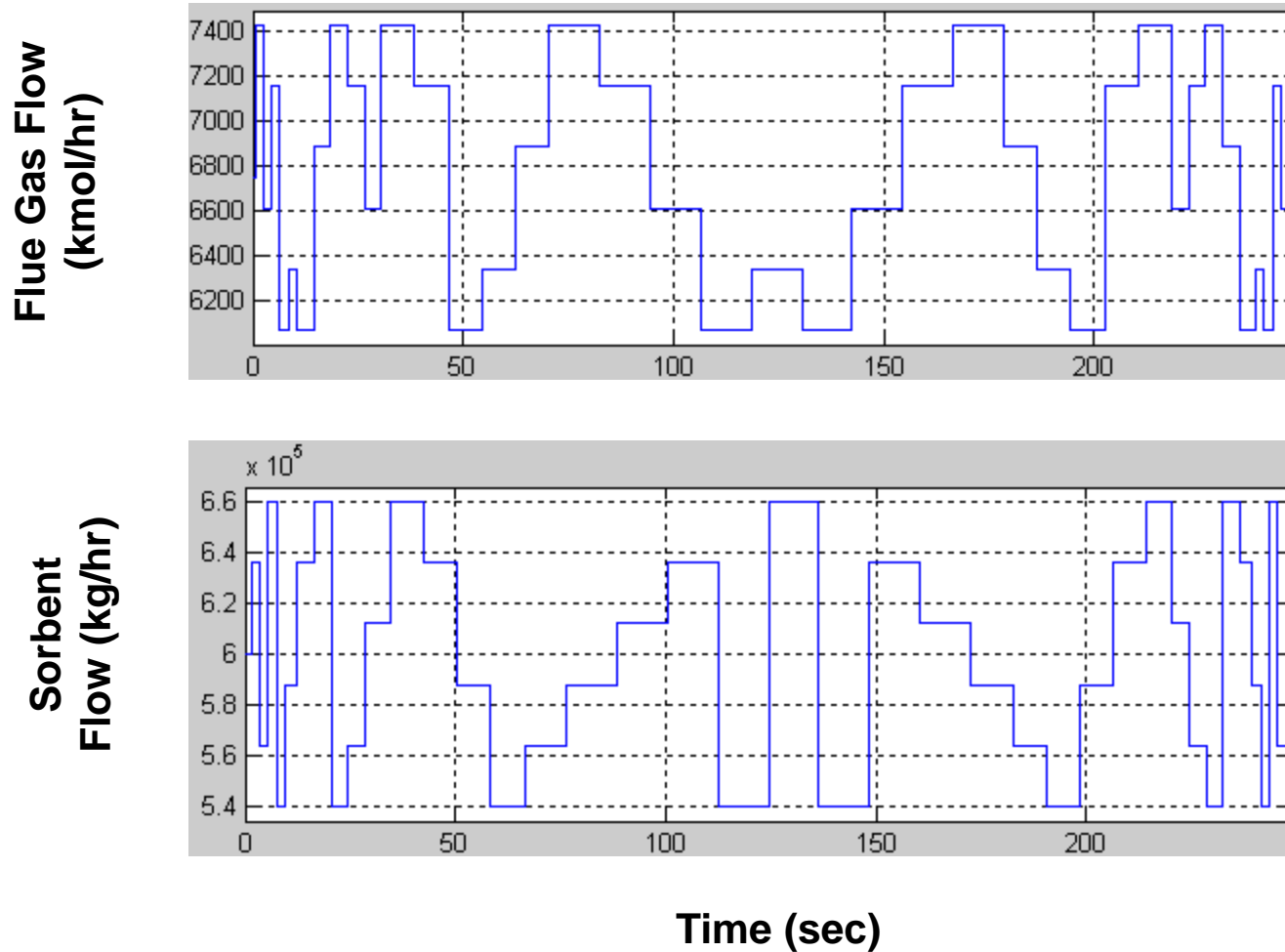
Work Flow of D-RM Builder



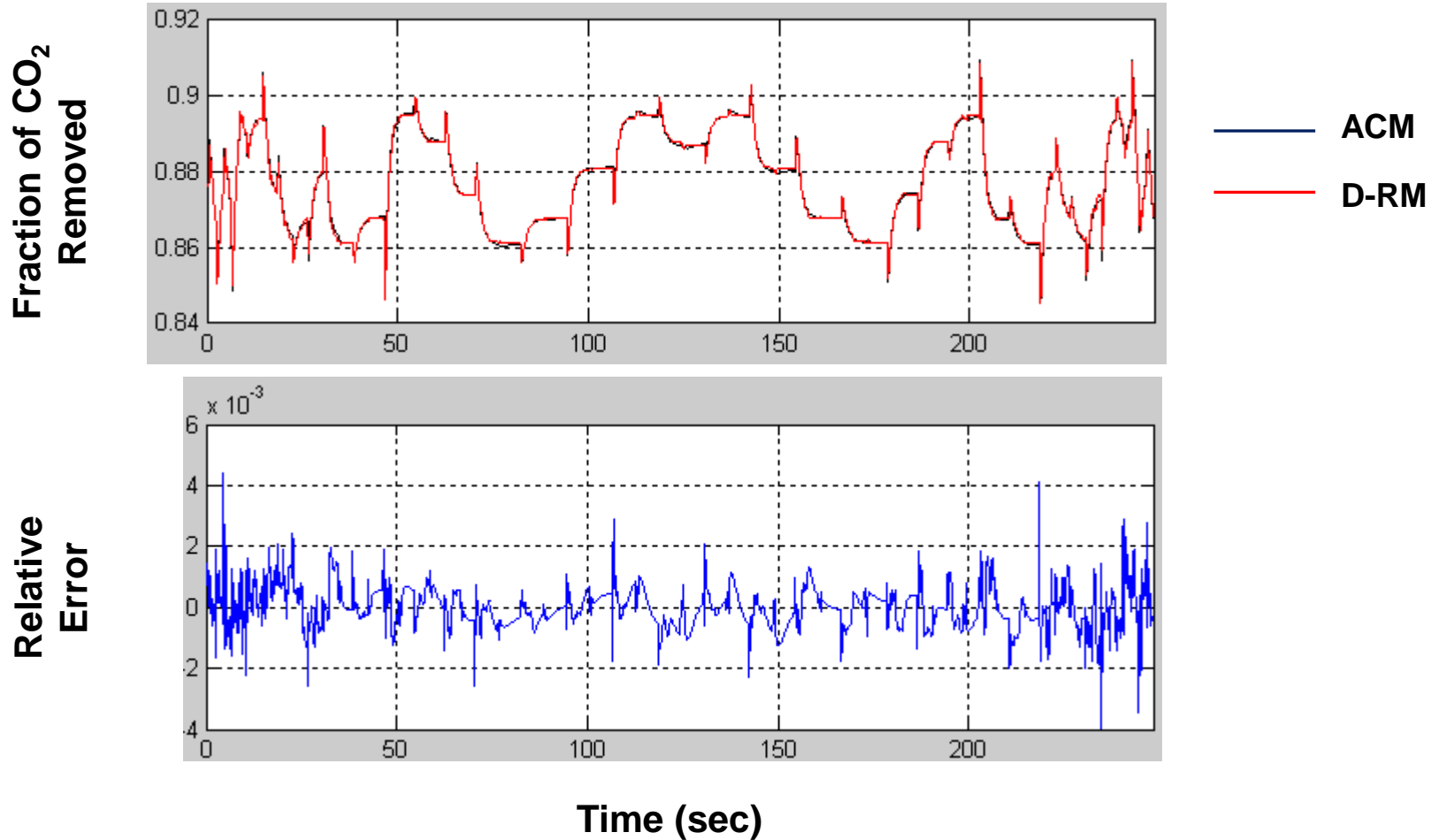
D-RM for the BFB Adsorber

- **D-RM generated based on open-loop ACM model**
- **Inputs:**
 - **Flue gas flow rate: 6,075 to 7,425 kmol/hr**
 - **Sorbent flow rate: 540,000 to 660,000 kg/hr**
- **Output:**
 - **CO₂ removal (Fraction of CO₂ in flue gas removed)**
- **DABNet model with pole values optimized**
- **CPU time required for ACM simulations**
 - **Approximately 50 minutes for 2500 sampling steps (Sampling time interval at 0.1 second)**

