



Surrogate-based optimization of simulated energy systems

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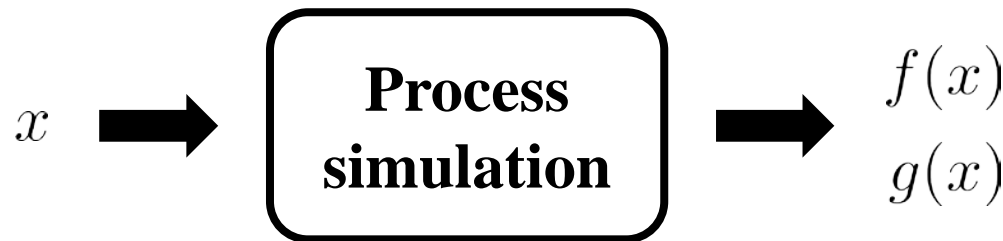
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SIMULATION-BASED OPTIMIZATION

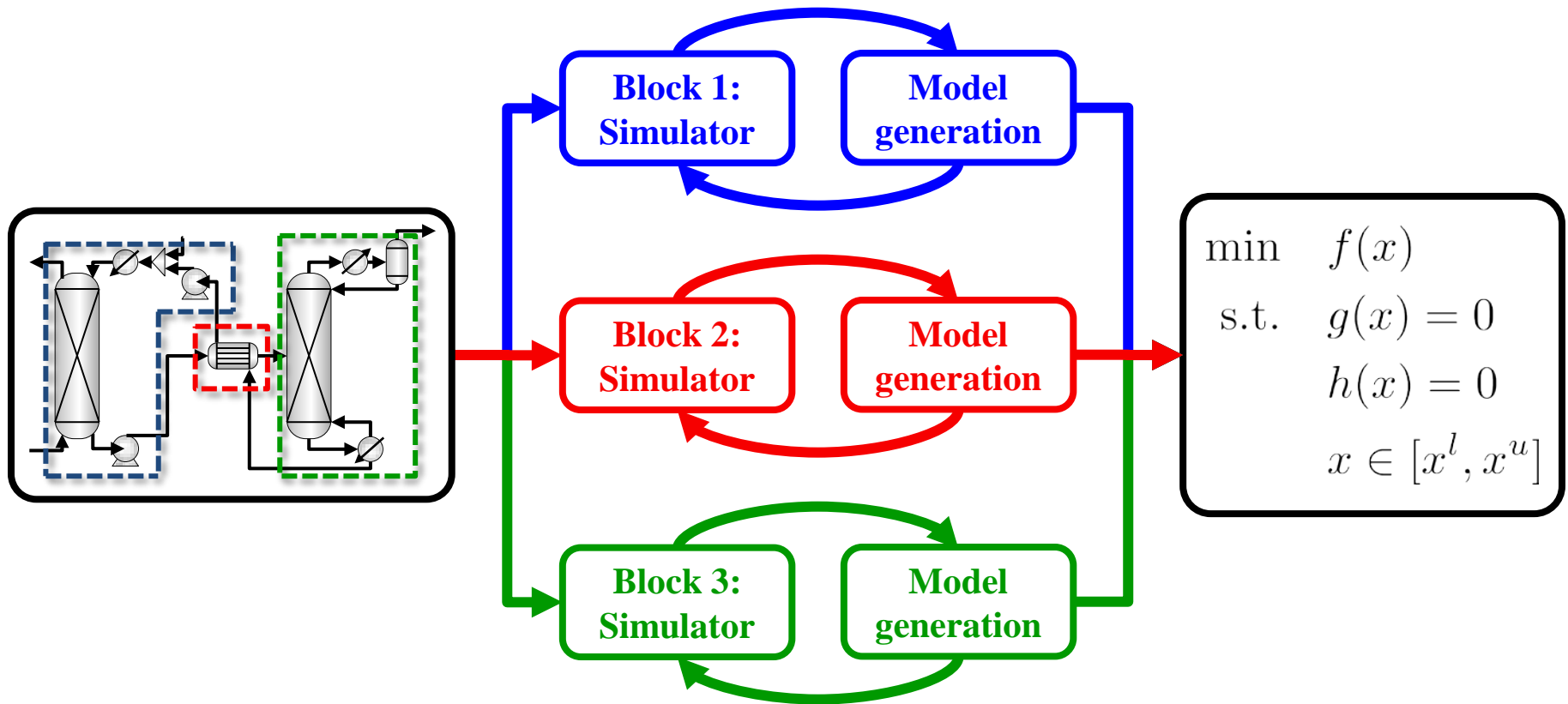
$$\begin{aligned} \min \quad & f(x) \\ \text{s.t.} \quad & g(x) = 0 \\ & h(x) = 0 \\ & x \in [x^l, x^u] \end{aligned}$$



- **Challenges and solutions:**

- Lack of an algebraic model → Build surrogate models
- Computationally costly simulations → Selectively choose a minimal data set
- Often noisy function evaluations → Use regression surrogate models
- Scarcity of fully robust simulations → Disaggregate the process

PROCESS DISAGGREGATION



Process Simulation

Disaggregate process into process **blocks**

Surrogate Models

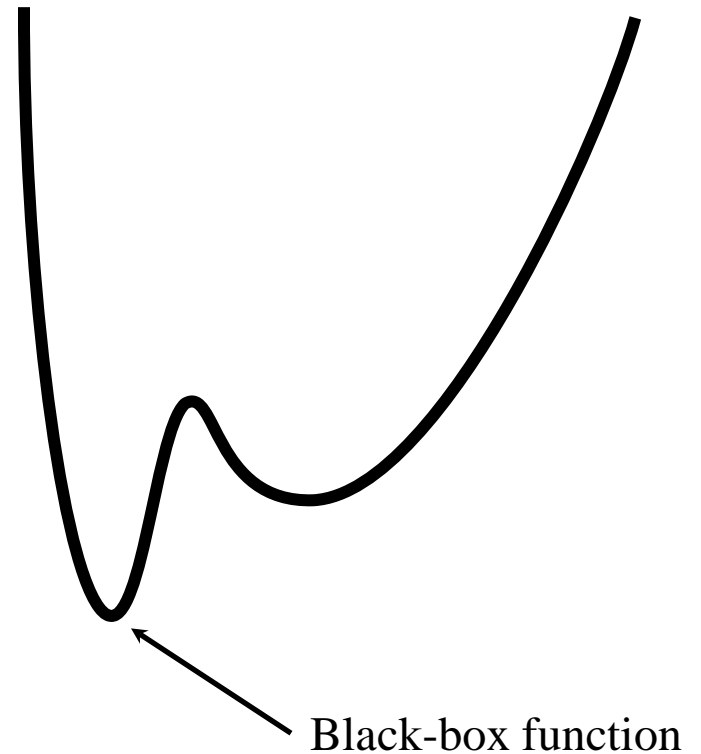
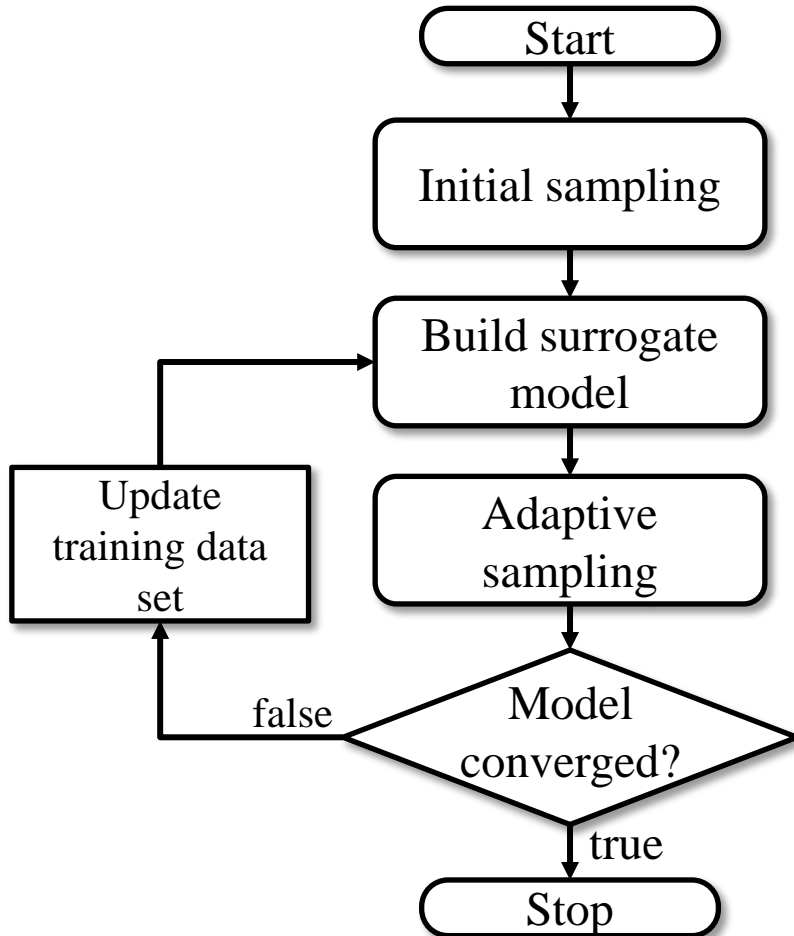
Build **simple** and **accurate** models with a functional form tailored for an optimization framework

Optimization Model

Add algebraic constraints $h(x)=0$: design specs, heat/mass balances, and logic constraints

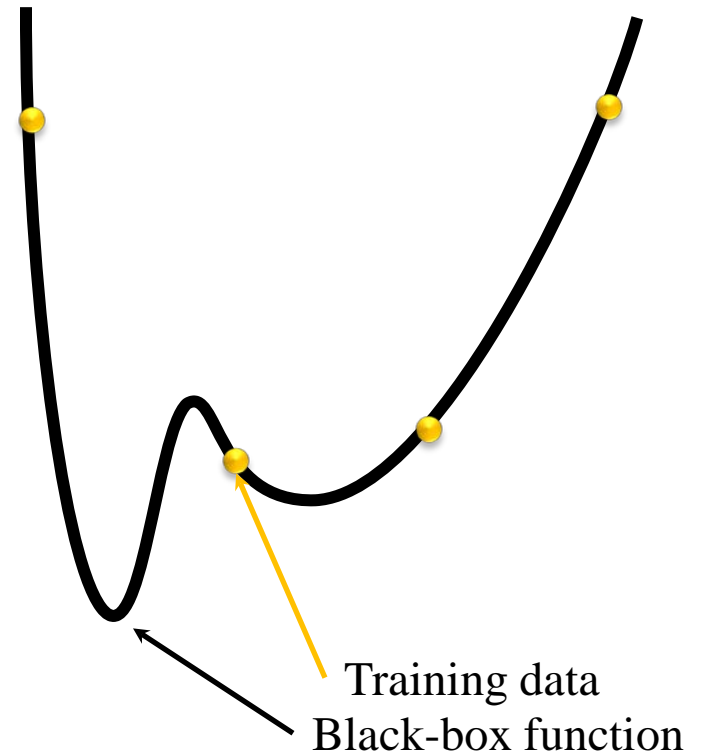
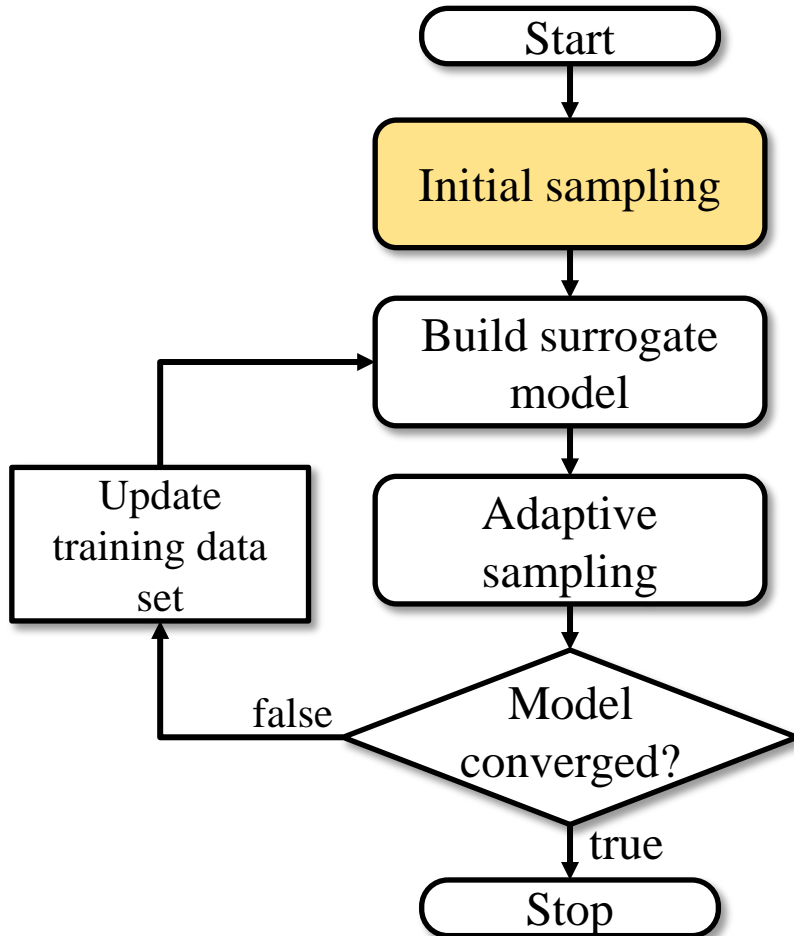
ALAMO

