

# Multi-Scale Chemical Process Modeling with Bayesian Nonparametric Regression

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**CCSI**

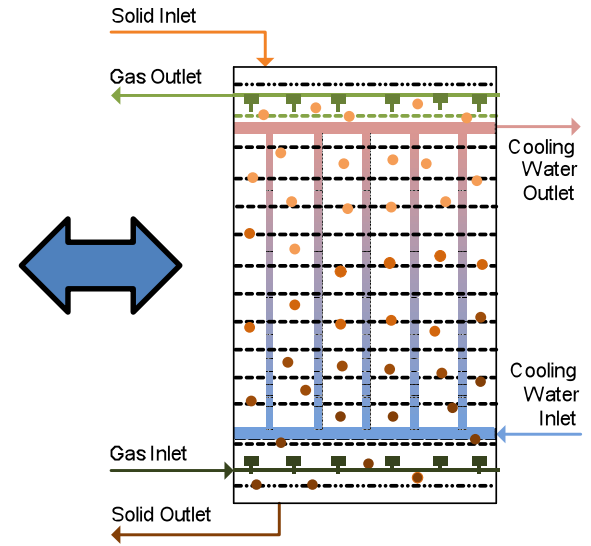
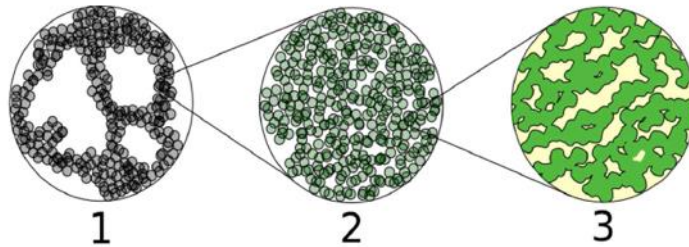
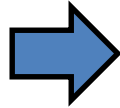
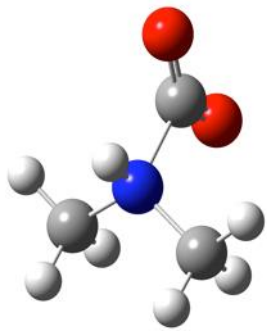
Carbon Capture Simulation Initiative