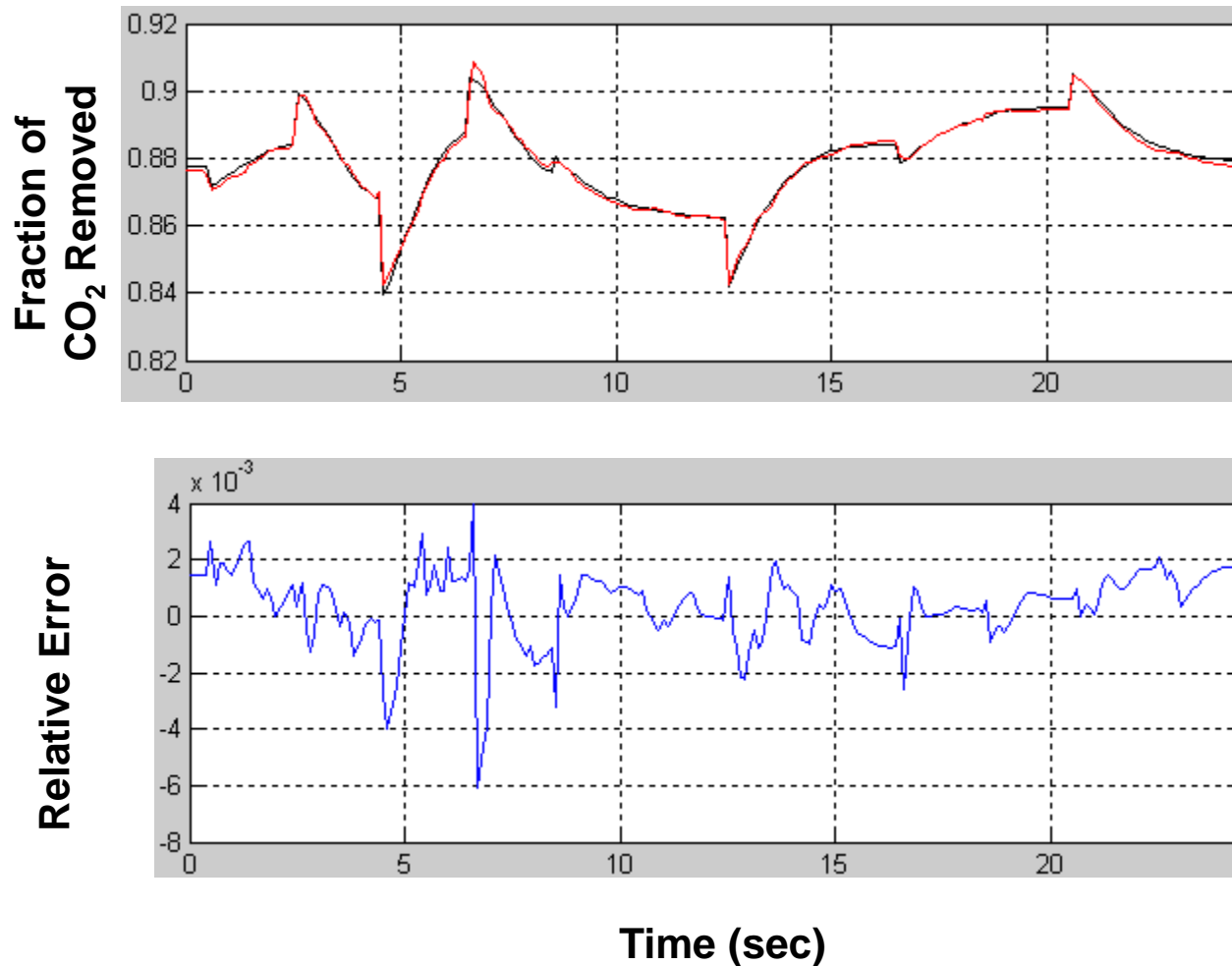
Training Input Data



Training Output Data

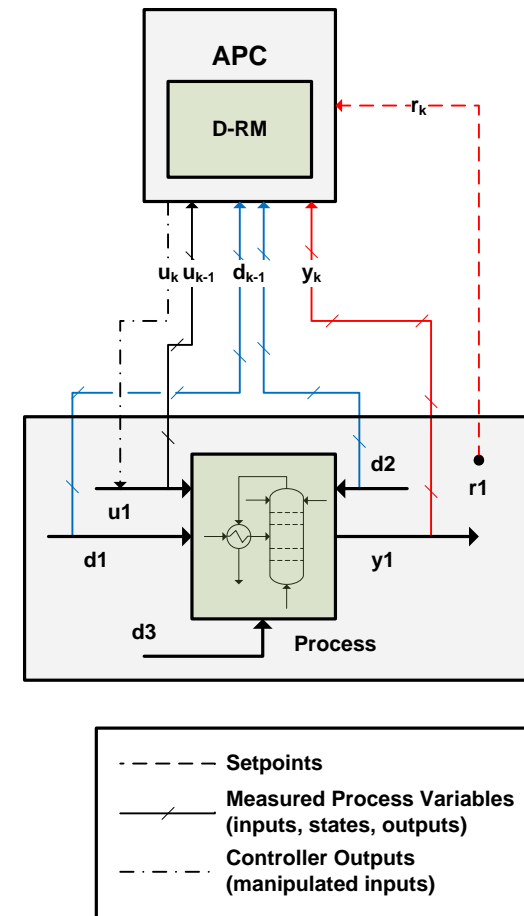


Validation Output Data



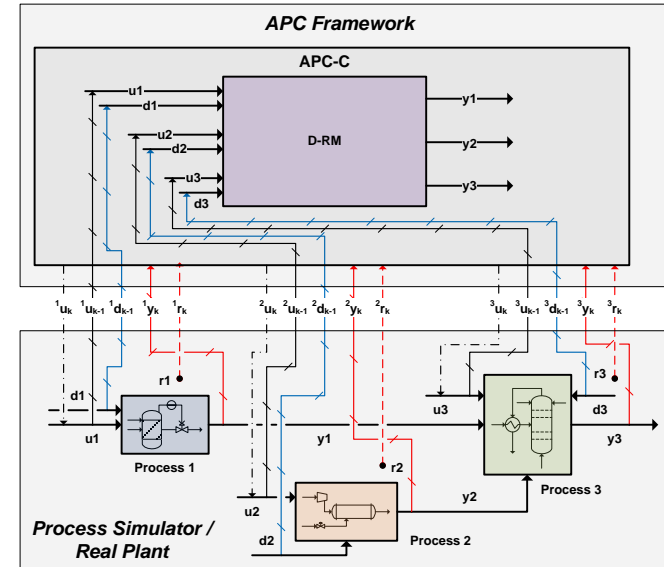
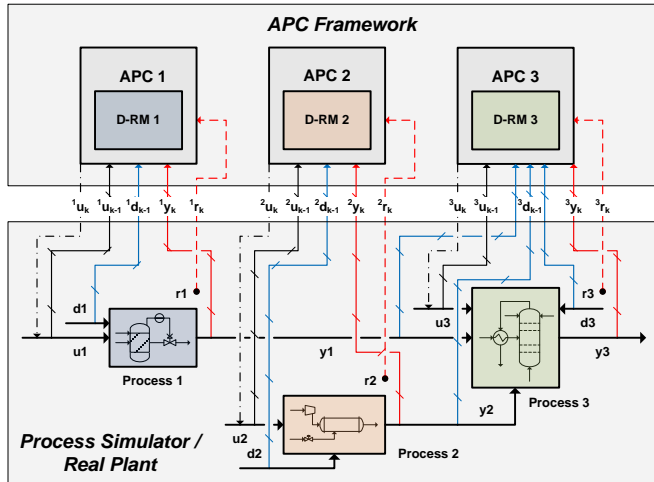
APC FRAMEWORK: Features

- **Nonlinear Model Predictive Control (NMPC) using DAB-Net DRM model**
- **Unscented Kalman Filter (UKF) feedback and disturbance estimation technique**
 - Accurate capture of true mean and covariance of estimates
- **Extended Kalman Filter (EKF) with Autocovariance Least-Squares (ALS) disturbance-estimation technique**
- **Interior Point Optimizer (IPOPT)**
 - Faster and more effective optimization routine for solving large-scale nonlinear programming (LS-NLP)
- **Advanced Multi-Step NMPC (amsNMPC)**
 - Deals with NLP problems where solution time > sampling period
 - Proven nominal stability
- **Multiple-Model Predictive Control (MMPC) with Multiple Disturbance Models**
 - Capture nonlinearity using model bank across wide operating regimes
 - Prospective alternative to NMPC
 - Significantly low computation cost (compared to NMPC)