Automated Learning of Algebraic Models for Optimization



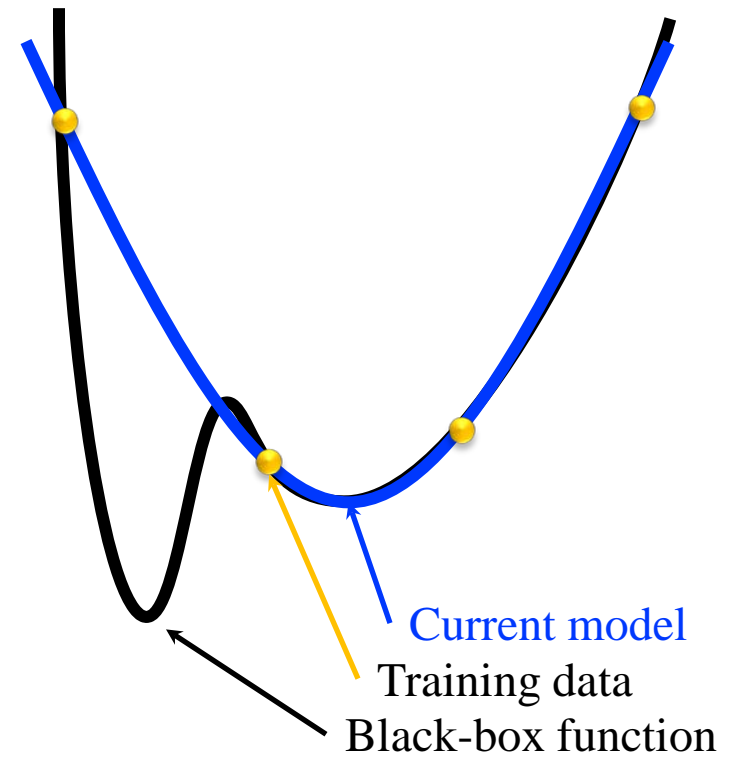
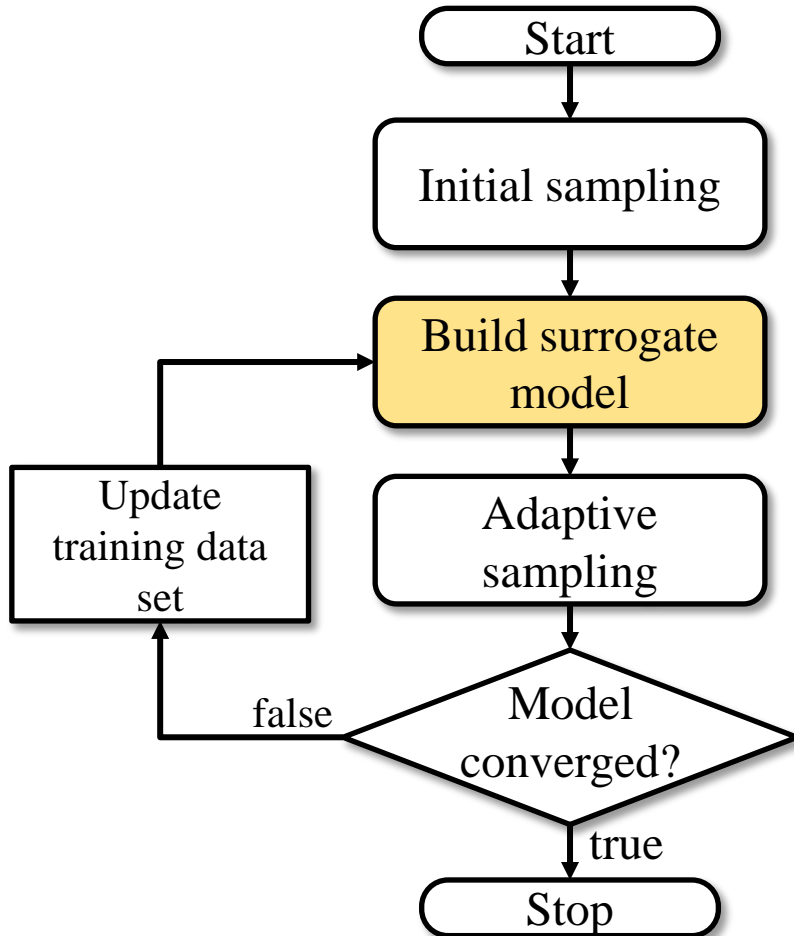
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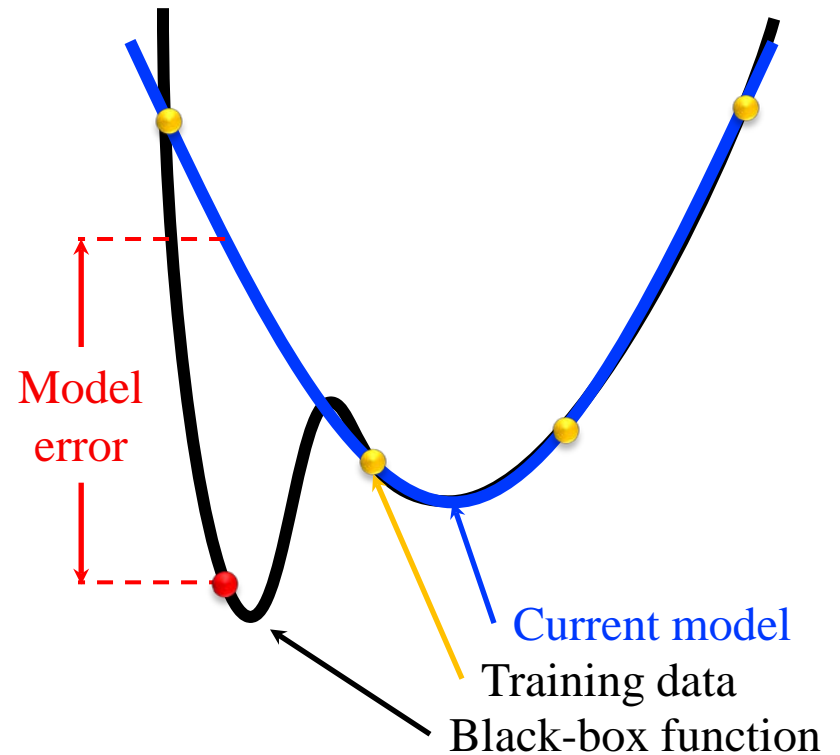
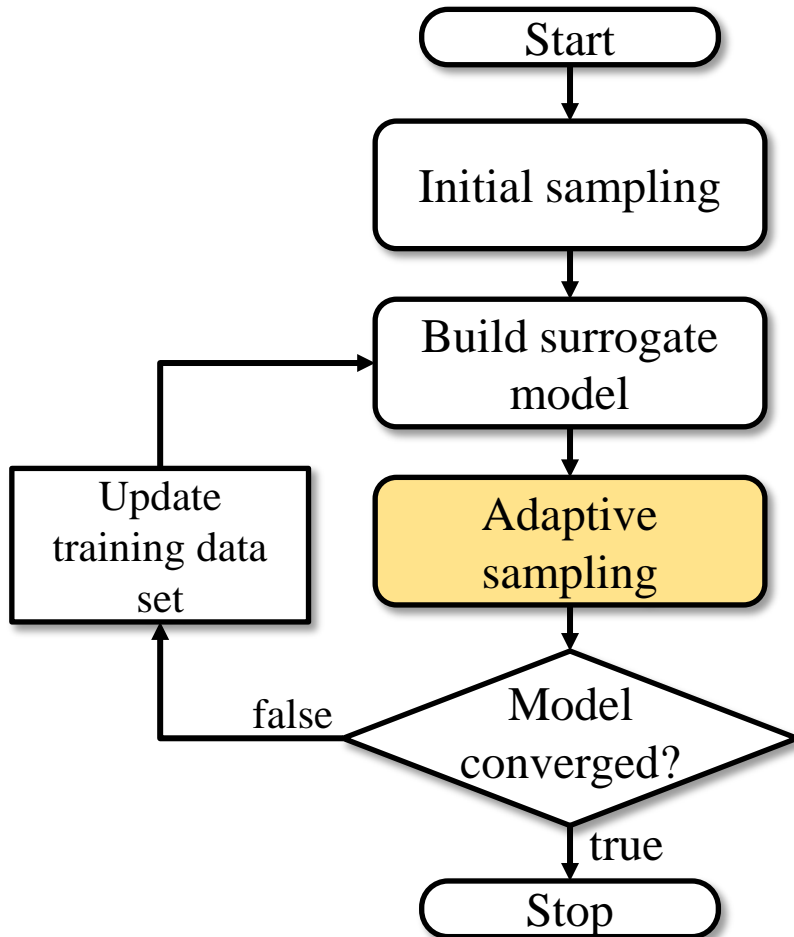
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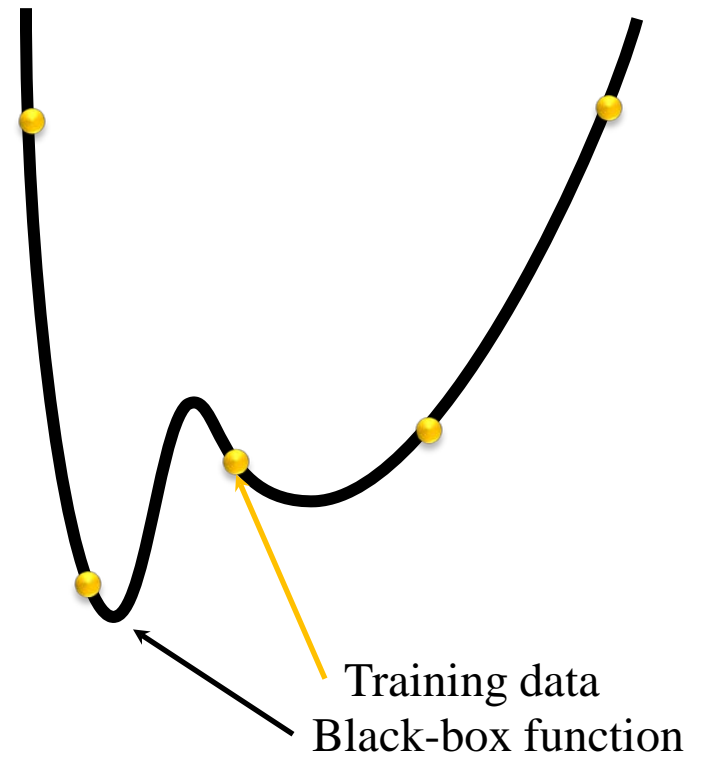
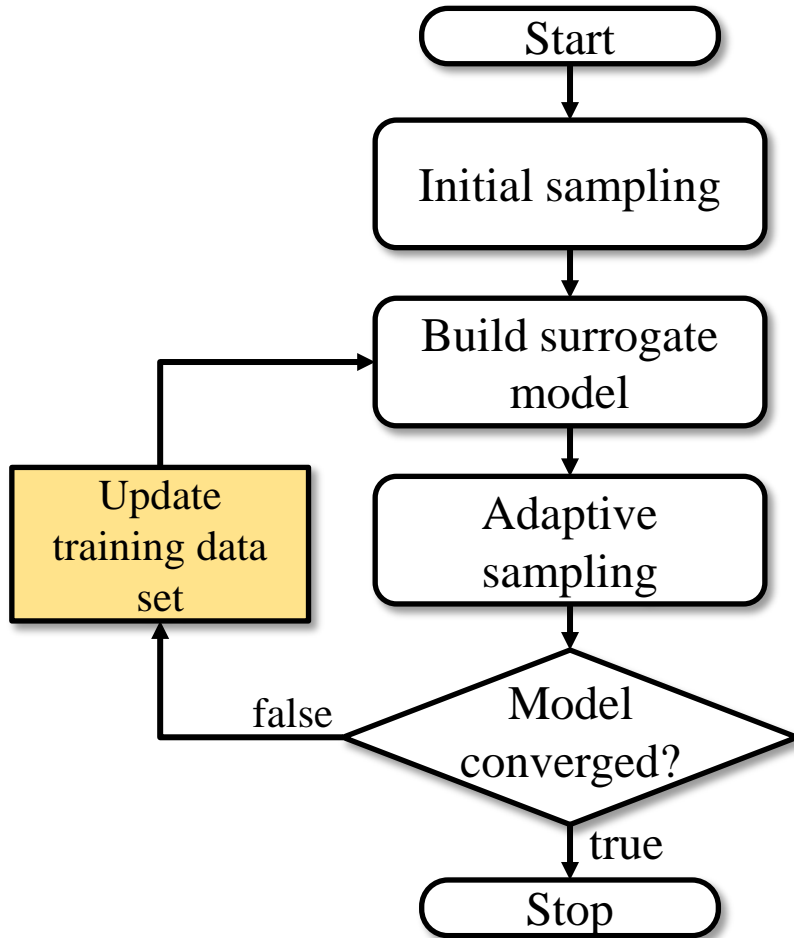
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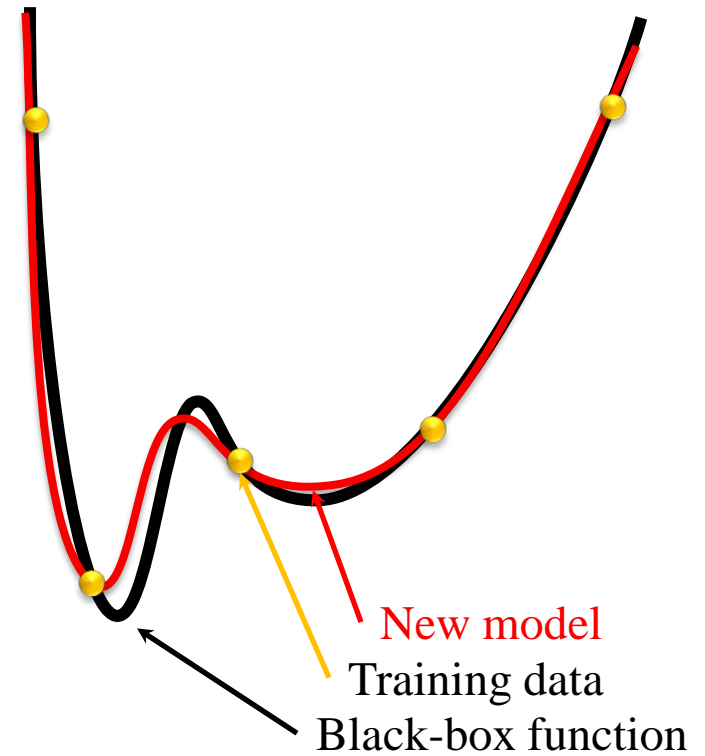
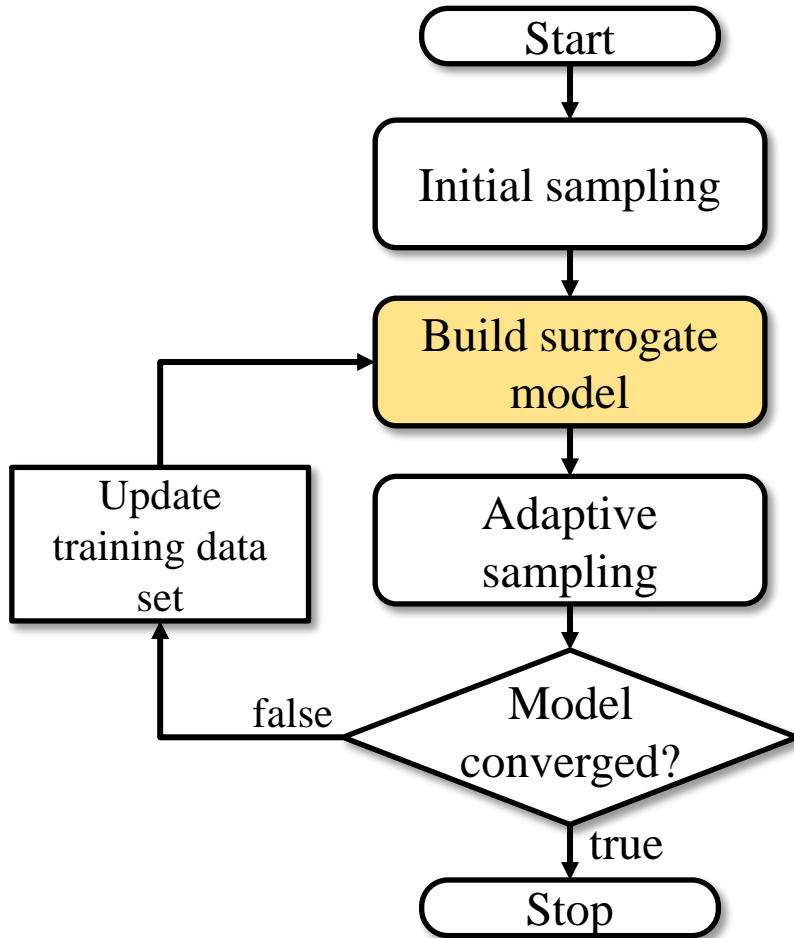
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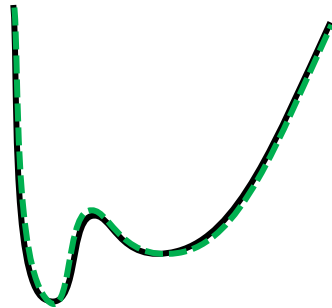
HOW TO BUILD THE SURROGATES