AICHE Annual Meeting, Salt Lake City

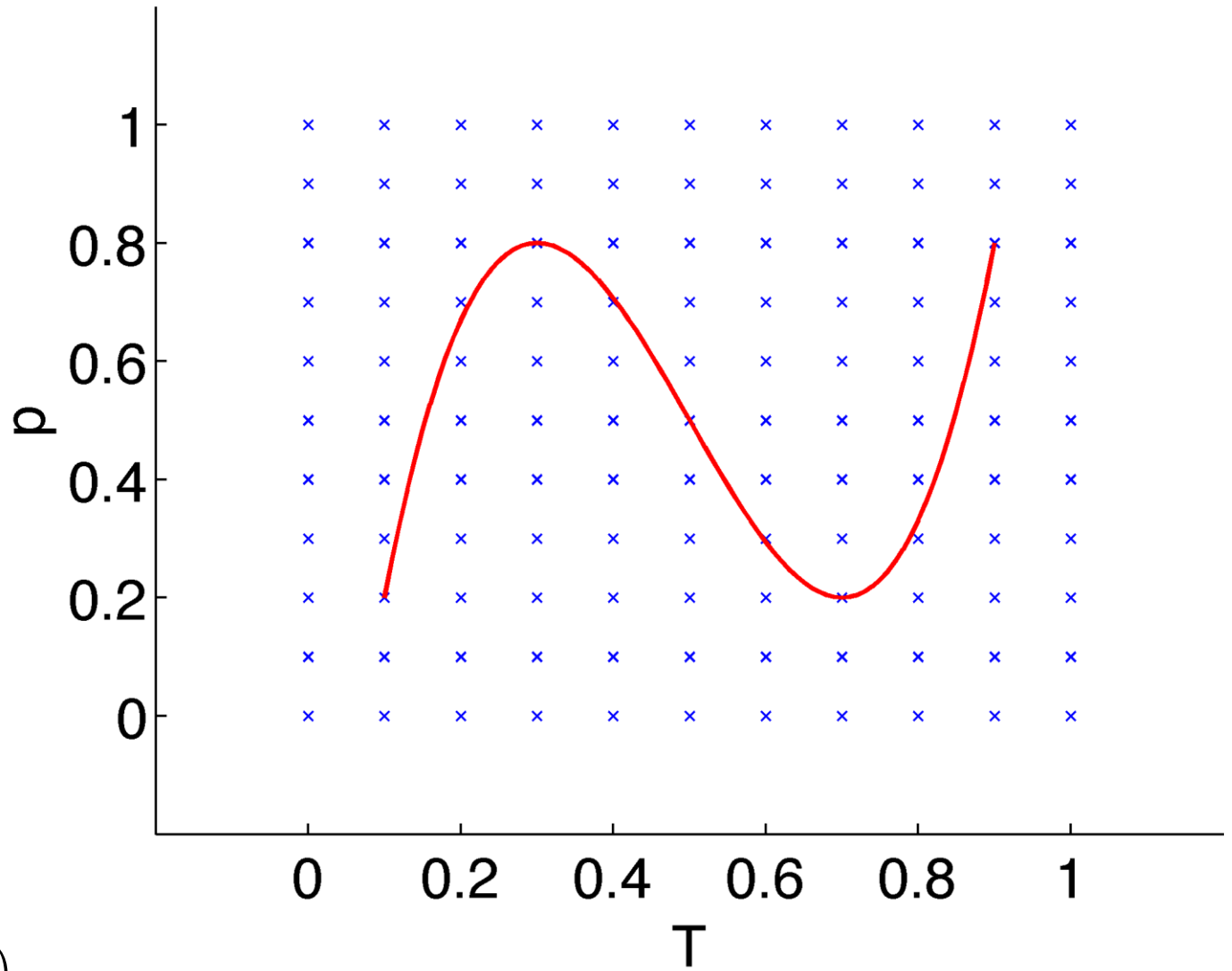
November 10<sup>th</sup>, 2015

# outline

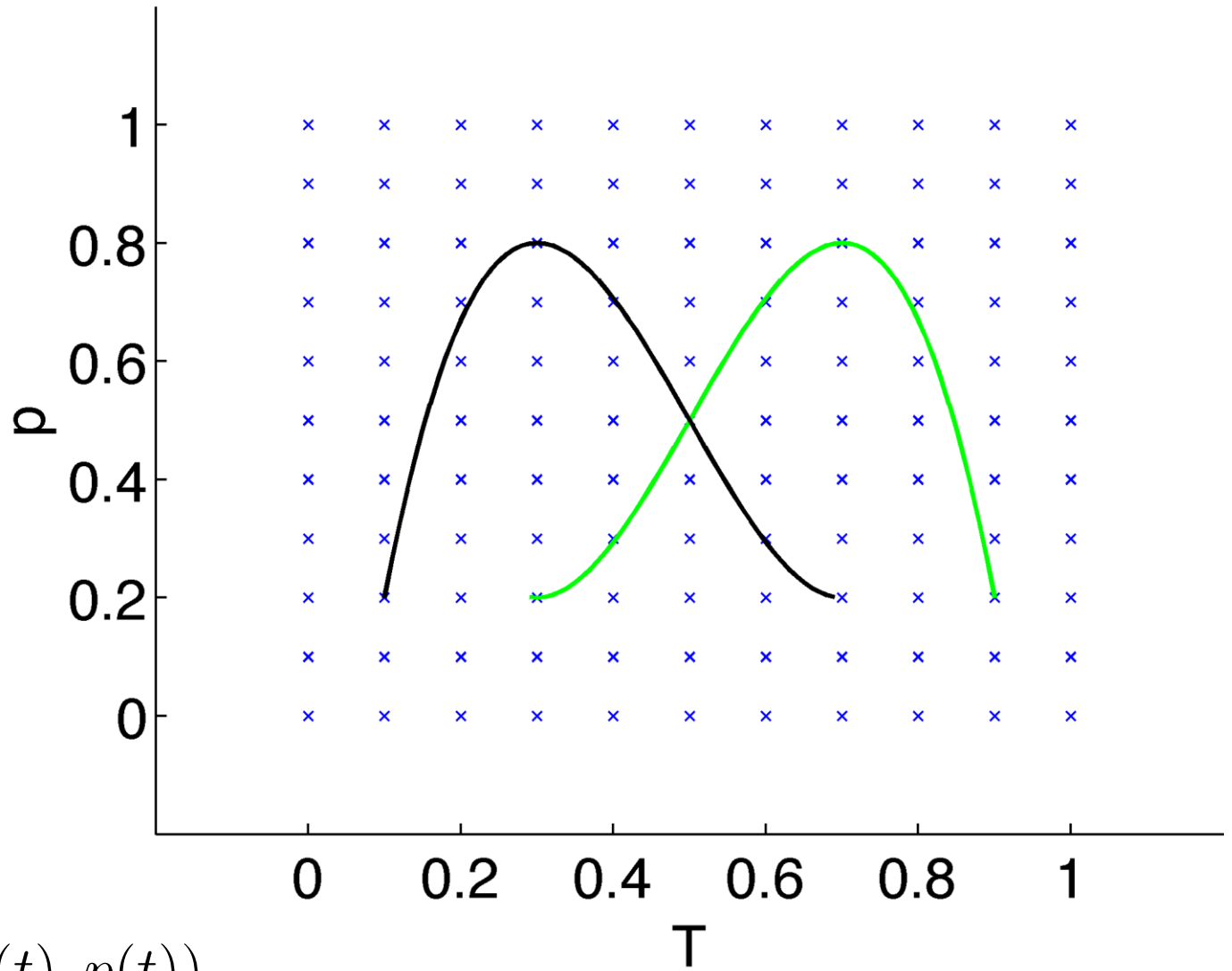
- Reduced modeling and prediction in dynamic systems → uncertainty quantification
- Bayesian calibration and BSS-ANOVA Gaussian processes
- Results in carbon capture: two-state reaction; calibration with propagation from TGA to BFB adsorber
- Results in catalytic steam reformation: 16-state reaction; calibration with propagation from lab-scale CSTR to industrial-scale PFR



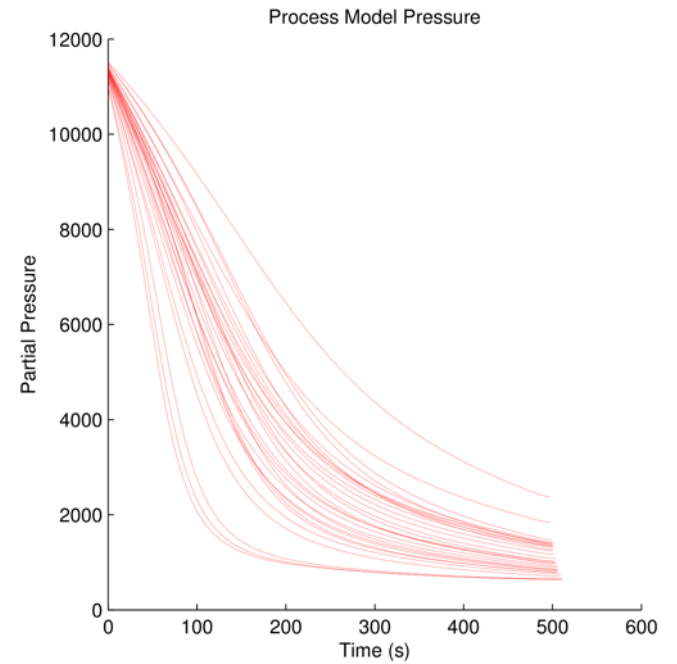
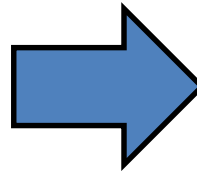
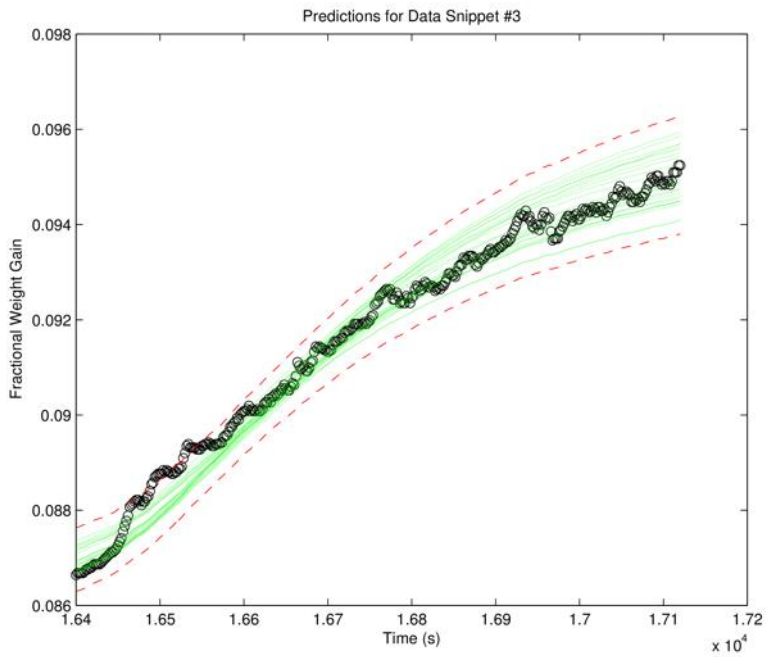
Bench-scale data: TGA, fixed bed, etc.