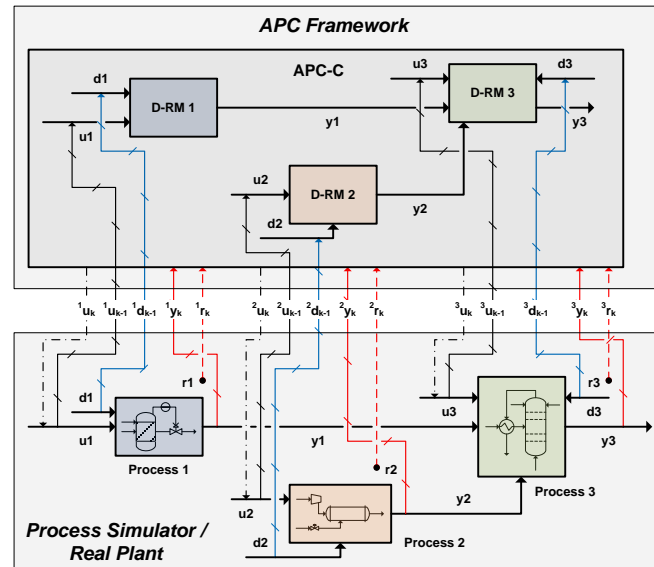
APC FRAMEWORK: Modes of Operation

Decentralized APC
Dedicated APC block for each sub-process

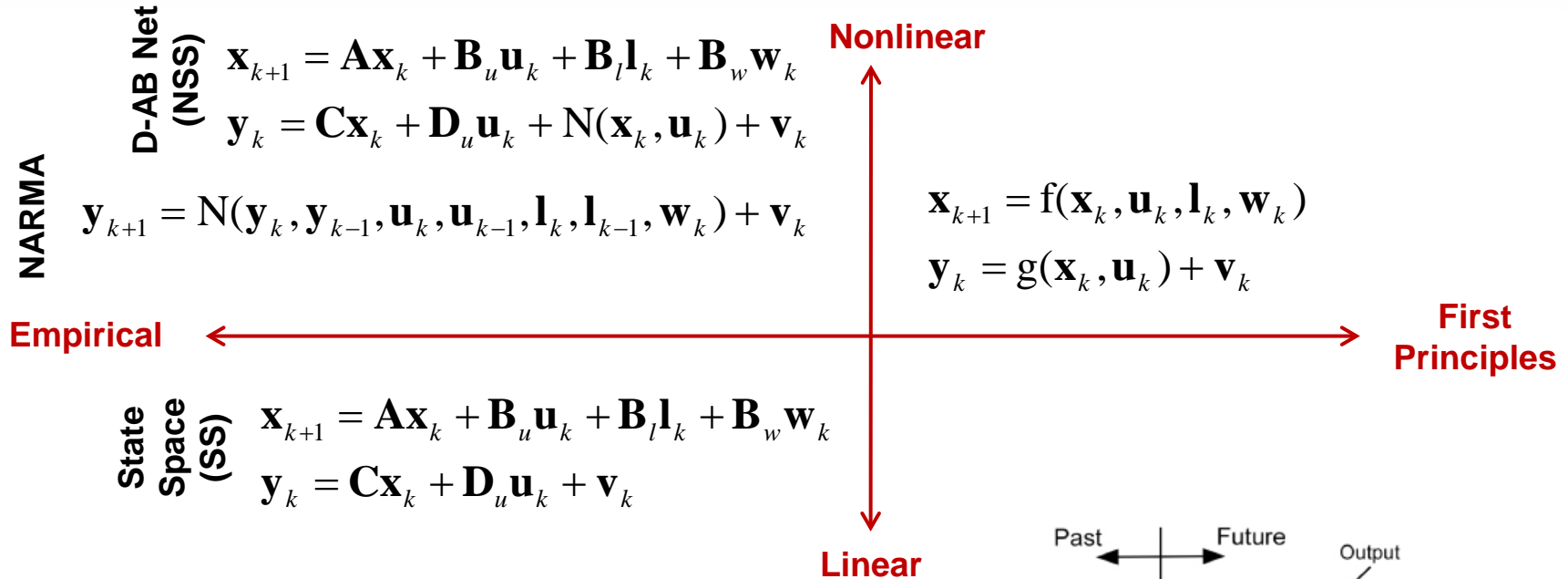


Centralized APC
Single APC block using single D-RM for entire flowsheet

Centralized APC
Single APC block using individual D-RM for each sub-process



APC FRAMEWORK: Formulation (control models & objectives)