- We aim to build surrogate models that are

- ✓ **Accurate**

- ✓ *We want to reflect the true nature of the simulation*

- ✓ **Tailored for algebraic optimization**

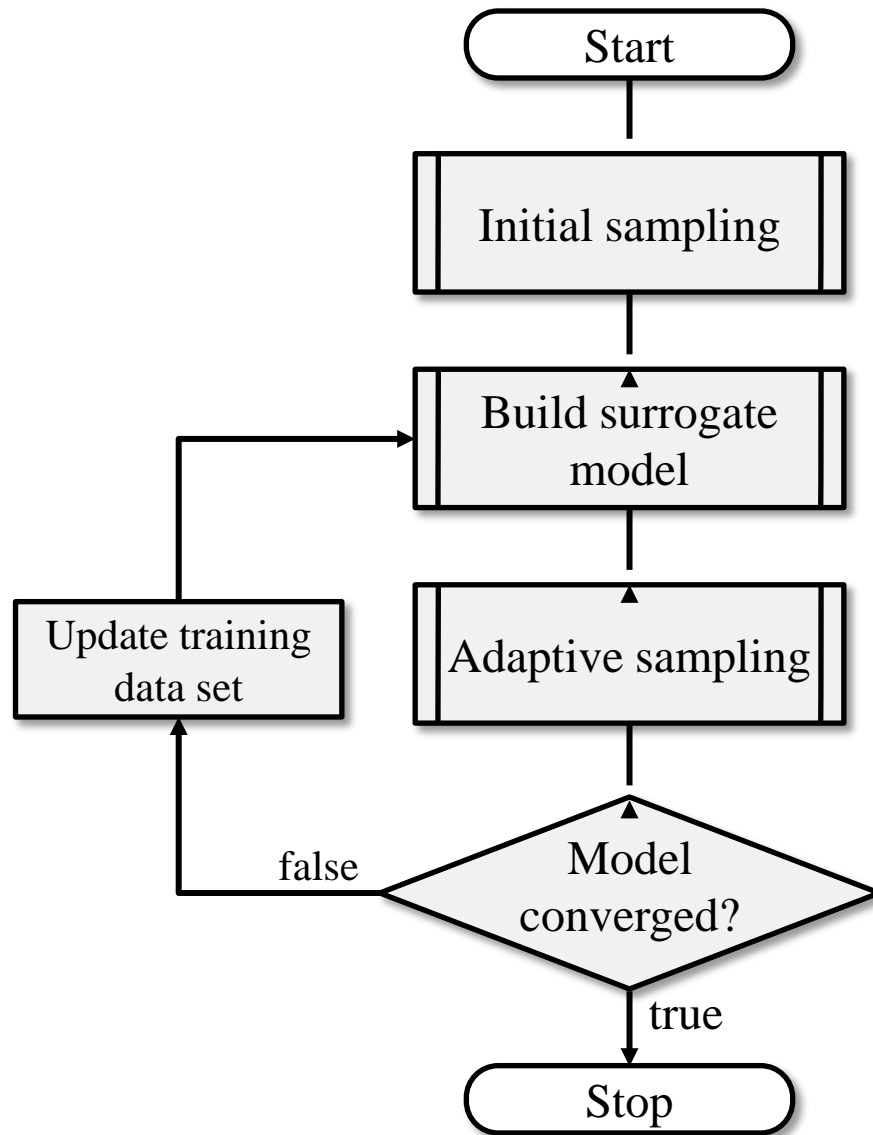


$$\hat{f}(x) = \sum_{i=1}^n \gamma_i \exp\left(\frac{\|x\|}{\sigma^2}\right) + \beta_0 + \beta_1 x + \dots$$

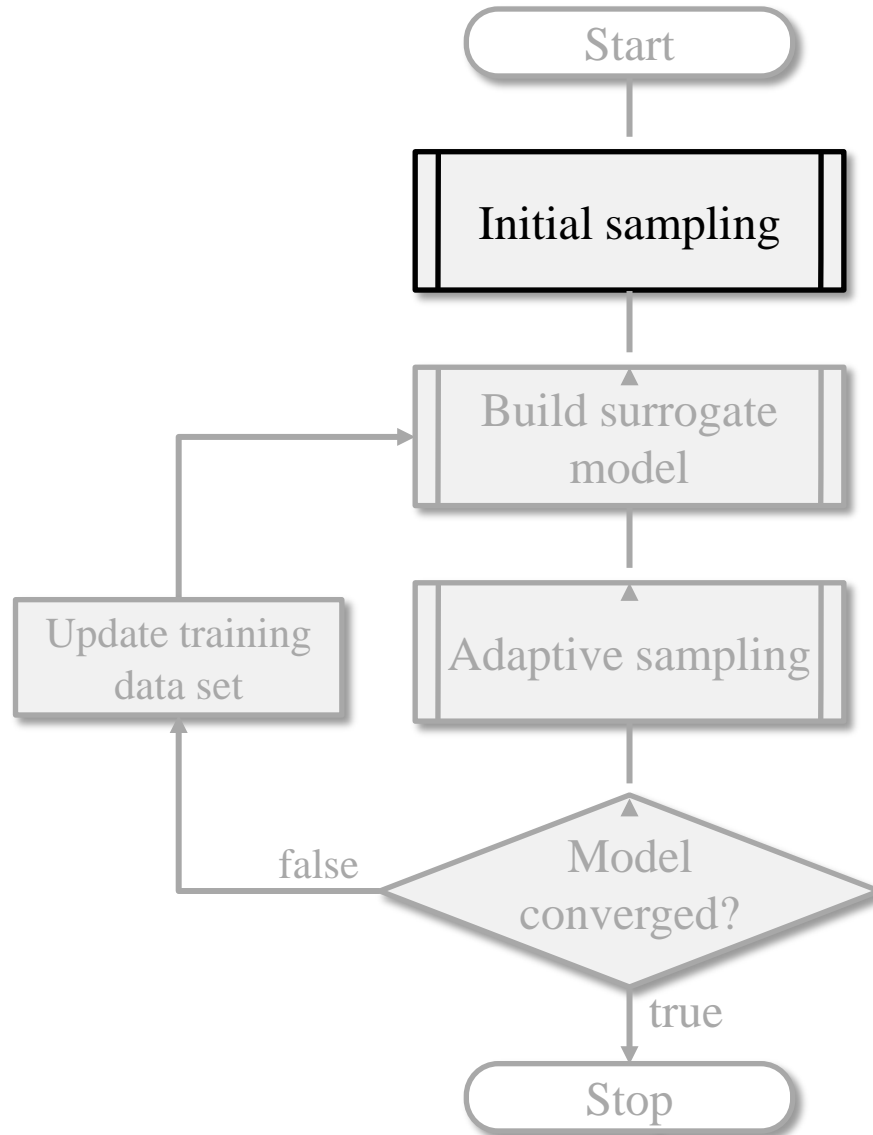
$$\hat{f}(x) = \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \beta_4 e^x$$

- ✓ **Generated from a minimal data set**

ALGORITHMIC FLOWSHEET



ALGORITHMIC FLOWSHEET



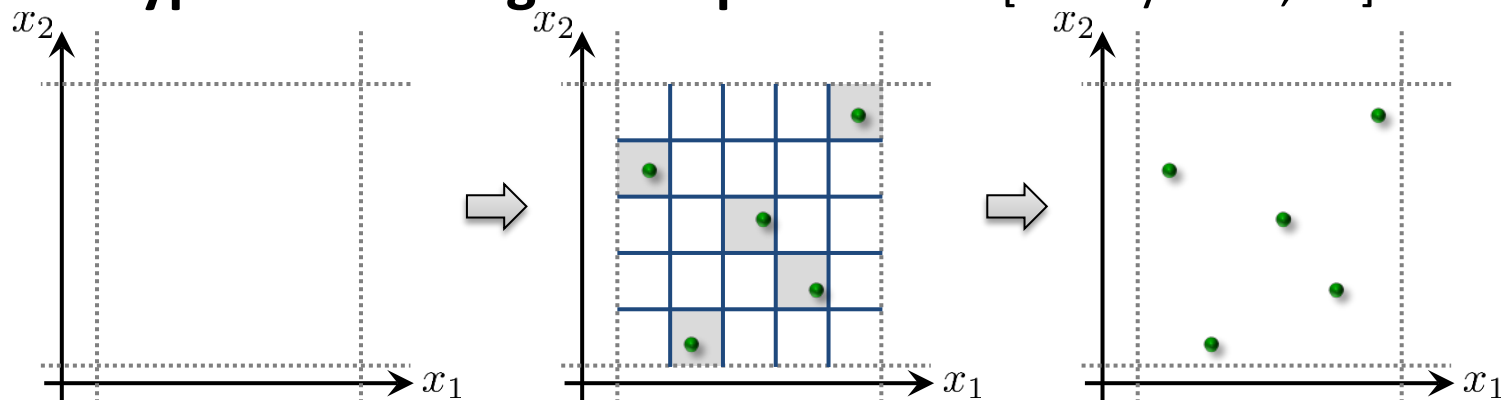
DESIGN OF EXPERIMENTS

- **Goal: To generate an initial set of input variables to evenly sample the problem space**

$$x = (x^1 \quad x^2 \quad \dots \quad x^i \quad \dots \quad x^N)$$

$$x^i = \begin{pmatrix} x_1^i \\ x_2^i \\ \vdots \\ x_d^i \\ \vdots \\ x_D^i \end{pmatrix}$$

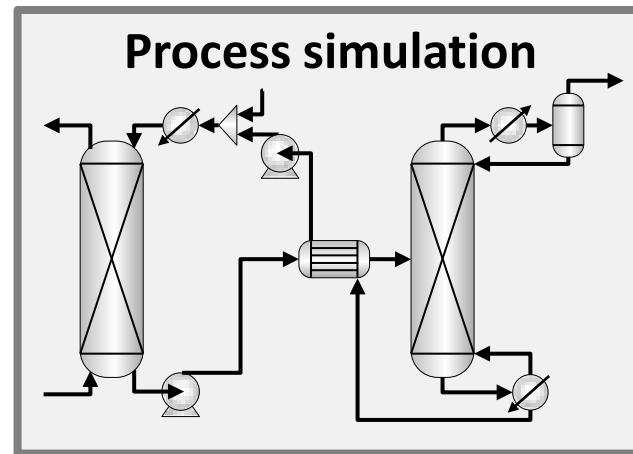
- **Latin hypercube design of experiments [McKay et al., 79]**



INITIAL SAMPLING

- After running the design of experiments, we will evaluate the black-box function to determine each z^i