$$x = f(T, p)$$



$$\dot{x} = f(x, T(t), p(t))$$



K.S. Bhat, DSM, *et al.*, submitted, arXiv:1411.2578.

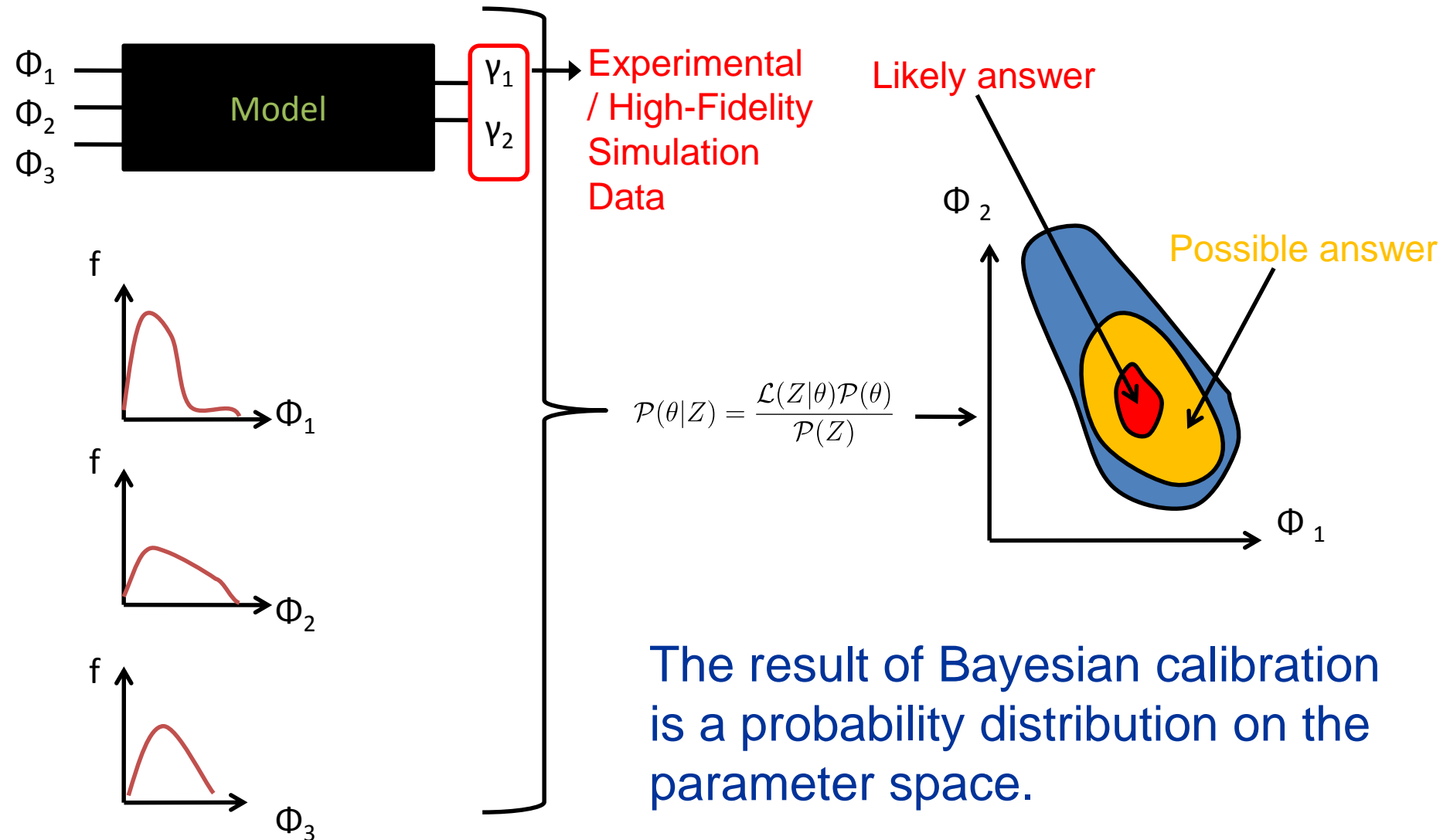
# what is Bayesian statistics?