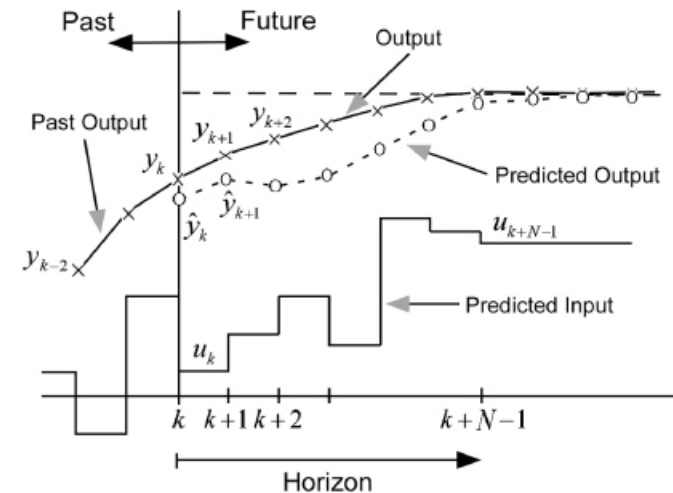


Dynamic Objective Function

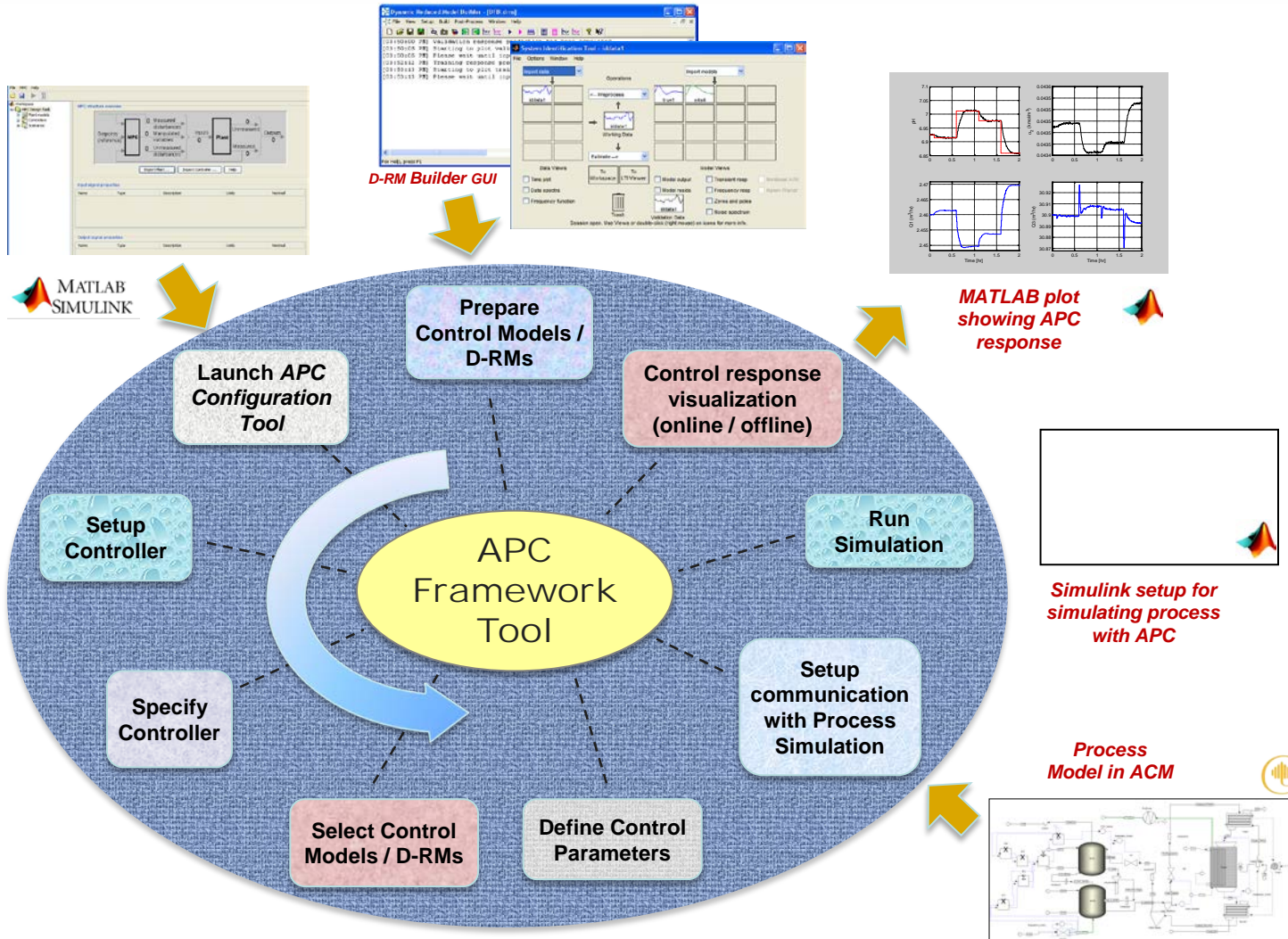
$$\min_{\Delta u} J = \sum_{j=1}^P \left(r_k - \hat{y}_{k+j|k} \right)^T W^y \left(r_k - \hat{y}_{k+j|k} \right) + \sum_{j=0}^{M-1} \Delta u_{k+j}^T W^u \Delta u_{k+j}$$