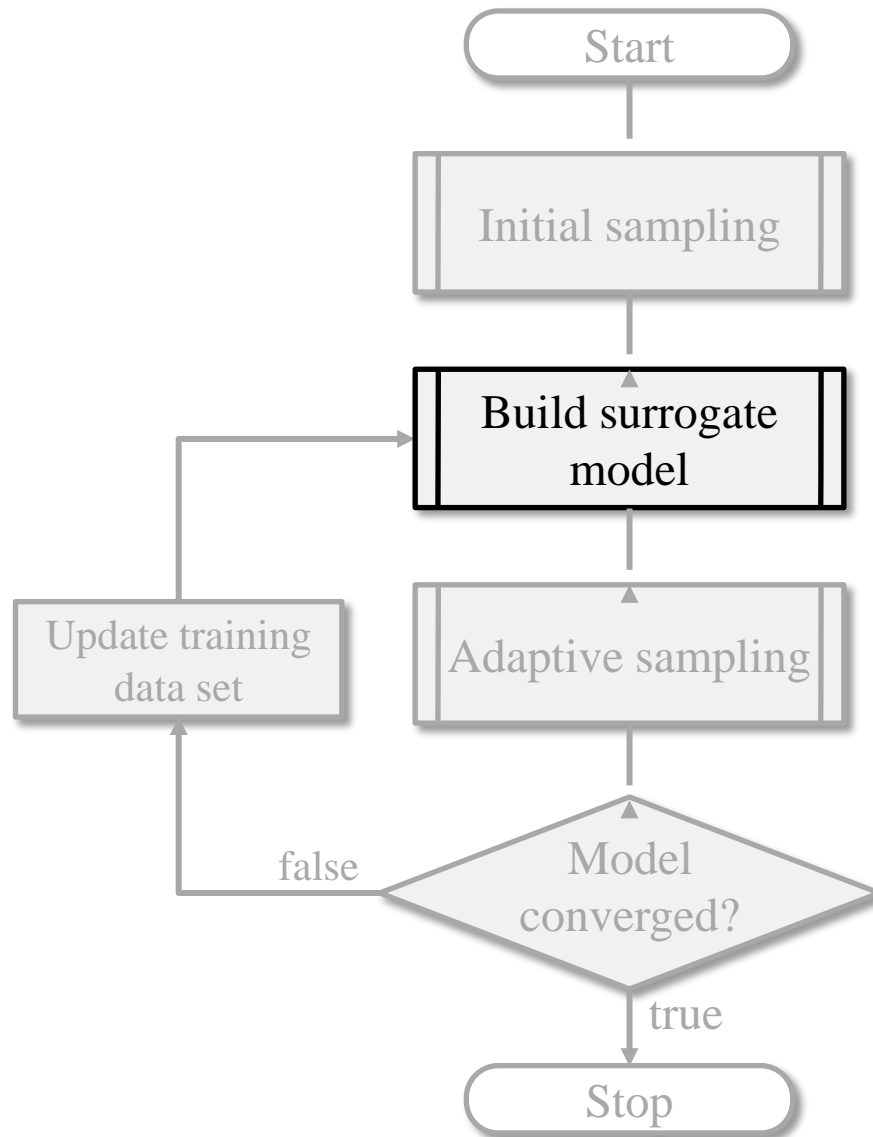
$$x = (x^1 \quad x^2 \quad \dots \quad x^i \quad \dots \quad x^N)$$



$$z = (z^1 \quad z^2 \quad \dots \quad z^i \quad \dots \quad z^N)$$

**Initial
training
set**

ALGORITHMIC FLOWSHEET



MODEL IDENTIFICATION

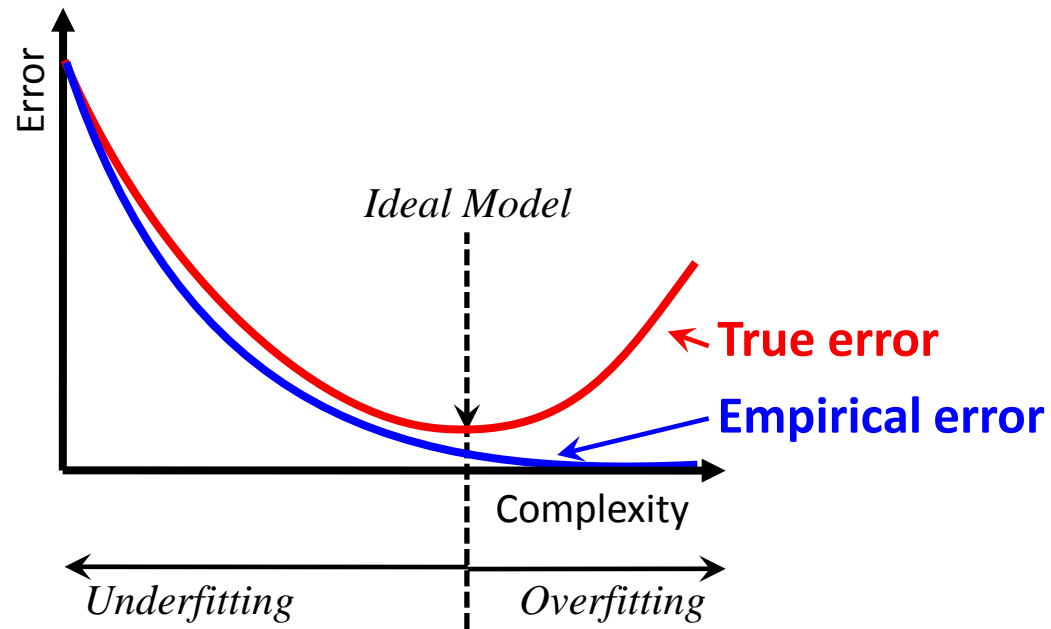
- **Goal: Identify the functional form and complexity of the surrogate models**

$$z = f(x)$$

- **Functional form:**
 - **General functional form is unknown: Our method will identify models with combinations of simple basis functions**

Category	$X_j(x)$
I. Polynomial	$(x_d)^\alpha$
II. Multinomial	$\prod_{d \in \mathcal{D}' \subseteq \mathcal{D}} (x_d)^{\alpha_d}$
III. Exponential and logarithmic forms	$\exp\left(\frac{x_d}{\gamma}\right)^\alpha, \log\left(\frac{x_d}{\gamma}\right)^\alpha$
IV. Expected bases	From experience, simple inspection, physical phenomena, etc.

OVERFITTING AND TRUE ERROR



Step 1: Define a large set of potential basis functions

$$\hat{z}(x_1) = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_1 x_2 + \beta_4 \frac{x_1}{x_2} + \beta_5 \frac{x_2}{x_1} + \beta_6 e^{x_1} + \beta_7 e^{x_2} + \dots$$

Step 2: Model reduction

$$\hat{z}(x) = \beta_0 + \beta_2 x_2 + \beta_5 \frac{x_2}{x_1} + \beta_7 e^{x_2}$$

BEST SUBSET METHOD

- **Generalized best subset problem:**

$$\begin{aligned} \min_{\mathcal{S}, \beta} \quad & \Phi(\mathcal{S}, \beta) \\ \text{s.t.} \quad & \mathcal{S} \subseteq \mathcal{B} \end{aligned}$$

where $\Phi(\mathcal{S}, \beta)$ is a goodness of fit measure for the subset of basis function, \mathcal{S} , and regression coefficients, β .

BEST SUBSET METHOD

- **Surrogate subset model:**

$$\hat{z}(x) = \sum_{j \in \mathcal{S}} \beta_j X_j(x)$$

- **Mixed-integer surrogate subset model:**

$$\hat{z}(x) = \sum_{j \in \mathcal{B}} (y_j \beta_j) X_j(x) \quad \text{such that} \quad \begin{array}{ll} y_j = 1 & j \in \mathcal{S} \\ y_j = 0 & j \notin \mathcal{S} \end{array}$$

- **Generalized best subset problem mixed-integer formulation:**

$$\begin{array}{ll} \min_{\beta, y} & \Phi(\beta, y) \\ \text{s.t.} & y_j = \{0, 1\} \end{array}$$

MIXED-INTEGER AICC

- **Corrected Akaike information criterion (AICc)** [Hurvich and Tsai, 93]

$$AICc(\mathcal{S}, \beta) = N \log \left(\frac{1}{N} \sum_{i=1}^N \left(z_i - \sum_{j \in \mathcal{S}} \beta_j X_{ij} \right)^2 \right) + 2|\mathcal{S}| + \frac{2|\mathcal{S}|(|\mathcal{S}| + 1)}{N - |\mathcal{S}| - 1}$$

- **Substituting the mixed integer surrogate form into AICc:**

$$AICc(\beta, y_j) = N \log \left(\frac{1}{N} \sum_{i=1}^N \left(z_i - \sum_{j \in \mathcal{B}} (y_j \beta_j) X_{ij} \right)^2 \right) + 2 \sum_j y_j + \frac{2 \sum_j y_j (\sum_j y_j + 1)}{N - \sum_j y_j - 1}$$

OR if $\sum_j y_j = T$

$$AICc(\beta, y_j) = N \log \left(\frac{1}{N} \sum_{i=1}^N \left(z_i - \sum_{j \in \mathcal{B}} (y_j \beta_j) X_{ij} \right)^2 \right) + 2T + \frac{2T(T + 1)}{N - T - 1}$$

MIXED-INTEGER PROBLEM

$$\begin{aligned} \min_{\beta, T, y} \quad & AICc(\beta, T, y) = N \log \left(\frac{1}{N} \sum_{i=1}^N \left(z_i - \sum_{j \in \mathcal{B}} (y_j \beta_j) X_{ij} \right)^2 \right) + 2T + \frac{2T(T+1)}{N-T-1} \\ \text{s.t.} \quad & \sum_{j \in \mathcal{B}} y_j = T \\ & y_j = \{0, 1\} \quad j \in \mathcal{B} \end{aligned}$$

MIXED-INTEGER PROBLEM

- **Further reformulation**

- **Replace bilinear terms with big-M constraints**

$$y_j \beta_j \quad \longrightarrow \quad \beta_j^l y_j \leq \beta_j \leq \beta_j^u y_j$$

- **Decouple objective into two problems**

a) model sizing

$$\text{General:} \quad \min_{\beta, T, y} \Phi(\beta, T, y) = \min_T \left\{ \underbrace{\min_{\beta, y} [\Phi_{\beta, y}(\beta, y)|_T]}_{\text{b) basis and coefficient selection}} + \Phi_T(T) \right\}$$

b) basis and coefficient selection

$$AICc(\beta, T) : \quad AICc_{\beta, y}(\beta, y)|_T = N \log \left(\frac{1}{N} \sum_{i=1}^N \left(z_i - \sum_{j \in \mathcal{B}} (y_j \beta_j) X_{ij} \right)^2 \right)$$

$$AICc_T(T) = 2T + \frac{2T(T+1)}{N-T-1}$$

- **Inner minimization objective reformulation**

NESTED MIXED-INTEGER PROBLEM

$$\begin{aligned} & \min_{T \in \{1, \dots, T^u\}} N \log \left(\frac{1}{N} \sum_{i=1}^N \left(z_i - \sum_{j \in \mathcal{B}} (y_j \beta_j) X_{ij} \right)^2 \right) + 2T + \frac{2T(T+1)}{N-T-1} \\ & \text{s.t.} \quad \min_{\beta, y} \sum_{i=1}^N \left(z_i - \sum_{j \in \mathcal{B}} \beta_j X_{ij} \right)^2 \\ & \quad \text{s.t.} \quad \sum_{j \in \mathcal{B}} y_j = T \\ & \quad \quad \beta^l y_j \leq \beta_j \leq \beta^u y_j \quad j \in \mathcal{B} \\ & \quad \quad y_j = \{0, 1\} \quad j \in \mathcal{B} \end{aligned}$$

a) Model sizing

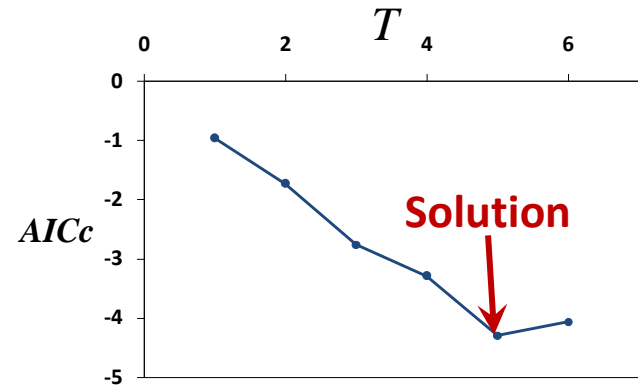
b) Basis and coefficient selection

PROBLEM SIMPLIFICATIONS

- **Simplifications:**

- **Outer problem**

- *The outer problem is parameterized by T and a local minima is found*



- **Inner problem**

- *Stationarity condition used to solve for continuous variables*

$$\frac{d}{d\beta_j} \sum_{i=1}^N \left(z_i - \sum_{j \in \mathcal{S}} \beta_j X_{ij} \right)^2 \propto \sum_{i=1}^N X_{ij} \left(z_i - \sum_{j \in \mathcal{S}} \beta_j X_{ij} \right) = 0, \quad j \in \mathcal{S}$$

- *Linear objective used to solved for integer variables*

$$\text{Objective: } \sum_{i=1}^N \left| z_i - \sum_{j \in \mathcal{S}} \beta_j X_{ij} \right|$$