- Two ways to think about probability:
  - Stuff is really random (rainfall) → aleatory uncertainty
  - Stuff is not really random, we just don't know what it is (oddsmaking) → epistemic uncertainty
- Bayesian statistics handles both kinds.
- Things that we think of as fixed values can now have probability distributions.
- How do these probability distributions evolve in light of evidence?
- Bayes' theorem:

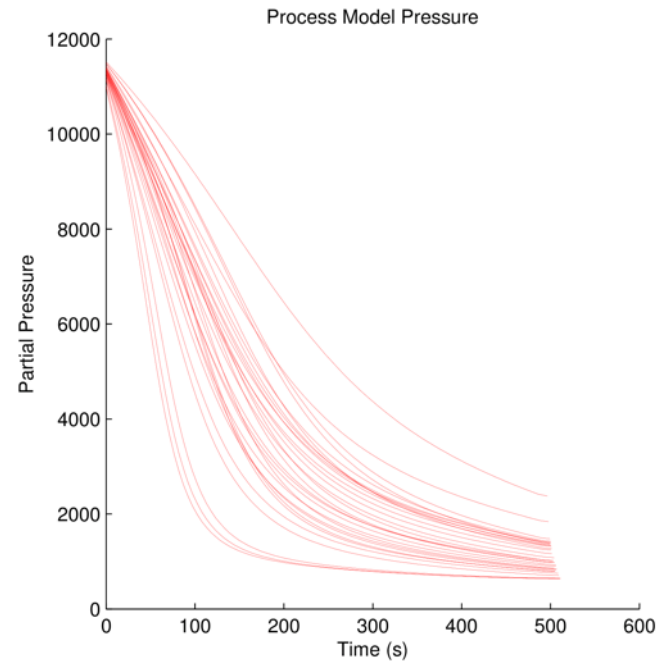
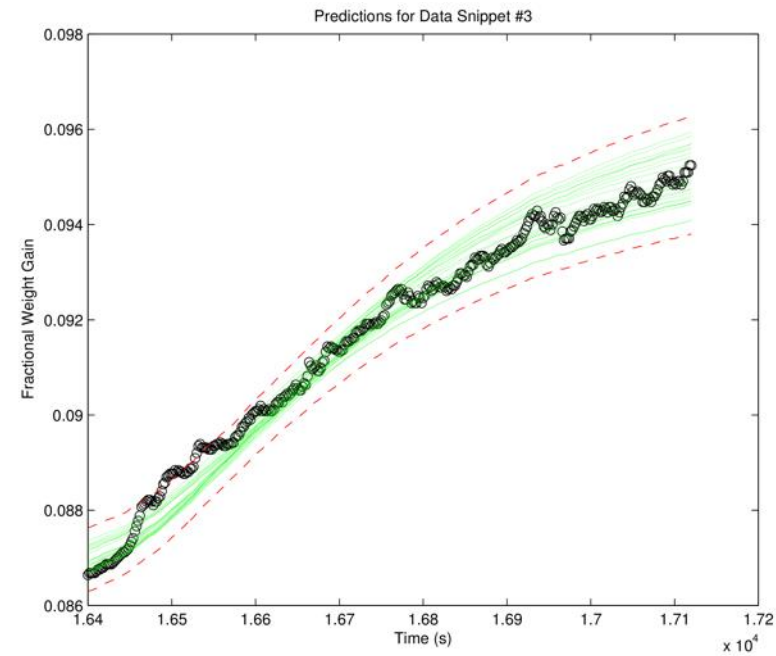
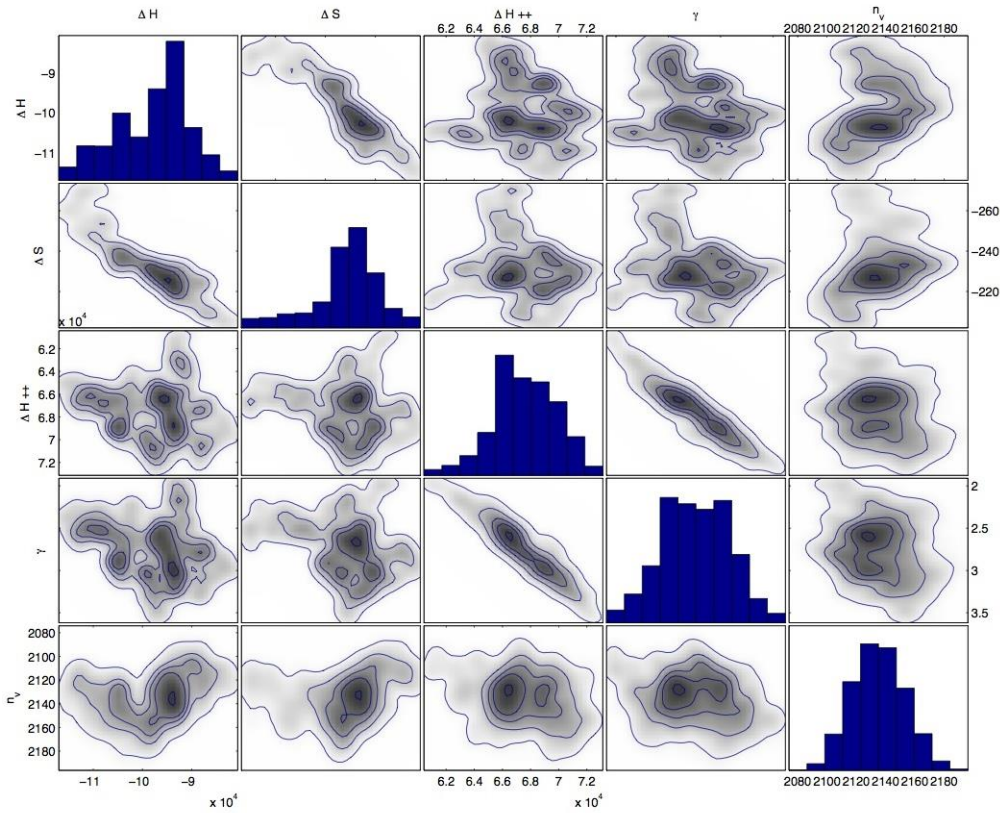
$$\mathcal{P}(\theta|Z) = \frac{\mathcal{L}(Z|\theta)\mathcal{P}(\theta)}{\mathcal{P}(Z)}$$

new odds = (old odds)(evidence adjustment)