$$u_{\min} \leq u_{k+j} \leq u_{\max} \quad \Delta u_{\min} \leq \Delta u_{k+j} \leq \Delta u_{\max}$$

$$y_{\min} \leq \hat{y}_{k+j|k} \leq y_{\max}$$

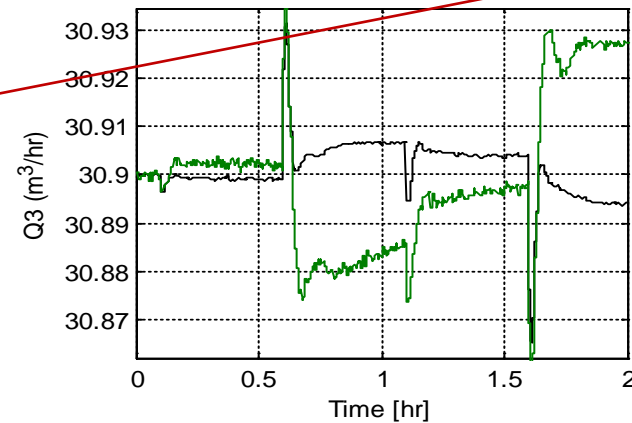
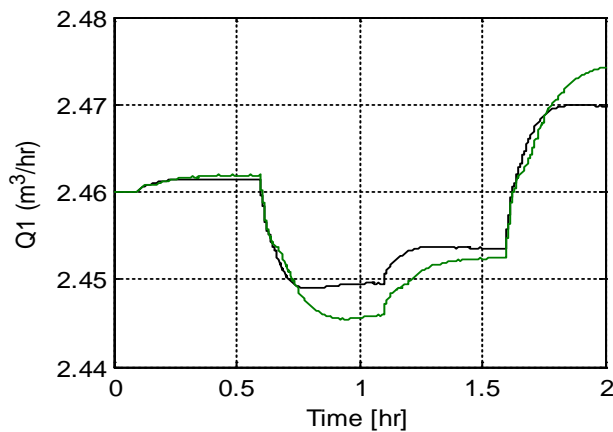
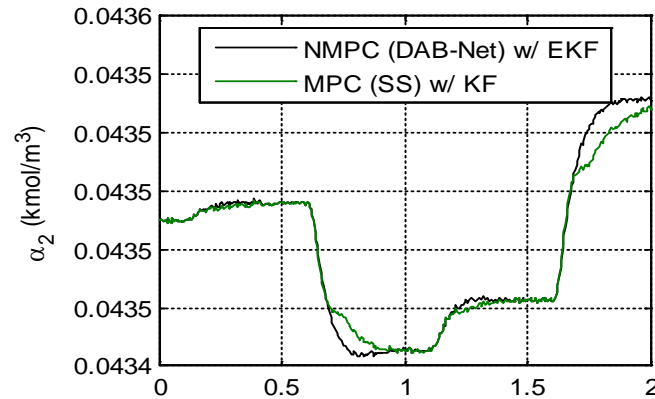
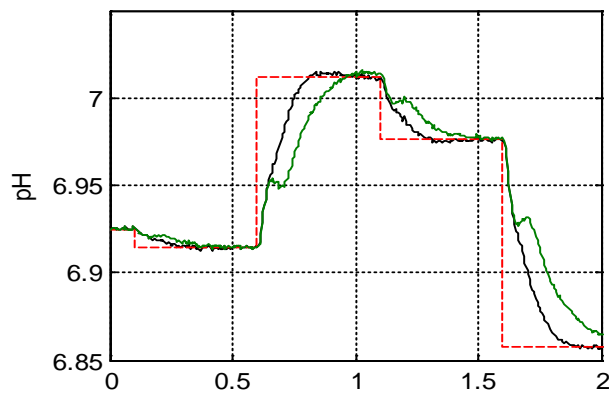