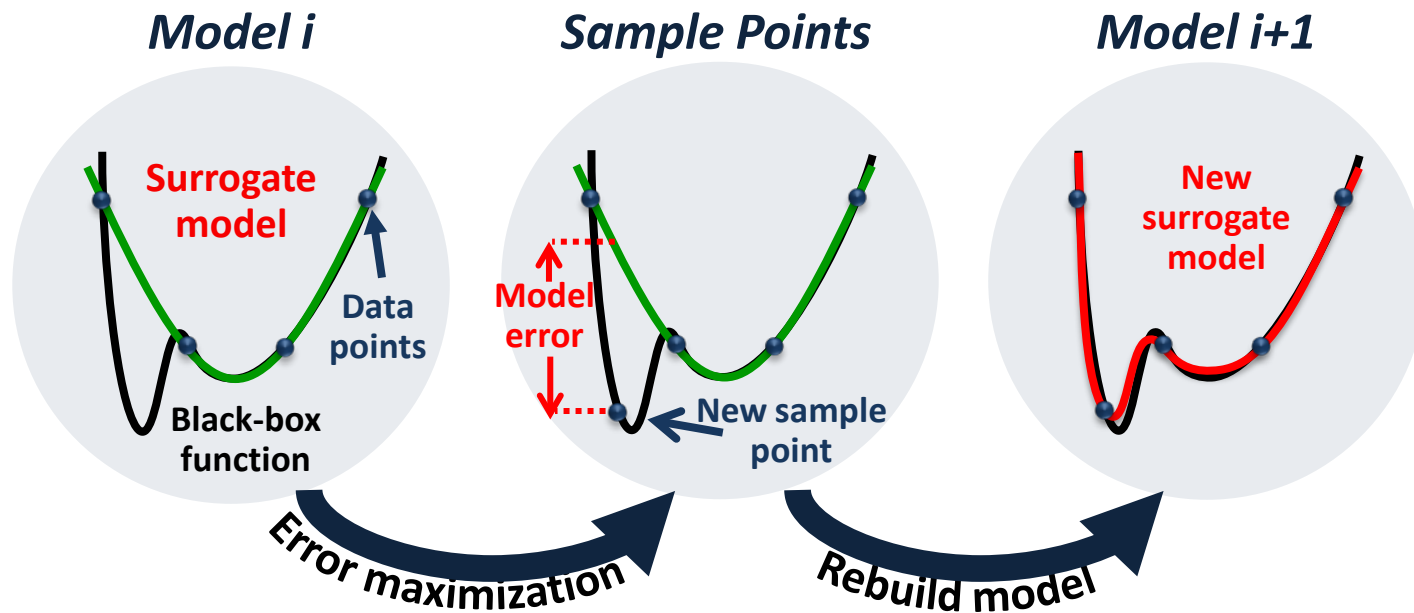
FINAL BEST SUBSET MODEL

$$\begin{aligned} \min \quad & SE = \sum_{i=1}^N \left| z_i - \sum_{j \in \mathcal{B}} \beta_j X_{ij} \right| \\ \text{s.t.} \quad & \sum_{j \in \mathcal{B}} y_j = T \\ & -U(1 - y_j) \leq \sum_{i=1}^N X_{ij} \left(z_i - \sum_{j \in \mathcal{B}} \beta_j X_{ij} \right) \leq U(1 - y_j) \quad j \in \mathcal{B} \\ & \beta^l y_j \leq \beta_j \leq \beta^u y_j \quad j \in \mathcal{B} \\ & y_j \in \{0, 1\} \quad j \in \mathcal{B} \\ & \beta_j \in [\beta_j^l, \beta_j^u] \quad j \in \mathcal{B} \end{aligned}$$

- **This model is solved for increasing values of T until the $AICc$ worsens**

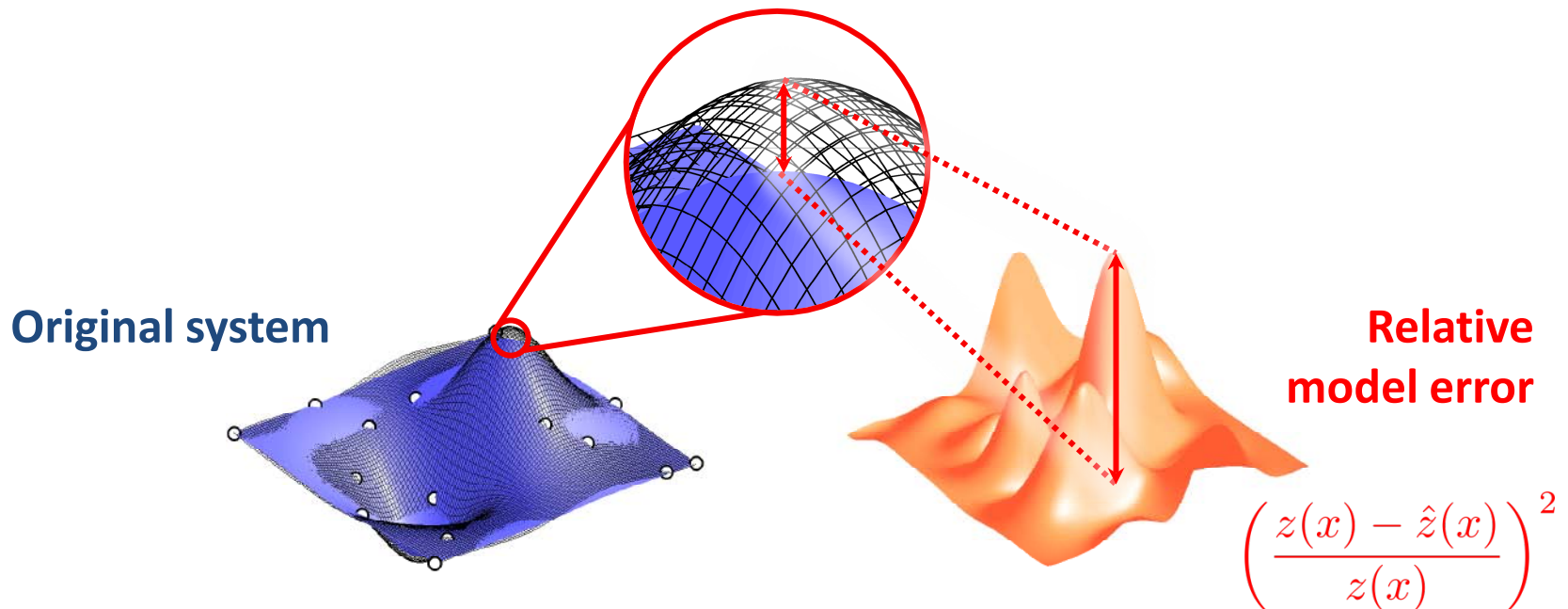
ADAPTIVE SAMPLING

- Goal: Choose new locations to sample that can best be used to **improve** the model
- Solution: Search the problem space for areas of model inconsistency or **model mismatch**



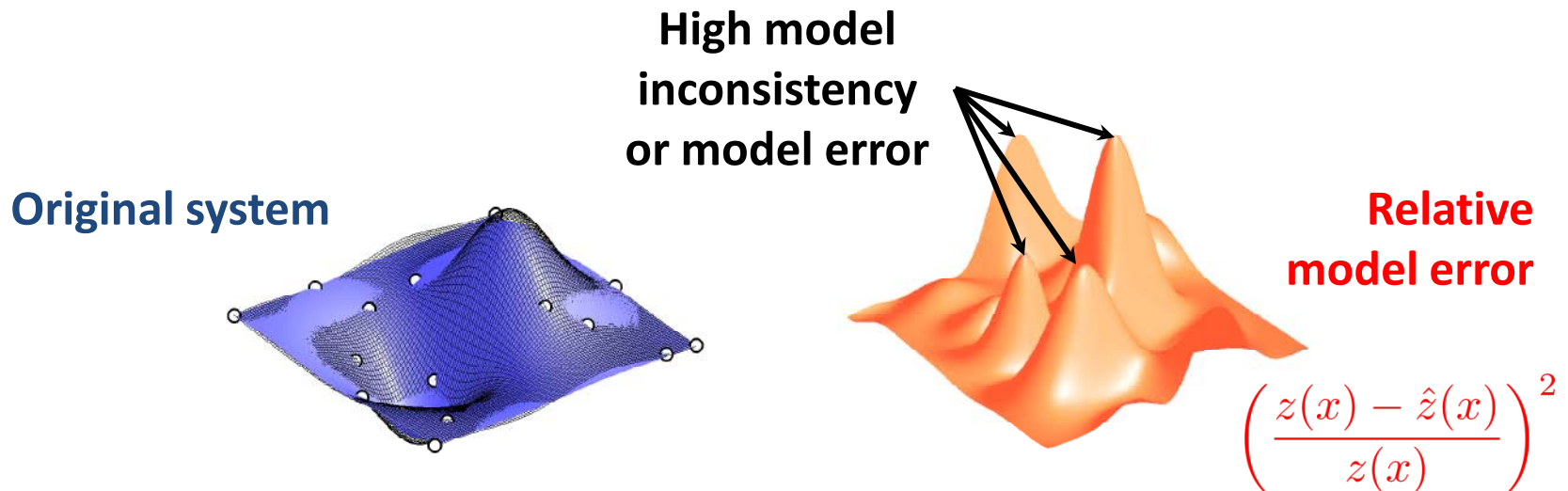
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ERROR MAXIMIZATION SAMPLING

- Goal: Search the problem space for areas of model inconsistency or **model mismatch**
- More succinctly, we are trying to find points that **maximizes the model error** with respect to the independent variables

$$\max_x \left(\frac{z(x) - \hat{z}(x)}{z(x)} \right)^2$$

Surrogate model


- Optimized using a black-box or derivative-free solver (SNOBFIT) [Huyer and Neumaier, 08]

ADAPTIVE SAMPLING

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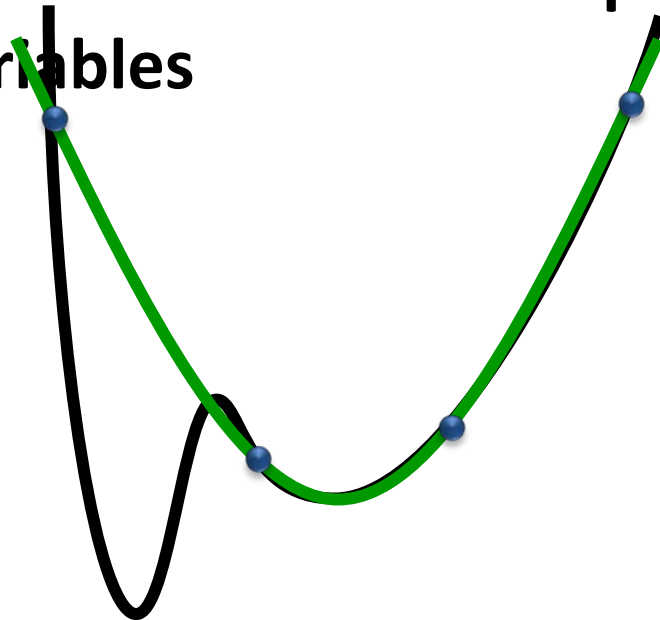
Surrogate model



- **Optimized using a black-box or derivative-free solver (SNOBFIT)**
[Huyer and Neumaier, 08]

ADAPTIVE SAMPLING

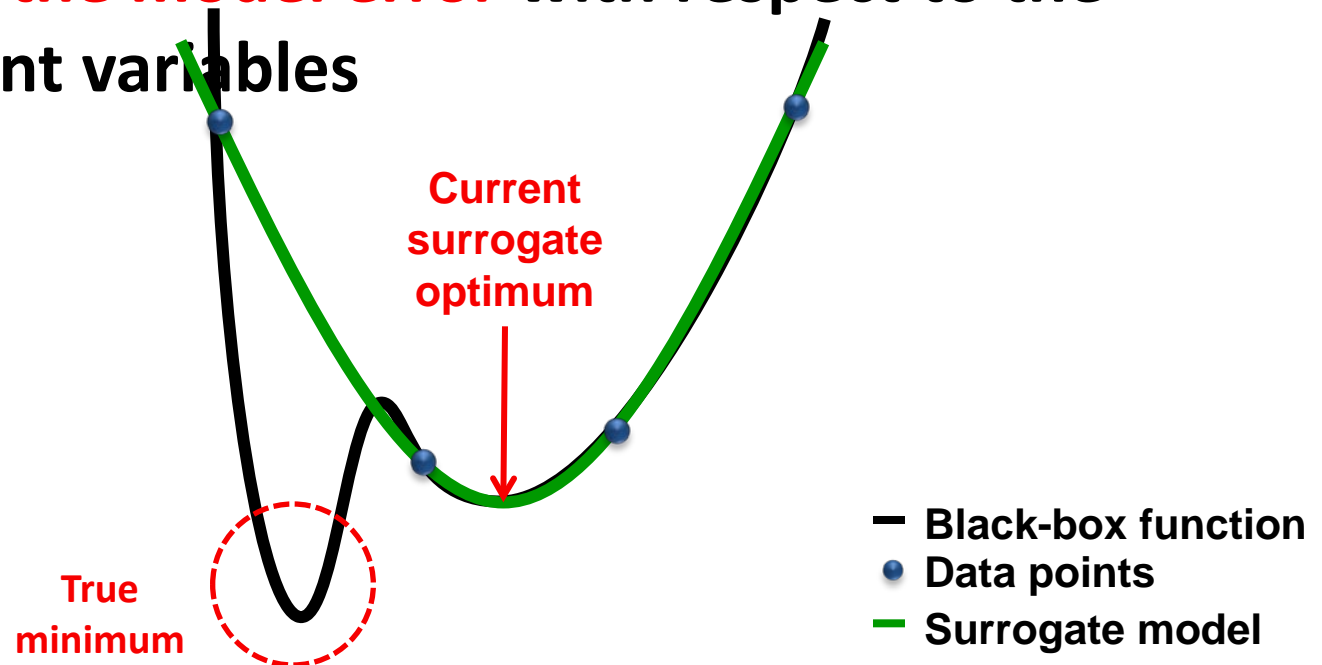
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- Black-box function
- Data points
- Surrogate model