# Bayesian model-based analysis







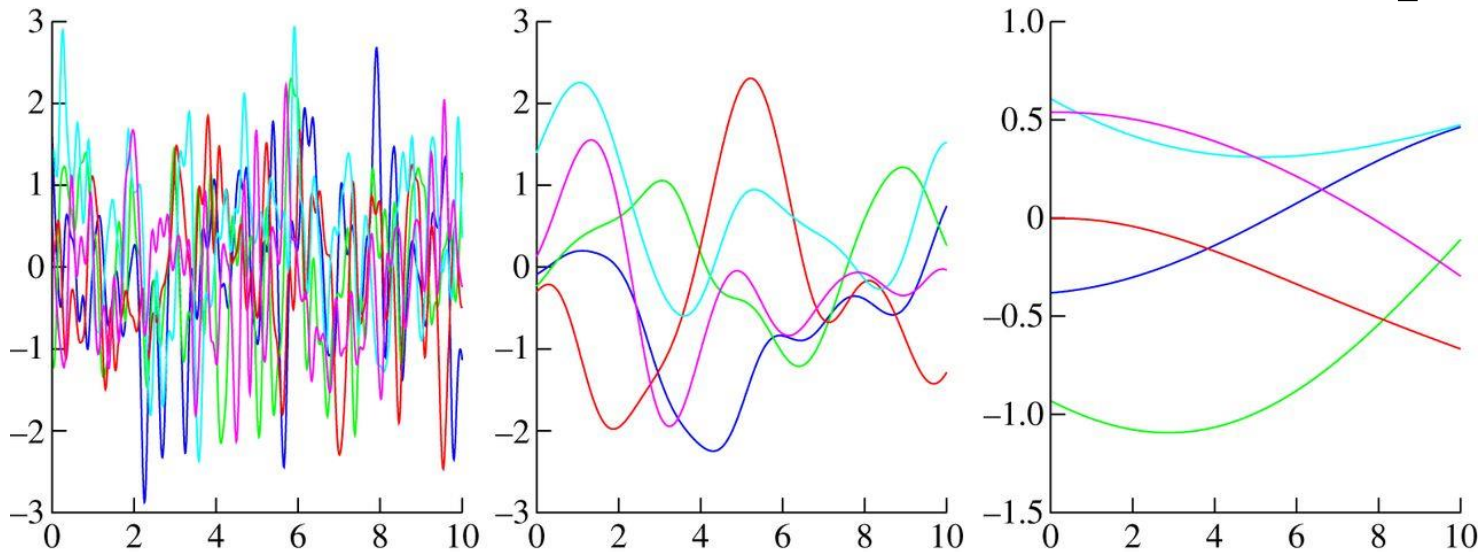
K.S. Bhat, DSM, *et al.*, submitted, arXiv:1411.2578.

$$\dot{x} = f(x, T(t), p(t))$$

- What is the form of  $f$ ?
  - flexible
  - easy for calibration
  - physically constrained

Gaussian process  $f = f(\theta, \delta) \quad \delta \sim MVN(0, \Gamma)$

$$\Gamma_{ij} = \sigma^2 \exp \left[ \frac{(\vartheta_i - \vartheta_j)^2}{\phi} \right]$$



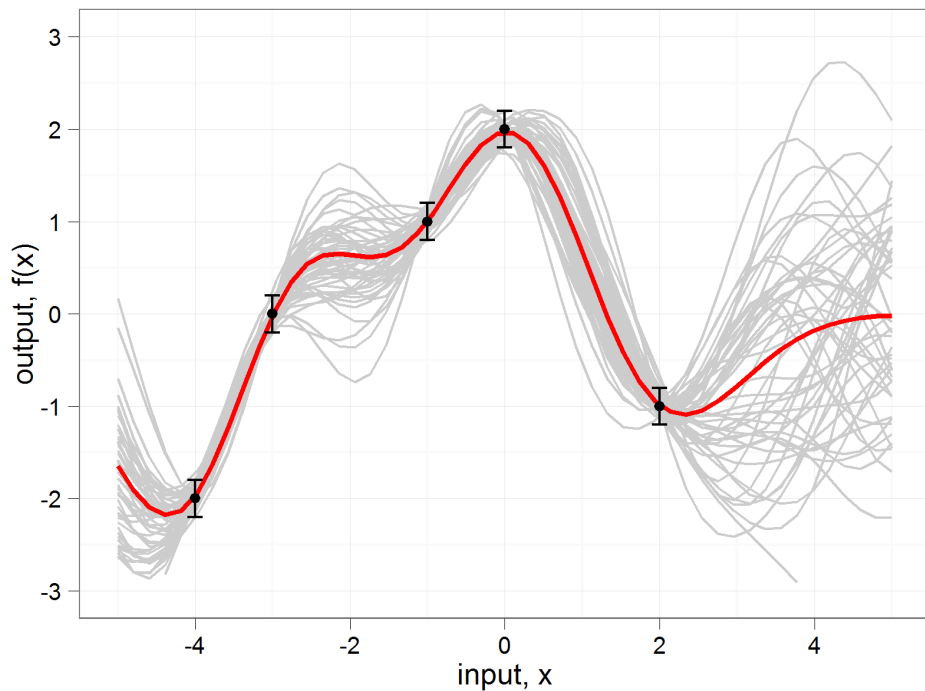
S. Roberts, *et al.*, *Phil. Trans. A* **371** (2013) 20110550.

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James Keirstead, Imperial College

$$\delta \sim MVN(0, \Gamma)$$

$$\Gamma(\vartheta, \vartheta') = \sigma_0^2 + \sum_{k=1}^K \sigma_k^2 \Gamma_1(\vartheta_k, \vartheta'_k) + \sum_{k=1}^{K-1} \sum_{l=k+1}^K \sigma_{kl}^2 \Gamma_2([\vartheta_k, \vartheta_l], [\vartheta'_k, \vartheta'_l]) + \dots$$

$$\Gamma_1(\vartheta_k, \vartheta'_k) = \mathcal{B}_1(\vartheta_k) \mathcal{B}_1(\vartheta'_k) + \mathcal{B}_2(\vartheta_k) \mathcal{B}_2(\vartheta'_k) - \frac{1}{4!} \mathcal{B}_4(|\vartheta_k - \vartheta'_k|)$$

$$\Gamma_2([\vartheta_k, \vartheta_l], [\vartheta'_k, \vartheta'_l]) = \Gamma_1(\vartheta_k, \vartheta'_k) \Gamma_1(\vartheta_l, \vartheta'_l)$$

$$\delta(\vartheta; \beta) = \beta_0 + \sum_{k=1}^K \sum_{m=1}^M \beta_{mk} \varphi_{m1}(\vartheta_k) + \sum_{k=1}^{K-1} \sum_{l=k+1}^K \sum_{m=1}^M \beta_{mkl} \varphi_{m2}(\vartheta_k, \vartheta_l) + \dots$$

$$\beta_{mk} \sim N(0, \lambda_{m1} \sigma_k^2)$$

$$\beta_{mkl} \sim N(0, \lambda_{m2} \sigma_{kl}^2)$$

$$\dot{x}_i = f_i(x_i, x_j; k_i, \kappa_i)$$

$$k_i = k_i^0 \exp \left[ \delta_{k_i}(x_i, x_j, T; \beta_{k_{ij}T}) \right]$$

$$\kappa_i = \kappa_i^0 \exp \left[ \delta_{\kappa_i}(x_i, x_j, T; \beta_{\kappa_{ij}T}) \right]$$

B.J. Reich, *et al.*, *Technometrics* **51** (2009) 110.