APC FRAMEWORK: End-User Workflow



APC FRAMEWORK

Results: DAB-Net based NMPC (comparison)



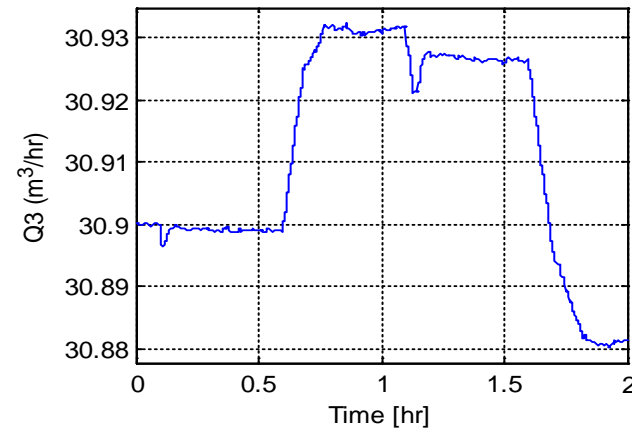
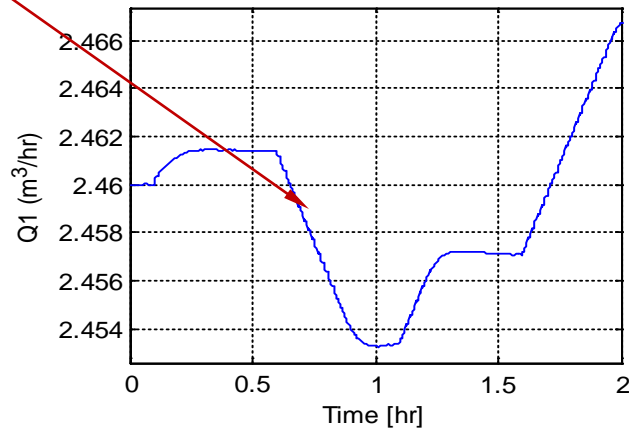
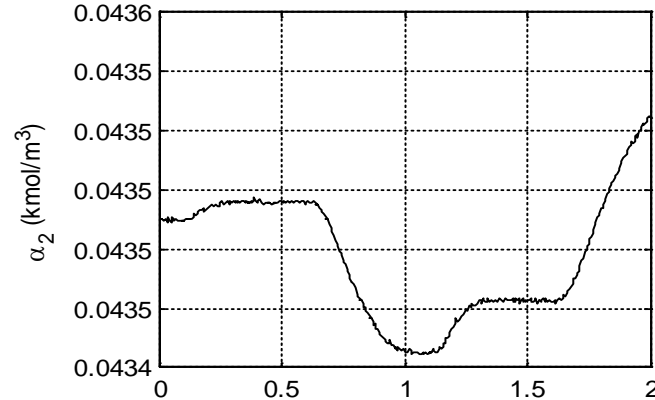
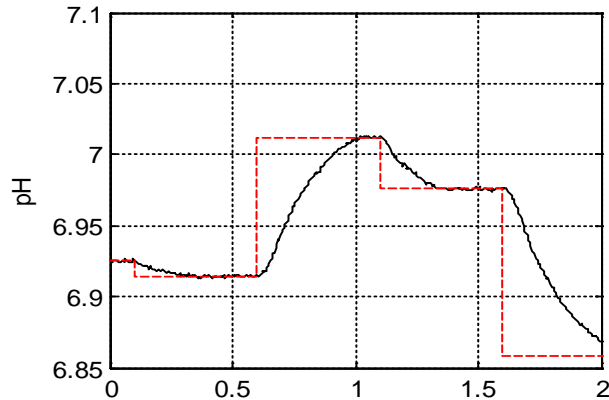
Both controller lead to different final steady-states. NMPC could capture nonlinear behavior during predictions leading to smoother transients