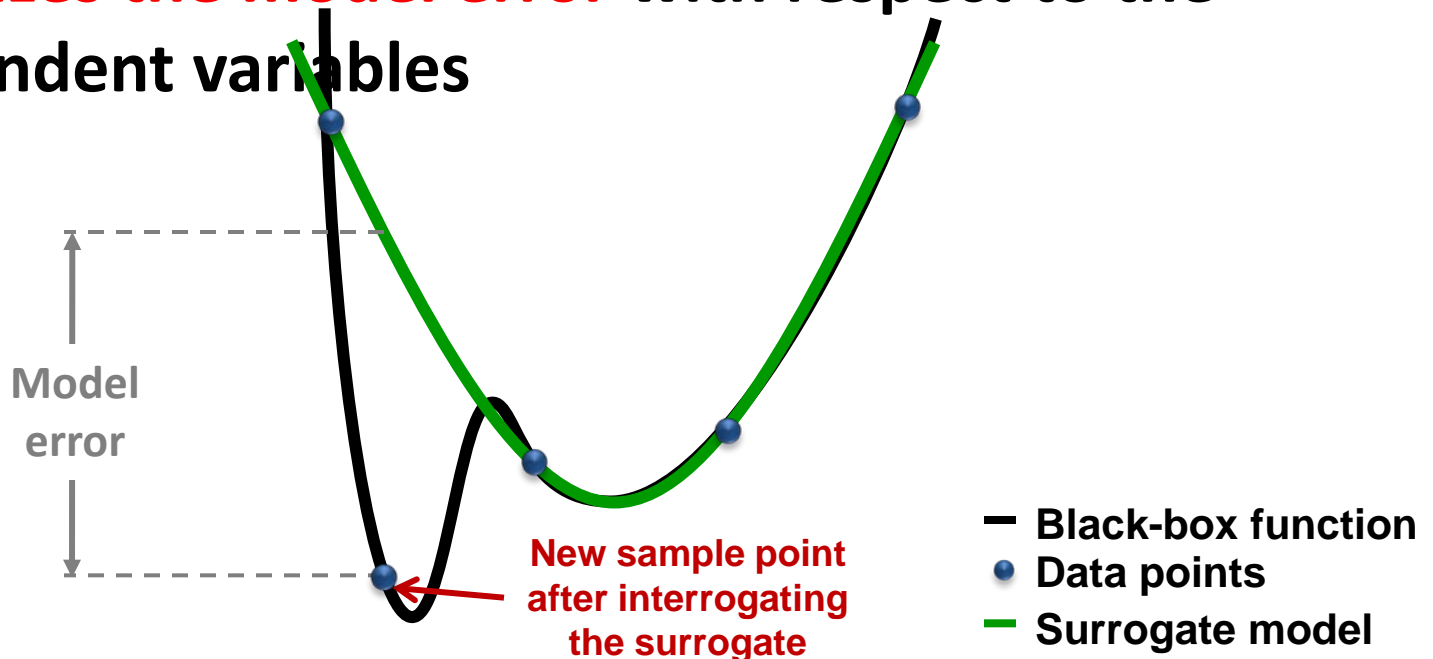
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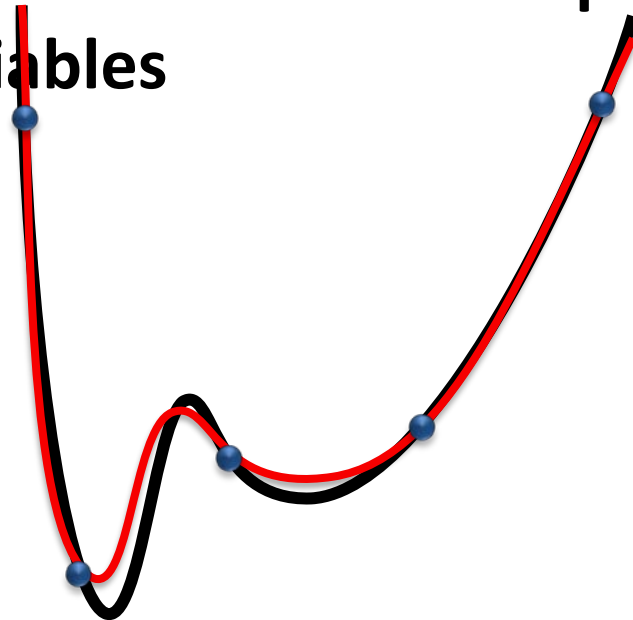
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- Black-box function
- Data points
- New surrogate model

ERROR MAXIMIZATION SAMPLING

- **Information gained using error maximization sampling:**
 1. **New data point locations that will be used to better train the next iteration's surrogate model**
 2. **Conservative estimate of the true model error**
 - *Defines a stopping criterion*
 - *Estimates the final model error*

COMPUTATIONAL TESTING

- Surrogate generation methods have been implemented into a package:

ALAMO

(Automated Learning of Algebraic Models for Optimization)

- Modeling methods compared
 - MIP – Proposed methodology
 - EBS – Exhaustive best subset method
 - *Note: due to high CPU times this was only tested on smaller problems*
 - LASSO – The lasso regularization
 - OLR – Ordinary least-squares regression
- Sampling methods compared
 - DFO – Proposed error maximization technique
 - SLH – Single latin hypercube (no feedback)

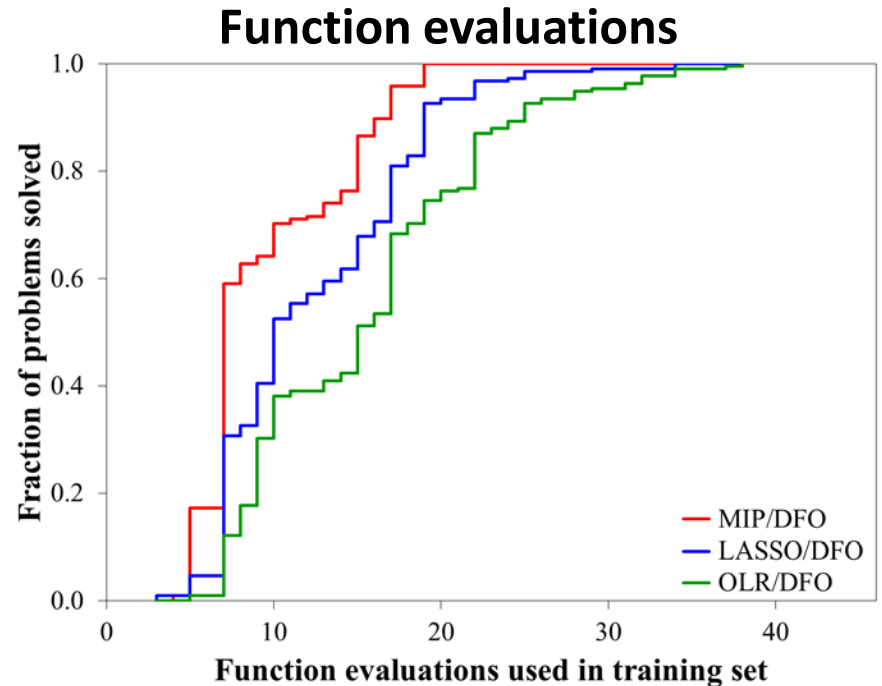
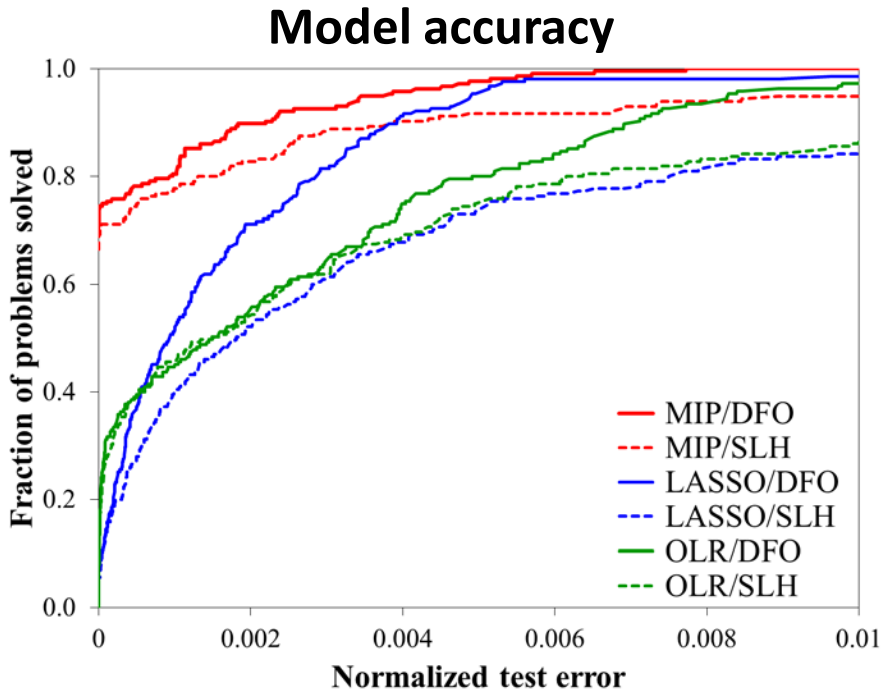
DESCRIPTION – TEST SET A

- Two and three input black-box functions randomly chosen basis functions available to the algorithms with varying complexity from 2 to 10 terms
- Basis functions allowed:

Category	$X_j(x)$	Parameters used
I. Polynomial	$(x_d)^\alpha$	$\alpha = \{\pm 3, \pm 2, \pm 1, \pm 0.5\}$
II. Multinomial	$\prod_{d \in \mathcal{D}' \subseteq \mathcal{D}} (x_d)^{\alpha_d}$	for $ \mathcal{D}' = 2$ $\alpha = \{\pm 2, \pm 1, \pm 0.5\}$ for $ \mathcal{D}' = 3$ $\alpha = \{\pm 1\}$
III. Exponential and logarithmic forms	$\exp\left(\frac{x_d}{\gamma}\right)^\alpha, \log\left(\frac{x_d}{\gamma}\right)^\alpha$	$\alpha = 1, \gamma = 1$

True basis function coefficients were randomly chosen from a uniform distribution where $\beta \in [-1, 1]$.

RESULTS – TEST SET A



45 test problems, repeated 5 times, tested against 1000 independent data points

MODEL COMPLEXITY – TEST SET A

No. in-puts	No. true terms	MIP/DFO	MIP/SLH	EBS/DFO	EBS/SLH	LASSO/DFO	LASSO/SLH	OLR/DFO	OLR/SLH
2	2	2	[2, 2]	2	2	[6, 8]	[6, 11]	[12, 15]	[12, 15]
2	3	3	3	3	3	[5, 12]	[5, 10]	[12, 14]	[12, 14]
2	4	[3, 4]	[3, 4]	[3, 4]	[3, 4]	[8, 11]	[8, 10]	[11, 12]	[11, 12]
2	5	[2, 4]	[2, 4]	[2, 5]	[2, 5]	[3, 12]	[4, 11]	[10, 16]	[10, 16]
2	6	[5, 6]	[6, 6]	[5, 6]	[6, 6]	[7, 10]	[6, 7]	[11, 13]	[11, 13]
2	7	[4, 6]	[4, 6]	[4, 7]	[4, 7]	[7, 11]	[6, 12]	[8, 13]	[8, 13]
2	8	[4, 5]	[5, 6]	[4, 5]	[5, 6]	[6, 8]	[6, 9]	[10, 15]	[10, 15]
2	9	[4, 6]	[4, 6]	NA	NA	[6, 14]	[7, 12]	[10, 17]	[10, 17]
2	10	[4, 8]	[4, 8]	NA	NA	[5, 14]	[7, 14]	[10, 14]	[10, 14]
3	2	[2, 3]	[2, 3]	NA	NA	[6, 12]	[7, 13]	[27, 29]	[27, 29]
3	3	[3, 3]	[3, 3]	NA	NA	[8, 16]	[7, 15]	[19, 22]	[19, 22]
3	4	4	[3, 4]	NA	NA	[10, 13]	[9, 10]	[16, 21]	[16, 21]
3	5	5	5	NA	NA	[11, 17]	[9, 15]	[15, 23]	[15, 23]
3	6	[5, 6]	[6, 6]	NA	NA	[9, 18]	[10, 13]	[15, 26]	[15, 26]
3	7	7	[7, 8]	NA	NA	[10, 22]	[10, 22]	22	22