K.S. Bhat, DSM, *et al.*, submitted, arXiv:1411.2578.

- All draws belong to a 2<sup>nd</sup>-order Sobolev space.
- Orthogonal basis functions → ordered set for model building.
- Dynamics physically constrained as chemical rate expressions.
- *betas* block proposed in calibration.

$$\delta(\vartheta; \beta) = \beta_0 + \sum_{k=1}^K \sum_{m=1}^M \beta_{mk} \varphi_{m1}(\vartheta_k) + \sum_{k=1}^{K-1} \sum_{l=k+1}^K \sum_{m=1}^M \beta_{mkl} \varphi_{m2}(\vartheta_k, \vartheta_l) + \dots$$

$$\beta_{mk} \sim N(0, \lambda_{m1} \sigma_k^2)$$

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$$\dot{x}_i = f_i(x_i, x_j; k_i, \kappa_i)$$

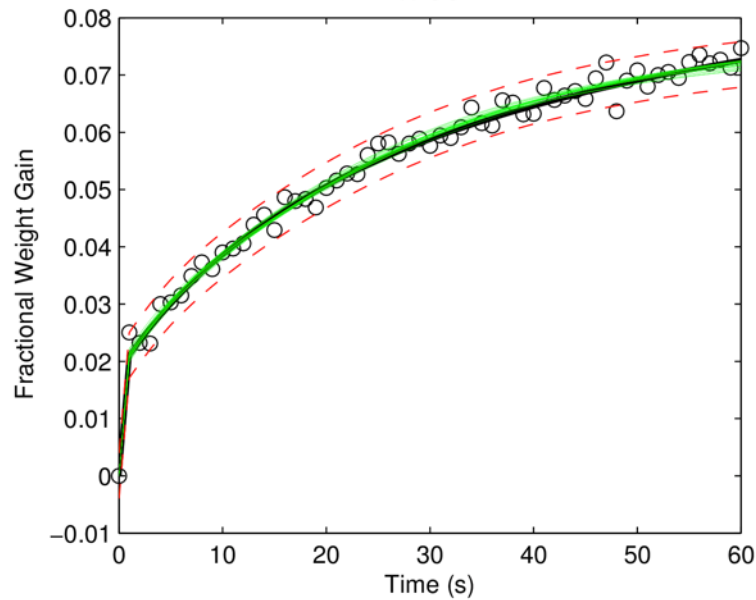
$$k_i = k_i^0 \exp \left[ \delta_{k_i}(x_i, x_j, T; \beta_{k_{ij}T}) \right]$$

$$\kappa_i = \kappa_i^0 \exp \left[ \delta_{\kappa_i}(x_i, x_j, T; \beta_{\kappa_{ij}T}) \right]$$

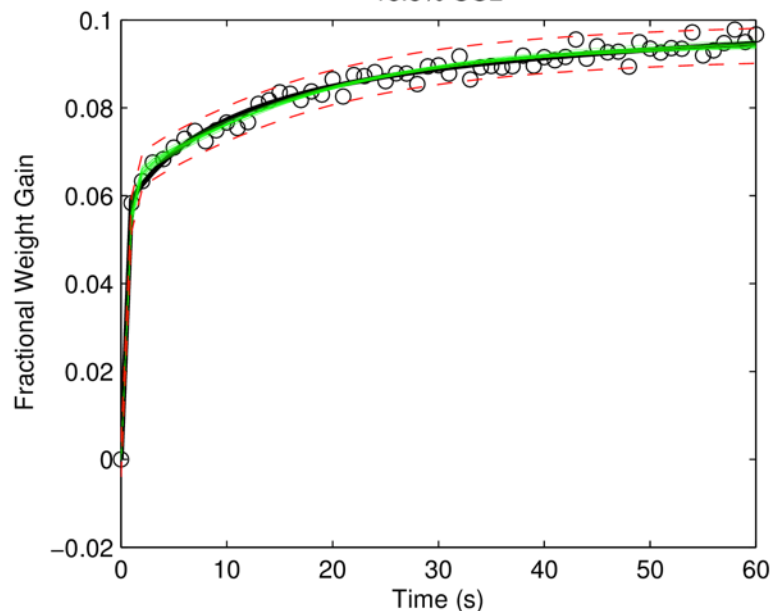
B.J. Reich, et al., *Technometrics* **51** (2009) 110.

K.S. Bhat, DSM, *et al.*, submitted, arXiv:1411.2578.

4% CO2



18.5% CO2



$$\dot{z} = k_z \left[ p(1 - 2x) - z/\kappa_z \right] - k_x \left[ z(1 - 2x) - x^2/\kappa_x \right]$$