APC FRAMEWORK



Results: DAB-Net based NMPC (input constraints)

Enforced
input rate-
constraint of
 $\pm 1\%$ per
time-step

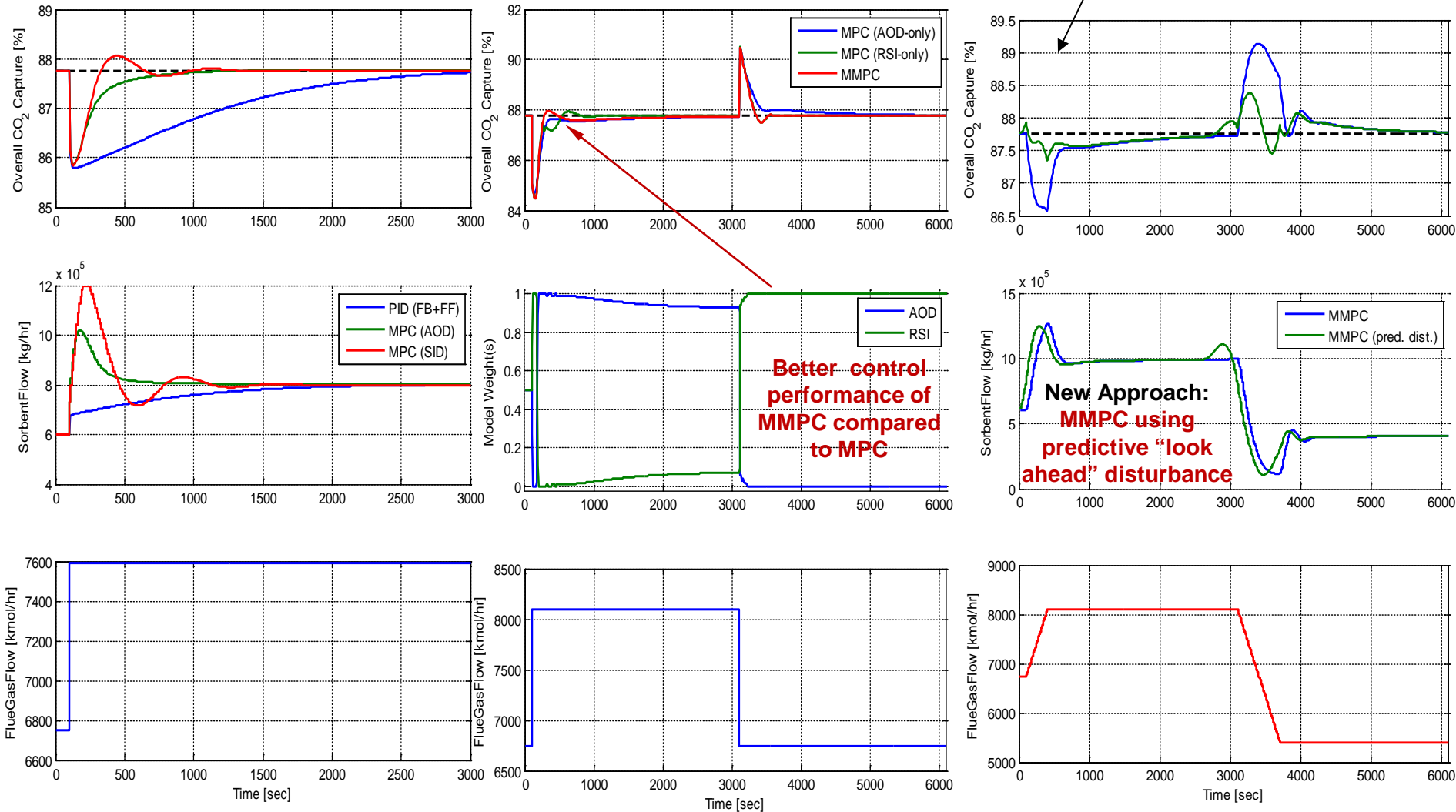


APC FRAMEWORK

Results: MMPC responses



“Look ahead” formulation drastically improves overall CO₂ capture during flue-gas ramp-up.



1. 1D non-isothermal, pressure-driven dynamic models of a two-stage BFB adsorber-reactor, a MB regenerator, an integral gear CO₂ compression system along with the balance of the plant have been developed in ACM and gPROMS for solid-sorbent CO₂ capture.
2. The DAB-Net D-RM is found to be satisfactory for the BFB reactor.
3. DAB-Net based NMPC was developed and was shown to provide superior control response for highly nonlinear systems. The MMPC formulation (especially w/ look-ahead disturbance) is found to provide fast and superior load-tracking performance for overall CO₂ capture.

Acknowledgements

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Questions?