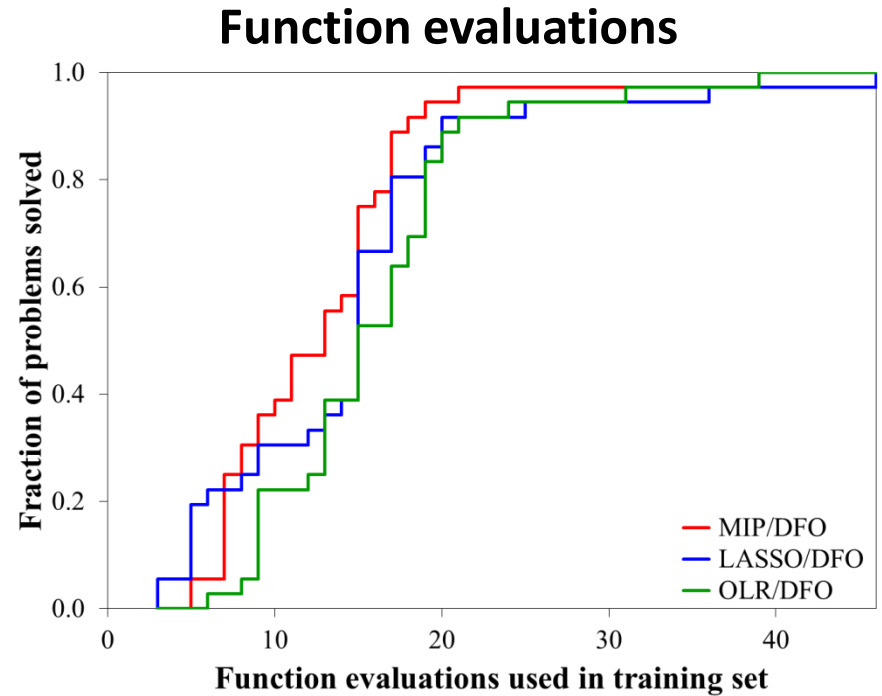
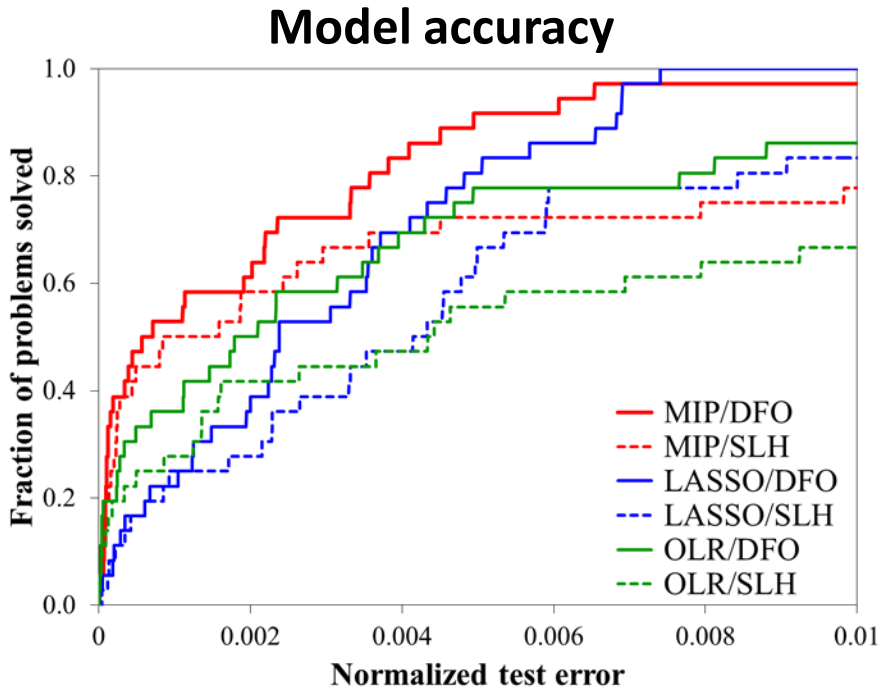
DESCRIPTION – TEST SET B

- Two input black-box functions with basis functions unavailable to the algorithms with

Function type	Functional form
I	$z(x) = \beta x_i^\alpha \exp(x_j)$
II	$z(x) = \beta x_i^\alpha \log(x_j)$
III	$z(x) = \beta x_1^\alpha x_2^\nu$
IV	$z(x) = \frac{\beta}{\gamma + x_i^\alpha}$

with true parameters chosen from a uniform distribution where $\beta \in [-1, 1]$, $\alpha, \nu \in [-3, 3]$, $\gamma \in [-5, 5]$, and $i, j \in \{1, 2\}$.

RESULTS – TEST SET B



12 test problems, repeated 5 times, tested against 1000 independent data points

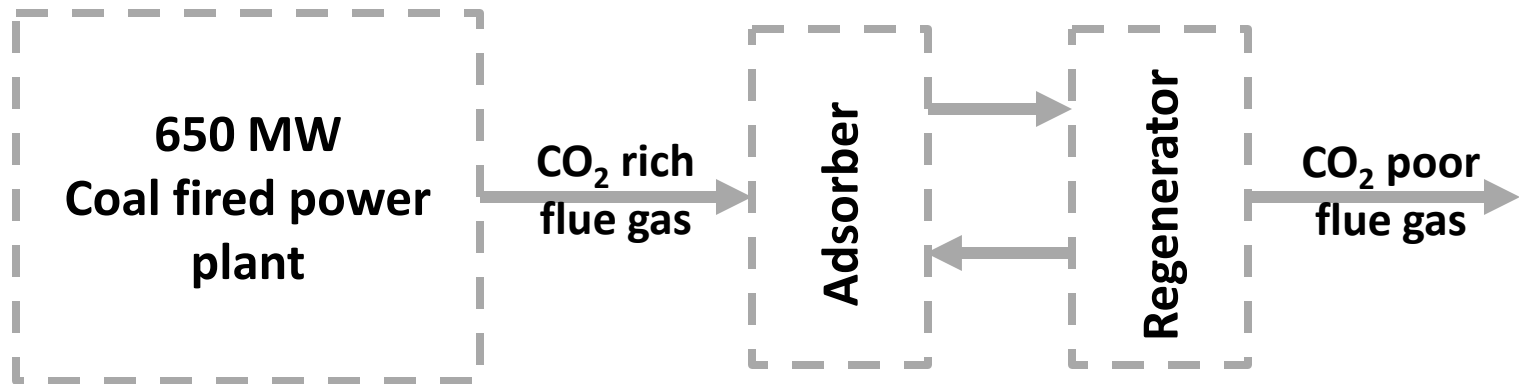
MODEL COMPLEXITY – TEST SET B

True func- tion type	Function ID	MIP/ DFO	MIP/ SLH	LASSO/ DFO	LASSO/ SLH	OLR/ DFO	OLR/ SLH
I	a	5	5	[3, 5]	[4, 9]	[6, 17]	[6, 17]
I	b	[4, 10]	[4, 10]	[10, 14]	[5, 8]	[8, 17]	[8, 17]
I	c	[3, 10]	[6, 9]	[8, 9]	[4, 10]	[13, 17]	[13, 17]
II	a	[4, 6]	[4, 10]	[8, 15]	[7, 9]	[15, 19]	[15, 19]
II	b	[1, 7]	[1, 9]	[13, 16]	[11, 17]	[13, 30]	[13, 30]
II	c	[5, 12]	[5, 12]	[9, 13]	[9, 16]	[9, 19]	[9, 19]
III	a	[3, 4]	[1, 4]	[2, 5]	[2, 5]	[9, 20]	[9, 20]
III	b	4	[1, 4]	5	5	[9, 20]	[9, 20]
III	c	[3, 4]	[3, 4]	[5, 8]	[5, 9]	[18, 24]	[18, 24]
IV	a	[7, 8]	[4, 10]	[8, 17]	[11, 18]	[13, 19]	[13, 19]
IV	b	[8, 9]	[9, 10]	[8, 12]	[10, 14]	[9, 17]	[9, 17]
IV	c	[6, 9]	[9, 10]	[5, 13]	[4, 12]	[13, 15]	[13, 15]

CARBON CAPTURE OPTIMIZATION

- Problem statement:

Capture **90% of CO₂** from a 350MW power plant's post combustion flue gas with **minimal increase in the cost of electricity**

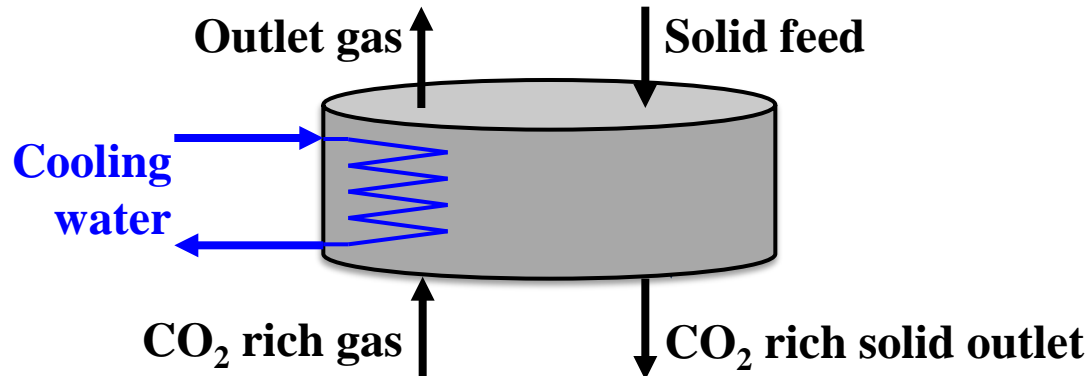


- Design considerations:

- Capture technology
 - *Bubbling fluidized bed, moving bed, fast fluidized bed, transport bed, etc.*
- Number of reactors
- Reactor configuration and geometry
- Operating conditions

BUBBLING FLUIDIZED BED

Bubbling fluidized bed adsorber diagram



- **Model inputs (14 total)**

- Geometry (3)
- Operating conditions (4)
- Gas mole fractions (2)
- Solid compositions (2)
- Flow rates (4)

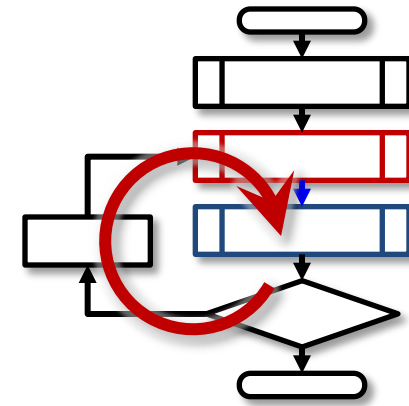
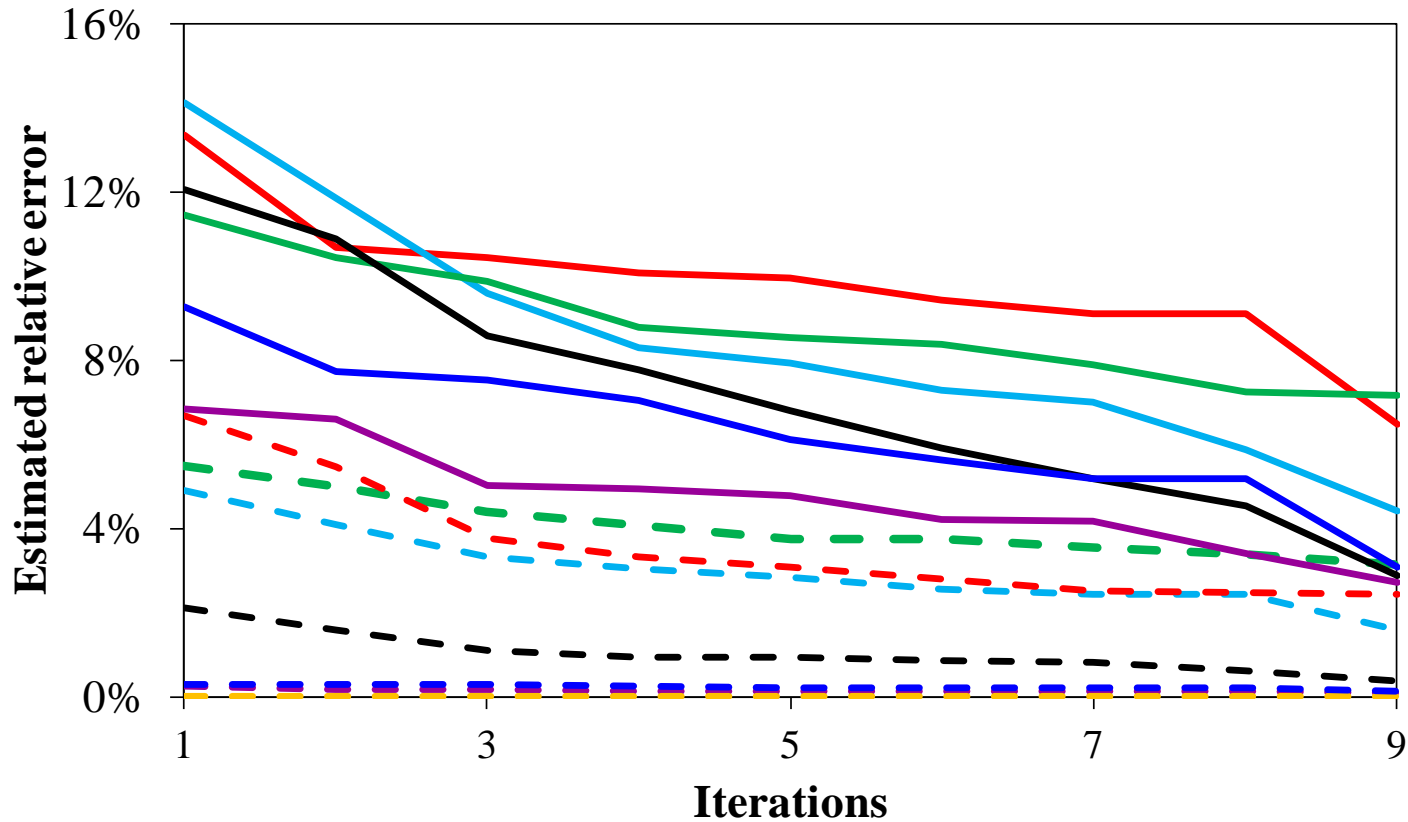
- **Model outputs (13 total)**

- Geometry required (2)
- Operating condition required (1)
- Gas mole fractions (2)
- Solid compositions (2)
- Flow rates (2)
- Outlet temperatures (3)
- Design constraint (1)

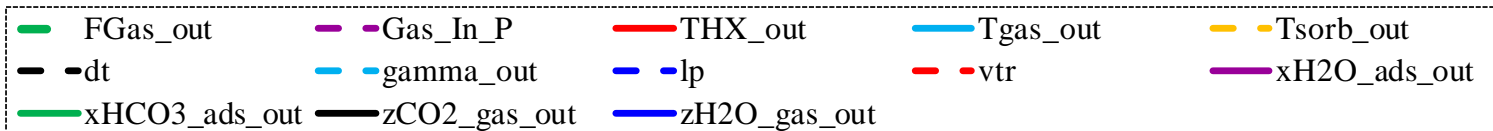
Model created by Andrew Lee at the National Energy and Technology Laboratory