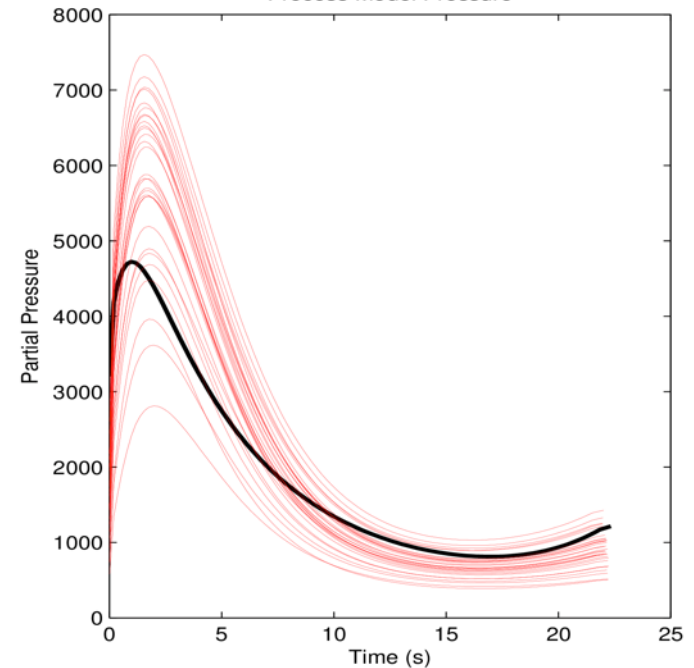


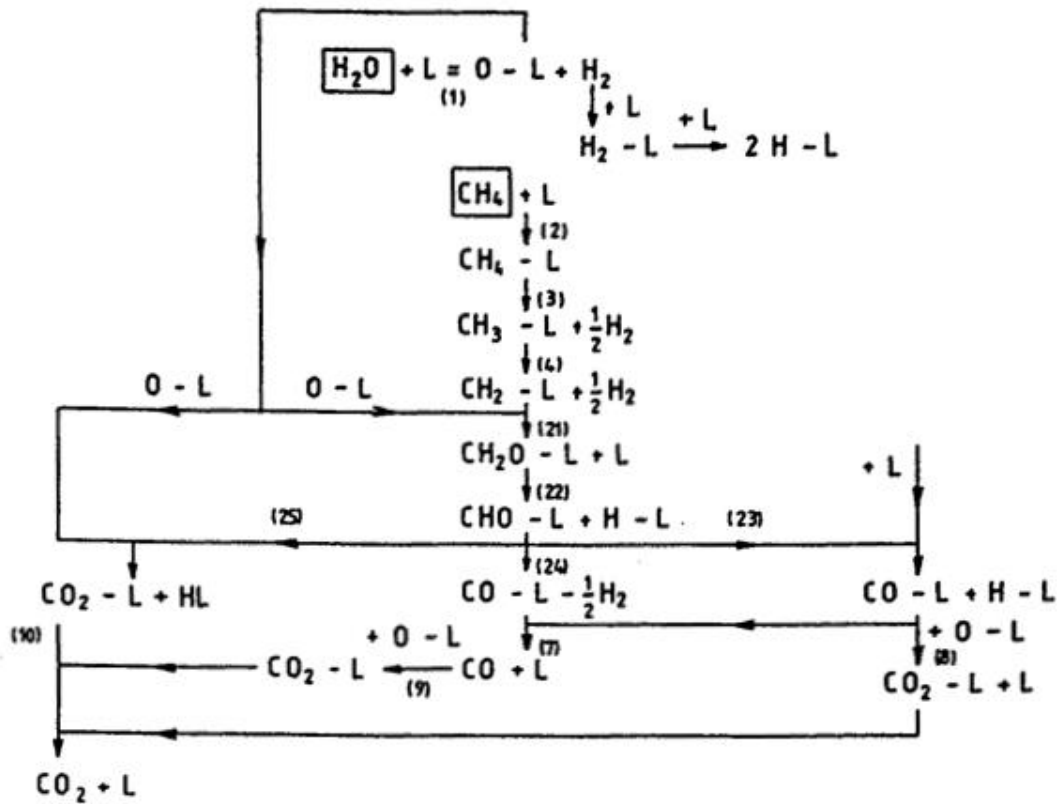
$$\dot{x} = k_x \left[ z(1 - 2x) - x^2/\kappa_x \right]$$

$$\dot{x} = k^0 \exp \left[ \delta_k(x, p, T) \right] \left\{ p(1 - 2x)^2 - x^2/\kappa^0 \exp \left[ \delta_K(p, T) \right] \right\}$$

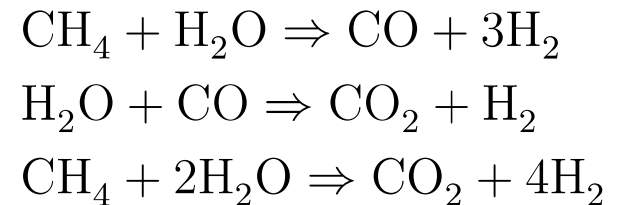
K.S. Bhat, DSM, *et al.*, submitted, arXiv:1411.2578.

Process Model Pressure



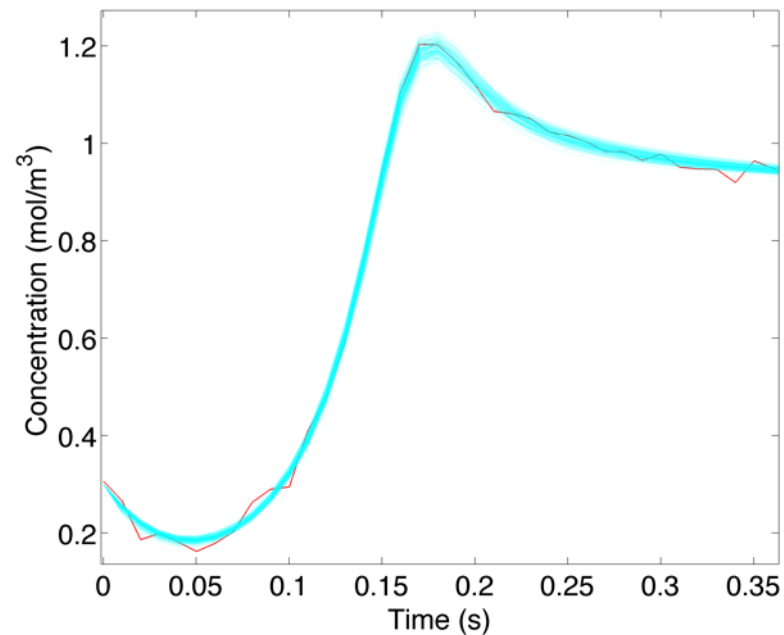
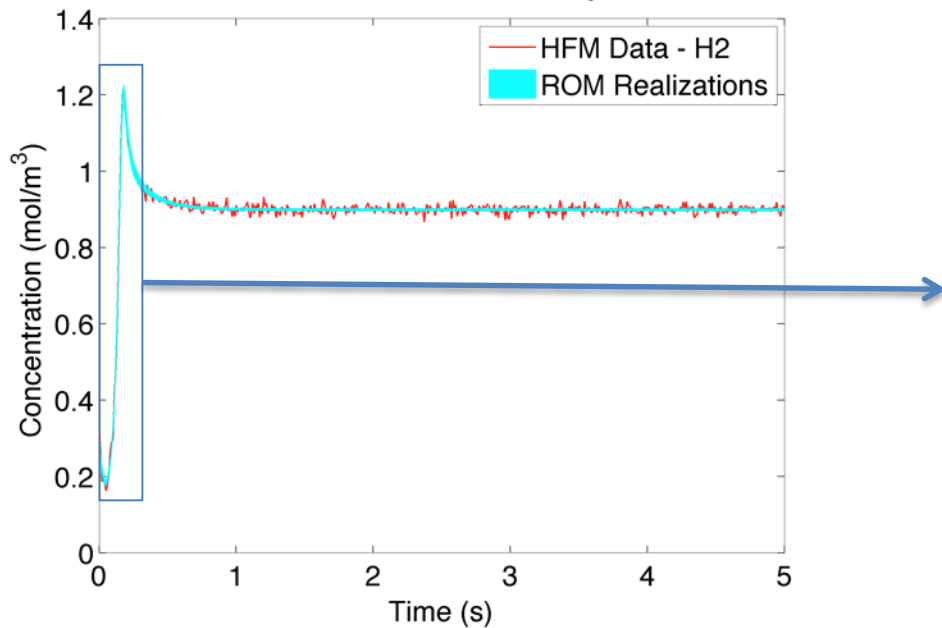


J. Xu and G.F. Froment, *AIChE J.* **35** (1989) 88.

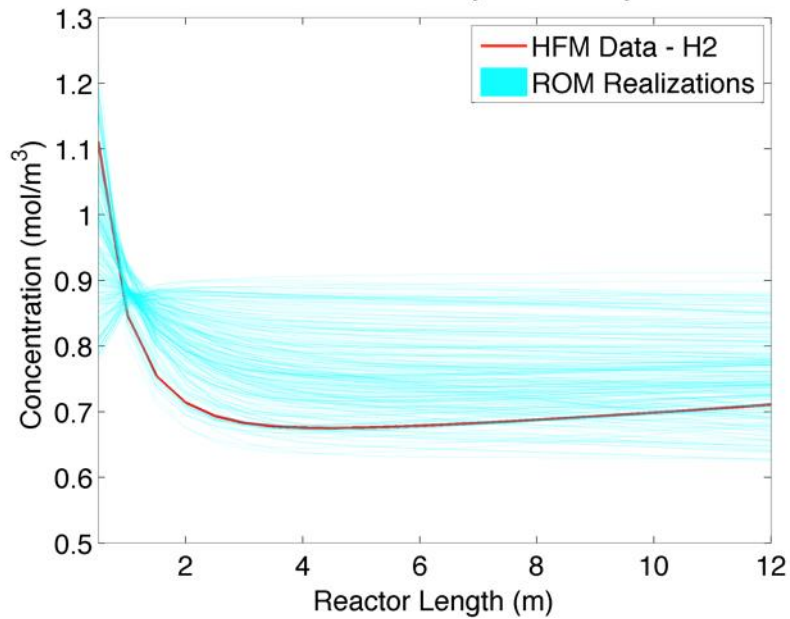




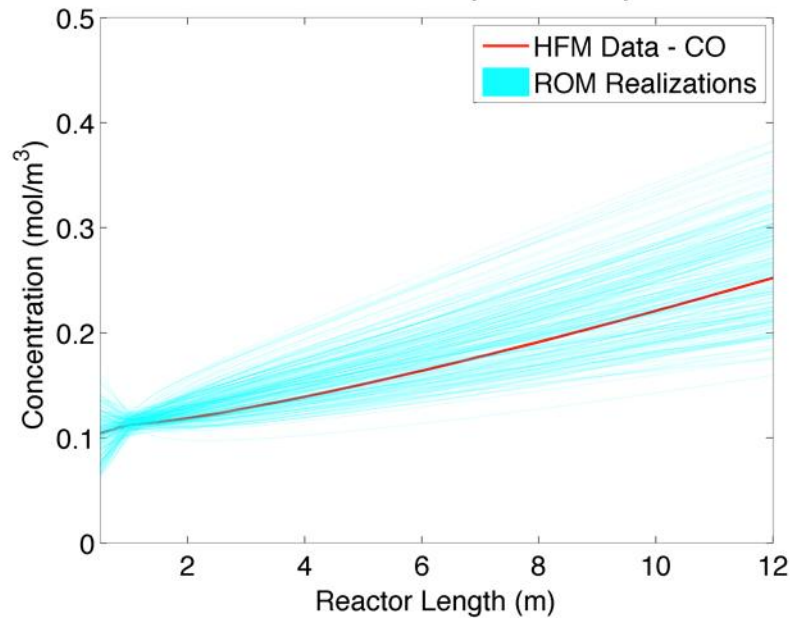
Lab Scale CSTR Transient Analysis - H2



Industrial Scale PFR Steady State Analysis - H2



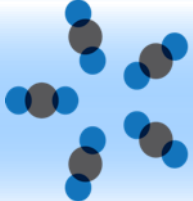
Industrial Scale PFR Steady State Analysis - CO





# what's next?

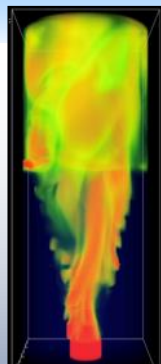
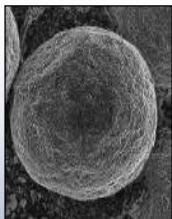
- Harder and harder problems: Fischer-Tropsch is up next.
- Solutions for optimization and design under uncertainty
- Solutions for machine learning-based control
- Automated model building for dynamic systems



# CCSI

Carbon Capture Simulation Initiative

# Accelerating Technology Development



Rapidly synthesize optimized processes to identify promising concepts



Better understand internal behavior to reduce time for troubleshooting



Quantify sources and effects of uncertainty to guide testing & reach larger scales faster



Stabilize the cost during commercial deployment

## National Labs



## Academia



## Industry



# acknowledgements

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National Energy Technology Lab

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