ADAPTIVE SAMPLING

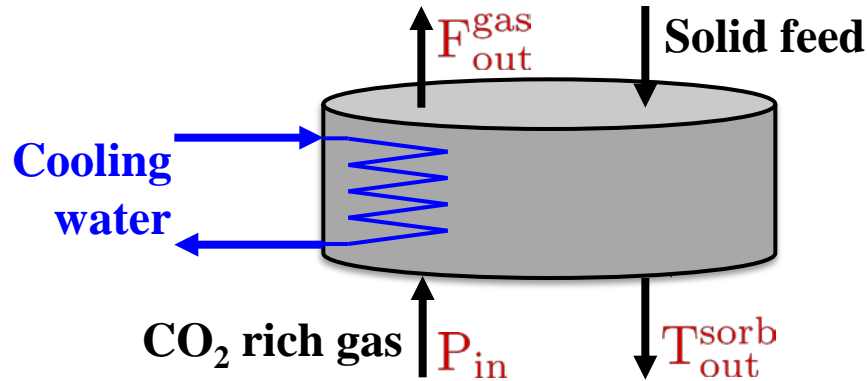
Progression of mean error through the algorithm



Initial data set:
137 pts
Final data set:
261



EXAMPLE MODELS



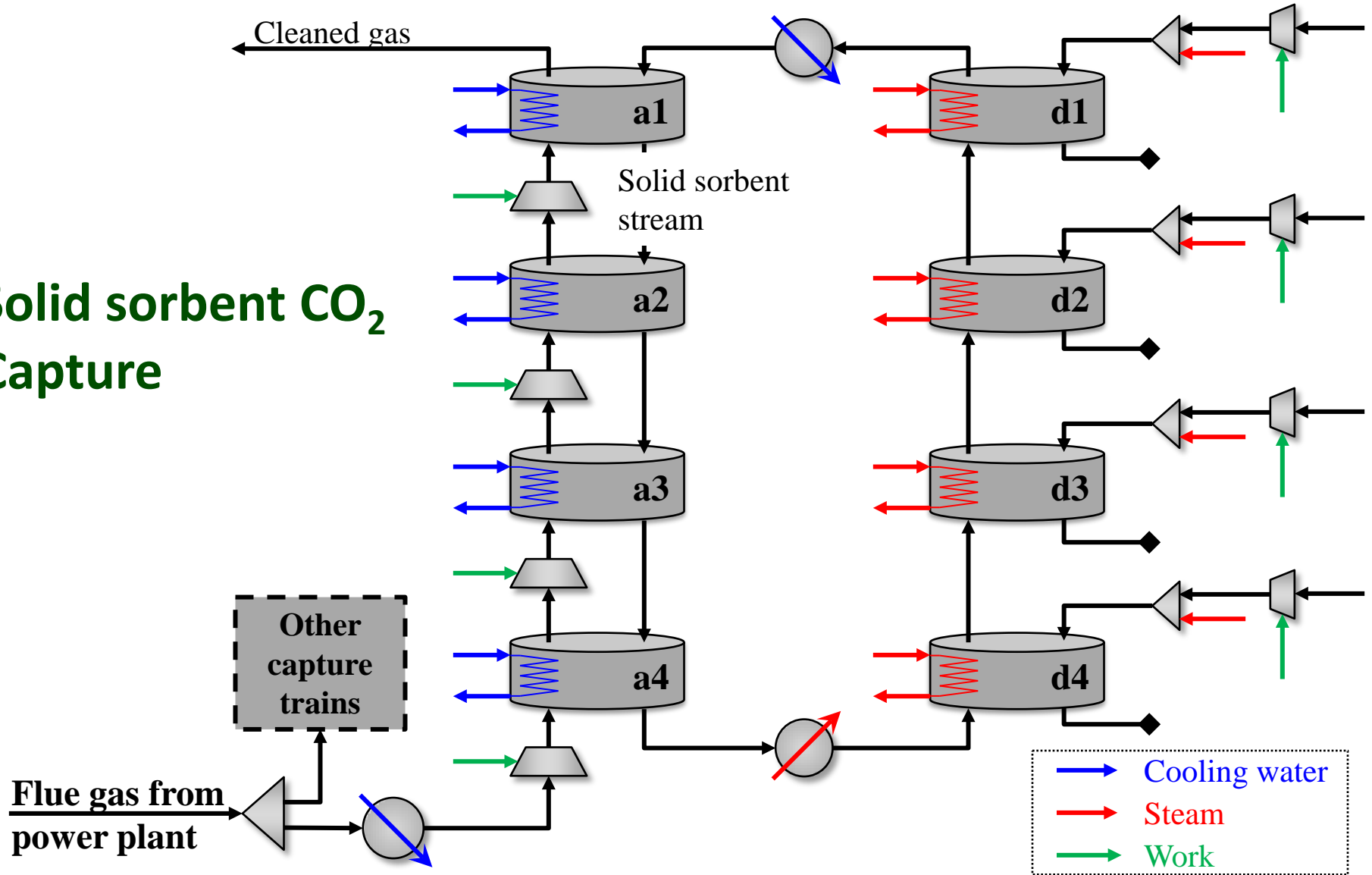
$$P_{in} = \frac{1.0 P_{out} + 0.0231 L_b - 0.0187 \ln(0.167 L_b) - 0.00626 \ln(0.667 v_{gi}) - 51.1 xHCO_3_{in}^{ads}}{F_{in}^{gas}}$$

$$T_{out}^{sorb} = 1.0 T_{in}^{gas} - \frac{(1.77 \cdot 10^{-10}) NX^2}{\gamma^2} - \frac{3.46}{NX T_{in}^{gas} T_{in}^{sorb}} + \frac{1.17 \cdot 10^4}{F^{sorb} NX xH_2O_{in}^{ads}}$$

$$F_{out}^{gas} = \frac{0.797 F_{in}^{gas} - \frac{9.75 T_{in}^{sorb}}{\gamma} - 0.77 F_{in}^{gas} xCO_2_{in}^{gas} + 0.00465 F_{in}^{gas} T_{in}^{sorb} - 0.0181 F_{in}^{gas} T_{in}^{sorb} xH_2O_{in}^{gas}}{1}$$

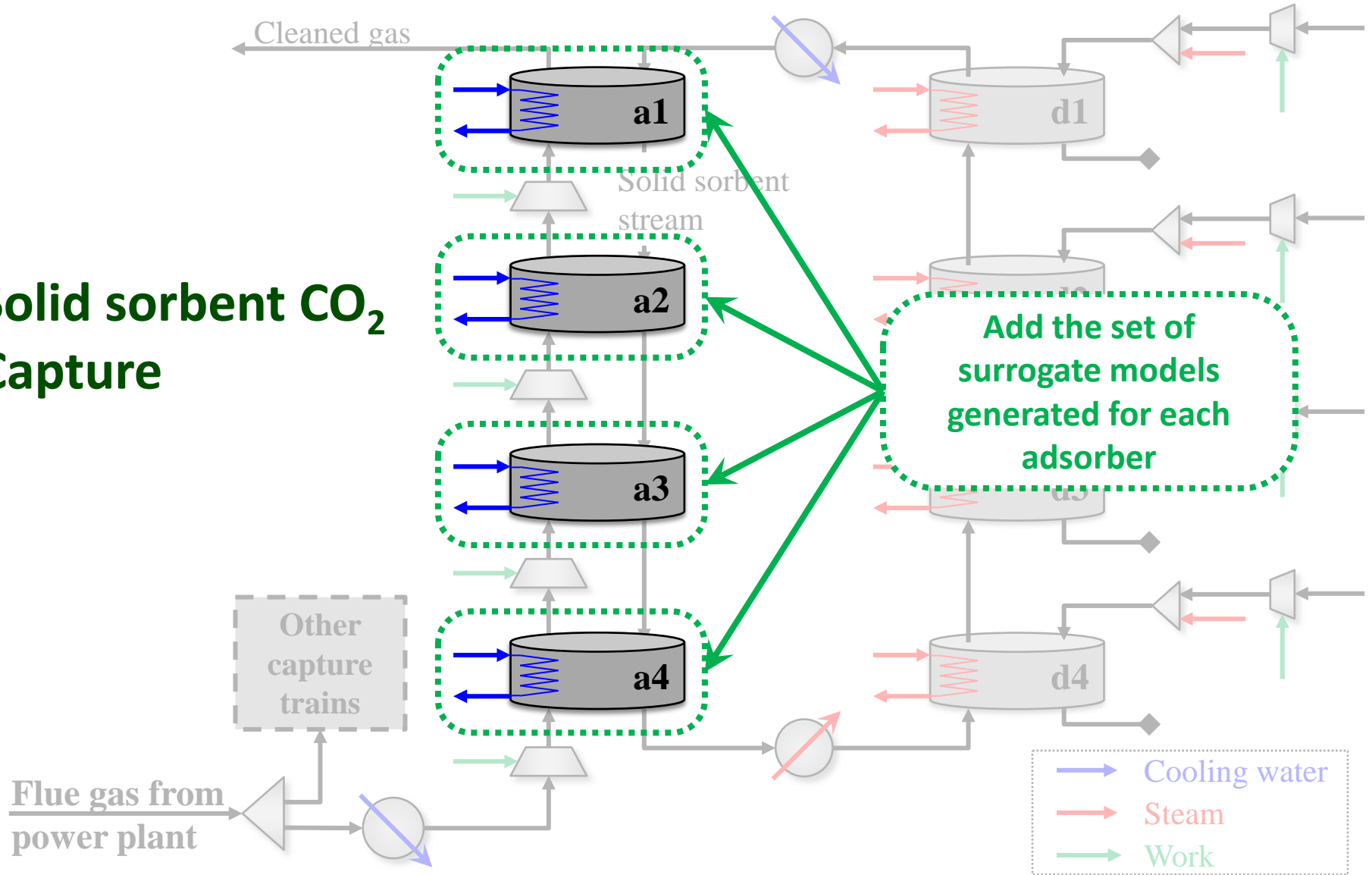
SUPERSTRUCTURE OPTIMIZATION

Solid sorbent CO₂ Capture

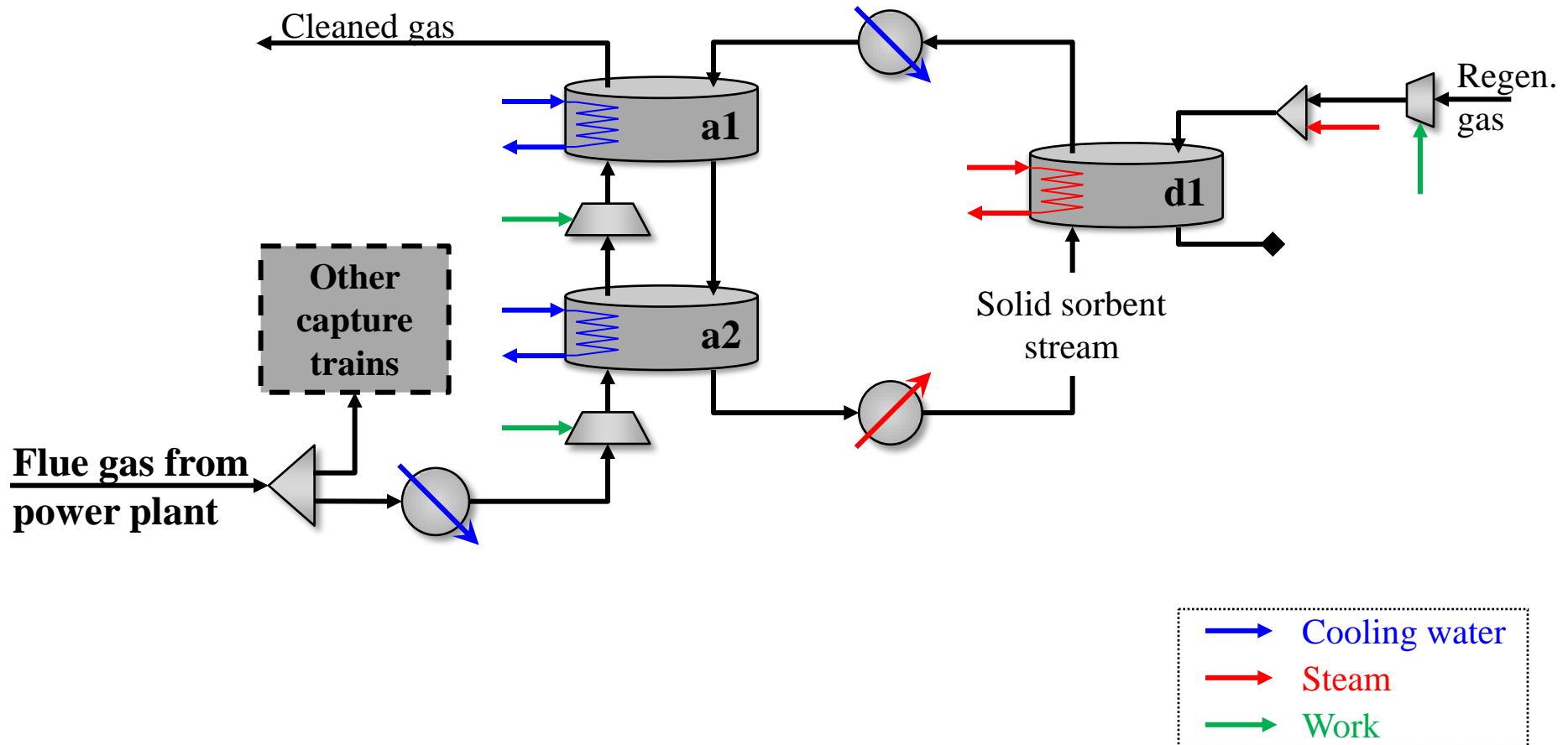


SUPERSTRUCTURE OPTIMIZATION

Solid sorbent CO₂ Capture



PRELIMINARY RESULTS



CONCLUSIONS

- The algorithm we developed is able to model black-box functions for use in optimization such that the models are
 - ✓ Accurate
 - ✓ Tractable in an optimization framework (low-complexity models)
 - ✓ Generated from a minimal number of function evaluations
- Surrogate models can then be incorporated within a optimization framework **flexible objective functions** and **additional constraints**

ALAMO

Automated Learning of Algebraic Models for Optimization

